

ON A HYPERLOGISTIC DELAY EQUATION

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1. Introduction. Consider the following hyperlogistic equation

$$\frac{d}{dt} N(t) = rN(t) \prod_{j=1}^m \left[1 - \frac{N(t - \tau_j)}{K} \right]^{\alpha_j}, \quad t \geq 0, \quad (1.1)$$

where $r, K, \tau_j \in (0, \infty)$, and $\alpha_j = p_j/q_j$ are rational numbers with q_j odd, p_j and q_j are co-prime, $1 \leq j \leq m$, and $\prod_{j=1}^m (-1)^{\alpha_j} = -1$.

When $m = 1$ and $\alpha_1 = 1$, Eq. (1.1) reduces to the well-known delay logistic equation

$$\frac{d}{dt} N(t) = rN(t) \left[1 - \frac{N(t - \tau)}{K} \right], \quad (1.2)$$

which has been extensively investigated by many authors. See for example [3, 5, 6, 7, 10, 13, 16]. Other related work includes [1, 2, 12] (in the case $m = 1$ and $\alpha_1 \neq 1$) and [4] (in the case $\alpha_1 = \dots = \alpha_m = 1$). Allowing $m \neq 1$, we wish to discuss the effect of different delayed terms on the oscillatory and asymptotic behaviors of solutions.

By making a change of variables

$$x(t) = \frac{N(t)}{K} - 1,$$

one can write (1.1) as

$$\frac{d}{dt} x(t) + r[1 + x(t)] \prod_{j=1}^m x^{\alpha_j}(t - \tau_j) = 0. \quad (1.3)$$

We are interested in those solutions $x(t)$ of (1.3) satisfying $x(t) \geq -1$ which correspond to solutions $N(t)$ of (1.1) satisfying $N(t) \geq 0$. Thus, the initial condition

$$\begin{cases} x(t) = \phi(t) \geq -1, & t \in [t_0 - \tau, t_0], \\ \phi \in C([t_0 - \tau, t_0], [-1, \infty)) \text{ and } \phi(t_0) > -1 \end{cases} \quad (1.4)$$

should be specified, where $\tau = \max\{\tau_1, \dots, \tau_m\}$. It can be easily shown that for any t_0 and any ϕ satisfying (1.4) Eq. (1.3)–(1.4) has a unique solution $x(t; t_0, \phi)$ on $[t_0 - \tau, \infty)$ and $x(t) > -1$ for $t \geq t_0$.

Of major concern in this paper is the oscillatory property of equation (1.3). We will show that all solutions of (1.3)–(1.4) are oscillatory when $\sum_{j=1}^m \alpha_j < 1$, but at least one non-oscillatory solution exists when $\sum_{j=1}^m \alpha_j > 1$. For the case where $\sum_{j=1}^m \alpha_j = 1$, we will

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establish an equivalence, as far as oscillation is concerned, between (1.3) and its so-called quasilinearized equation

$$\frac{d}{dt}y(t) + r \prod_{j=1}^m y^{\alpha_j}(t - \tau_j) = 0, \quad (1.5)$$

whose oscillation has been thoroughly studied in [8, 9, 14, 15]. Consequently, some existing results can be applied to give necessary and sufficient conditions for the oscillation of Eq. (1.3) when $\sum_{j=1}^m \alpha_j = 1$.

2. The case $\sum_{j=1}^m \alpha_j < 1$.

THEOREM 2.1. *If $\alpha = \sum_{j=1}^m \alpha_j < 1$, then every solution of Eq. (1.3)–(1.4) oscillates.*

Proof. Assume, by way of contradiction, that Eq. (1.3)–(1.4) has a non-oscillatory solution $x(t)$. We first suppose that $x(t)$ is eventually positive. Then, by (1.3), we eventually have

$$\frac{d}{dt}x(t) = -r(1 + x(t)) \prod_{j=1}^m x^{\alpha_j}(t - \tau_j) < 0,$$

which implies that $x(t)$ is eventually decreasing, thus

$$x(t - \tau_j) \geq x(t) \quad \text{eventually, for } j = 1, \dots, m.$$

and hence

$$\frac{d}{dt}x(t) + r(1 + x(t))x^\alpha(t) \leq \frac{d}{dt}x(t) + r(1 + x(t)) \prod_{j=1}^m x^{\alpha_j}(t - \tau_j) = 0.$$

Thus

$$\frac{d}{dt}x^{1-\alpha}(t) \leq -(1-\alpha)r[1 + x(t)] \leq -(1-\alpha)r,$$

which implies that $x^{1-\alpha}(t) \rightarrow -\infty$, as $t \rightarrow \infty$. This is impossible since $x(t) > 0$ eventually and $1 - \alpha > 0$.

