

ERRATUM

End-to-end deep learning-based framework for path planning and collision checking: bin-picking application – ERRATUM

Mehran Ghafarian Tamizi¹, Homayoun Honari¹, Aleksey Nozdryn-Plotnicki² and Homayoun Najjaran¹

¹University of Victoria, Victoria, BC, V8W 2Y2, Canada

²Apera AI, Vancouver, BC, V6B 2K4, Canada

Corresponding author: Homayoun Najjaran; Email: najjaran@uvic.ca

DOI: <https://doi.org/10.1017/S0263574724000109>, Published online by Cambridge University Press, 13 February 2024.

This paper cites the following (Reference n. 4): “Boscariol, P., Gasparetto, A. and Scalera, L., “Path Planning for Special Robotic Operations,” In: Robot Design: From Theory to Service Applications (Carbone, G. and Laribi, M. A., eds.) (Springer, Cham, 2022) pp. 69–95”.

However, the details of this reference should correctly be given as:

Boscariol, P., Gasparetto, A., Scalera, L. (2023). Path Planning for Special Robotic Operations. In: Carbone, G., Laribi, M.A. (eds) *Robot Design. Mechanisms and Machine Science*, vol. 123, pp. 69–95. Springer, Cham. https://doi.org/10.1007/978-3-031-11128-0_4.

Reference

Ghafarian Tamizi, M., Honari, H., Nozdryn-Plotnicki, A. and Najjaran, H. (2024) End-to-end deep learning-based framework for path planning and collision checking: bin-picking application, *Robotica*, **42**(4): 1094–1112. doi: [10.1017/S0263574724000109](https://doi.org/10.1017/S0263574724000109)

Cite this article: M. G. Tamizi, H. Honari, A. Nozdryn-Plotnicki and H. Najjaran (2025). “End-to-end deep learning-based framework for path planning and collision checking: bin-picking application – ERRATUM”, *Robotica* **43**, 792. <https://doi.org/10.1017/S0263574724001942>

© The Author(s), 2024. Published by Cambridge University Press. This is an Open Access article, distributed under the terms of the Creative Commons Attribution licence (<https://creativecommons.org/licenses/by/4.0/>), which permits unrestricted re-use, distribution and reproduction, provided the original article is properly cited.

Downloaded from <https://www.cambridge.org/core>. IP address: 13.201.136.108, on 08 Aug 2025 at 14:10:28, subject to the Cambridge Core terms of use, available at <https://www.cambridge.org/core/terms>. <https://doi.org/10.1017/S0263574724001942>