We next suppose that $x(t)$ is eventually negative. Noting that $x(t) > -1$ for $t \geq 0$, we have eventually

$$\begin{aligned} \frac{d}{dt}x(t) &= -r(1 + x(t)) \prod_{j=1}^m x^{\alpha_j}(t - \tau_j) \\ &= r(1 + x(t)) \prod_{j=1}^m [-x(t - \tau_j)]^{\alpha_j} > 0, \end{aligned}$$

which implies that $x(t)$ is eventually increasing. Hence, there exists $T_1 > 0$ such that $x(t - \tau_j) \leq x(t) < 0$ and $1 + x(t) > 1 + x(T_1) > 0$, for all $t > T_1$ and $j = 1, \dots, m$. Therefore

$$\frac{d}{dt}x(t) + r(1 + x(t))x^\alpha(t) \geq \frac{d}{dt}x(t) + r(1 + x(t)) \prod_{j=1}^m x^{\alpha_j}(t - \tau_j) = 0, \quad t > T_1,$$

and hence

$$\begin{aligned} \frac{d}{dt}x^{1-\alpha}(t) &\leq -r(1 - \alpha)(1 + x(t)) \\ &< -r(1 - \alpha)(1 + x(T_1)) < 0, \quad t \geq T_1. \end{aligned}$$

Integrating the above inequality from T_1 to $t > 0$ and letting $t \rightarrow \infty$, we would get $x^{1-\alpha}(t) \rightarrow -\infty$, as $t \rightarrow \infty$. This is a contradiction to the fact that $x(t) > -1$ for $t \geq 0$, and completes the proof.

3. The case $\sum_{j=1}^m \alpha_j > 1$.

THEOREM 3.1. *If $\alpha = \sum_{j=1}^m \alpha_j > 1$, then Eq. (1.3) has a non-oscillatory solution.*

In order to complete the proof of Theorem 3.1, we will need the following Lemma from [15].

LEMMA 3.2. *Every solution of Eq. (1.5) with $\sum_{j=1}^m \alpha_j = 1$ oscillates if and only if*

$$r \sum_{j=1}^m \alpha_j \tau_j > \frac{1}{e}.$$

Moreover, the above inequality holds if and only if

$$\begin{cases} \frac{d}{dt}y(t) + r \prod_{j=1}^m y^{\alpha_j}(t - \tau_j) \leq 0 \text{ has no eventually positive solution,} \\ \frac{d}{dt}y(t) + r \prod_{j=1}^m y^{\alpha_j}(t - \tau_j) \geq 0 \text{ has no eventually negative solution.} \end{cases}$$

Proof of Theorem 3.1. Choose rational numbers $\beta_j = r_j/s_j \in [0, \infty)$ with s_j odd, $1 \leq j \leq m$, such that

$$\beta_j \leq \alpha_j, \quad \text{for } j = 1, \dots, m, \quad \sum_{j=1}^m \beta_j = 1, \quad \prod_{j=1}^m (-1)^{\beta_j} = -1.$$

Let $\varepsilon > 0$ satisfy

$$r\varepsilon \sum_{j=1}^m \beta_j \tau_j \leq \frac{1}{e}.$$

Then, by Lemma 3.2, the following equation

$$\frac{d}{dt}x(t) + r\varepsilon \prod_{j=1}^m x^{\beta_j}(t - \tau_j) = 0. \quad (3.1)$$

has a positive solution $x(t)$ defined on $[t_0, \infty)$ for some $t_0 \geq 0$. It is clear that $x(t) \rightarrow 0$, as $t \rightarrow \infty$. Since $\beta_j \leq \alpha_j$ and $\sum_{j=1}^m \beta_j < \sum_{j=1}^m \alpha_j$, we have

$$\lim_{t \rightarrow \infty} (1 + x(t)) \frac{\prod_{j=1}^m x^{\alpha_j}(t - \tau_j)}{\prod_{j=1}^m x^{\beta_j}(t - \tau_j)} = 0.$$

Thus, there exists $t_1 > t_0$ such that

$$(1 + x(t)) \prod_{j=1}^m x^{\alpha_j}(t - \tau_j) < \varepsilon \prod_{j=1}^m x^{\beta_j}(t - \tau_j), \quad \text{for } t \geq t_1,$$

and hence

$$\frac{d}{dt}x(t) + r(1 + x(t)) \prod_{j=1}^m x^{\alpha_j}(t - \tau_j) < \frac{d}{dt}x(t) + r\varepsilon \prod_{j=1}^m x^{\beta_j}(t - \tau_j) = 0, \quad \text{for } t \geq t_1. \quad (3.2)$$

Set $y(t) = \ln(1 + x(t))$. Then, from (3.2) we have

$$\frac{d}{dt}y(t) + r \prod_{j=1}^m [e^{y(t-\tau_j)} - 1]^{\alpha_j} < 0, \quad \text{for } t \geq t_1,$$

which yields

$$y(t) > r \int_t^\infty \prod_{j=1}^m [e^{y(s-\tau_j)} - 1]^{\alpha_j} ds, \quad \text{for } t \geq t_1. \quad (3.3)$$

Define \mathbf{X} to be the set of piecewise continuous functions $z : [t_1 - \tau, \infty) \rightarrow [0, 1]$ and endow \mathbf{X} with the usual pointwise ordering \leq , that is

$$z_1 \leq z_2 \Leftrightarrow z_1(t) \leq z_2(t), \quad \text{for all } t \geq t_1 - \tau.$$

Then $(\mathbf{X}; \leq)$ becomes an ordered set. It is obvious that for any nonempty subset M of \mathbf{X} , $\inf(M)$ and $\sup(M)$ exist. So $(\mathbf{X}; \leq)$ is actually a complete lattice. Define a mapping Ψ on \mathbf{X} as follows:

$$(\Psi z)(t) = \begin{cases} \frac{r}{y(t)} \int_t^\infty \prod_{j=1}^m [e^{y(s-\tau_j)z(s-\tau_j)} - 1]^{\alpha_j} ds, & t \geq t_1, \\ \frac{t}{t_1} (\Psi z)(t_1) + \left(1 - \frac{t}{t_1}\right), & t_1 - \tau \leq t \leq t_1. \end{cases}$$

For each $z \in \mathbf{X}$, we can show that

$$0 \leq (\Psi z)(t) \leq \frac{r}{y(t)} \int_t^\infty \prod_{j=1}^m [e^{y(s-\tau_j)} - 1]^{\alpha_j} ds < 1, \quad \text{for } t \geq t_1,$$

and

$$0 \leq (\Psi z)(t) \leq 1, \text{ for } t \in [t_1 - \tau, t_1].$$

This shows that $\Psi X \subseteq X$. Moreover, it can be easily verified that Ψ is a monotone increasing mapping. Therefore, by the Knaster-Tarski fixed-point theorem (see [11]), we know that there exists a $z \in X$ such that $\Psi z = z$, that is

$$z(t) = \begin{cases} \frac{r}{y(t)} \int_t^\infty \prod_{j=1}^m [e^{y^{(s-\tau_j)} z^{(s-\tau_j)}} - 1]^{\alpha_j} ds, & \text{for } t \geq t_1, \\ \frac{t}{t_1} (\Psi z)(t_1) + \left(1 - \frac{t}{t_1}\right), & t_1 - \tau \leq t \leq t_1. \end{cases} \tag{3.4}$$

By (3.4), $z(t)$ is continuous on $[t_1 - \tau, \infty)$. Moreover, since $z(t) > 0$ for $t \in [t_1 - \tau, t_1)$, we must have $z(t) > 0$, for all $t \geq t_1$. Set $w(t) = y(t)z(t)$. Then $w(t)$ is positive, continuous on $[t_1 - \tau, \infty)$ and satisfies

$$w(t) = r \int_t^\infty \prod_{j=1}^m [e^{w^{(s-\tau_j)}} - 1]^{\alpha_j} ds, \text{ for } t \geq t_1. \tag{3.5}$$

Differentiating (3.5) yields

$$\frac{d}{dt} w(t) + r \prod_{j=1}^m [e^{w^{(t-\tau_j)}} - 1]^{\alpha_j} = 0, \text{ for } t \geq t_1,$$

which shows that $e^{w(t)} - 1$ is a positive solution of (1.3) on $[t_1, \infty)$. This completes the proof.

4. The case $\sum_{j=1}^m \alpha_j = 1$.

The following theorem establishes an equivalence between the oscillation of Eq. (1.3)–(1.4) and the oscillation of Eq. (1.5):

THEOREM 4.1. *When $\sum_{j=1}^m \alpha_j = 1$, every solution of Eq. (1.3)–(1.4) oscillates if and only if every solution of Eq. (1.5) oscillates.*

Proof. \Rightarrow : Assume that Eq. (1.5) has a non-oscillatory solution $y(t)$. Since $-y(t)$ is also a solution of Eq. (1.5), we may assume that $y(t)$ is eventually positive. We will prove that Eq. (1.3)–(1.4) has a non-oscillatory solution for some t_0 . To this end, we only need to prove that the following equation

$$\frac{d}{dt} z(t) + r \prod_{j=1}^m (1 - e^{-z^{(t-\tau_j)}})^{\alpha_j} = 0 \tag{4.2}$$

has an eventually positive solution. Let t_0 be such that $y(t - \tau) > 0$ for $t \geq t_0$. Using the inequality $1 - e^{-x} \leq x$ for $x \geq 0$, we have

$$\frac{d}{dt} y(t) + r \prod_{j=1}^m (1 - e^{-y^{(t-\tau_j)}})^{\alpha_j} \leq \frac{d}{dt} y(t) + r \prod_{j=1}^m y^{\alpha_j}(t - \tau_j) = 0, \text{ for } t \geq t_0. \tag{4.3}$$

It can be easily shown that $y(t) \rightarrow 0$, as $t \rightarrow \infty$. Integrating the above inequality from t to ∞ , we obtain

$$y(t) \geq r \int_t^\infty \prod_{j=1}^m (1 - e^{-y^{(s-\tau_j)}})^{\alpha_j}, \text{ for } t \geq t_0.$$

Now a similar argument to the proof of Theorem 3.1 shows that (4.2) would have an eventually positive solution $z(t)$ on $[t_0, \infty)$ satisfying $z(t) > 0$ for all $t \geq t_0$.

⇐: Assume, for the sake of contradiction, that (1.3)–(1.4) has a non-oscillatory solution $x(t)$ for every t_0 . Then $1 + x(t) > 0$, for $t \geq t_0$. We now distinguish two cases:

Case (i): $x(t)$ is eventually positive. Then there exists $T \geq t_0$ such that $x(t) > 0$, for $t \geq T$. From (1.3) it follows that

$$\frac{d}{dt}x(t) + r \prod_{j=1}^m x^{\alpha_j}(t - \tau_j) \leq \frac{d}{dt}x(t) + r(1 + x(t)) \prod_{j=1}^m x^{\alpha_j}(t - \tau_j) = 0. \quad (4.4)$$

This, together with Lemma 3.2, implies that (1.5) has a non-oscillatory solution, contrary to the assumption that every solution of (1.5) oscillates.

Case (ii): $x(t)$ is eventually negative. Since $1 + x(t) > 0$, for $t \geq t_0$, and $x(t) < 0$ for $t \geq T$, for some $T \geq t_0$, we have

$$\frac{d}{dt}x(t) = r(1 + x(t)) \prod_{j=1}^m [-x(t - \tau_j)]^{\alpha_j} > 0, \quad \text{for } t \geq T,$$

from which we can easily see that $x(t) \nearrow 0$ as $t \rightarrow \infty$. On the other hand, in view of Lemma 3.2, we can choose $\varepsilon \in (0, 1)$ such that

$$r(1 - \varepsilon) \sum_{j=1}^m \alpha_j \tau_j > \frac{1}{e}. \quad (4.5)$$

Now, let $T_1 > T$ be sufficiently large such that $1 > 1 + x(t) > 1 - \varepsilon$, for $t \geq T$. Then, by (1.3) we have

$$\frac{d}{dt}x(t) + r(1 - \varepsilon) \prod_{j=1}^m x^{\alpha_j}(t - \tau_j) \geq \frac{d}{dt}x(t) + r(1 + x(t)) \prod_{j=1}^m x^{\alpha_j}(t - \tau_j) = 0, \quad \text{for } t \geq T + \tau, \quad (4.6)$$

which is also a contradiction since, by Lemma 3.2, (4.5) implies that the inequality

$$\frac{d}{dt}x(t) + r(1 - \varepsilon) \prod_{j=1}^m x^{\alpha_j}(t - \tau_j) \geq 0$$

can not have an eventually negative solution. This completes the proof.

The following corollary is an immediate result of Theorem 4.1 and Lemma 3.2.

COROLLARY 4.2. *If $\sum_{j=1}^m \alpha_j = 1$, then every solution of (1.3)–(1.4) oscillates (or every positive solution of (1.1) oscillates about the steady state K) if and only if*

$$r \sum_{j=1}^m \alpha_j \tau_j > \frac{1}{e}.$$

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