

CORRECTION TO A RESULT OF JAIN ON A CORRELATED RANDOM WALK

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ABSTRACT. The authors have found that the formula for $U(t)$ —the probability generating function (p.g.f) of a return to the starting position, obtained by Jain [1, p. 344] is incorrect and have obtained its correct formulae.

Consider the walk $\{S_n, n = 0, 2, \dots\}$ where $S_0 = 0, S_n = X_1 + \dots + X_n$. Let X_i be the random variable associated with the i th step, assuming the value $+1, -1$ or zero according as the i th step is to the right, to the left or a stay, with probabilities as per the t.p.m., for $n \geq 1$,

$$(1) \quad \begin{array}{l} \text{From/To} \\ \text{right} \\ \text{left} \\ \text{stay} \end{array} \begin{array}{ccc} \text{right} & \text{left} & \text{stay} \\ \left[\begin{array}{ccc} p_1\alpha & q_1\alpha & 1-\alpha \\ q_2\alpha & p_2\alpha & 1-\alpha \\ \beta & \gamma & 1-\beta-\gamma \end{array} \right] & & \end{array} \quad p_1 + q_1 = p_2 + q_2 = 1,$$

for $n = 0, P(X_0 = 1) = \rho_1 (= 1 - \rho_2)$ is an arbitrary probability.

For $r = 0$ or an integer, let

$$(2) \quad u_r(n) = \begin{bmatrix} u_r^{+1,+1}(n) & u_r^{+1,-1}(n) & u_r^{+1,0}(n) \\ u_r^{-1,+1}(n) & u_r^{-1,-1}(n) & u_r^{-1,0}(n) \\ u_r^{0,+1}(n) & u_r^{0,-1}(n) & u_r^{0,0}(n) \end{bmatrix}$$

where $u_r^{i,j}(n) = P\{S_n = r, X_n = j \mid X_0 = i\}$. Also, let

$$u_r^i(n) = \sum_j u_r^{i,j}(n) \quad \text{and} \quad U_r^i(t) = \sum_{n=0}^{\infty} u_r^i(n)t^n, \quad \text{etc.}$$

On using the ‘one-step’ t.p.ms. (as defined in [2]) for walk (1), we can easily write

$$(3) \quad P(s) = \begin{bmatrix} p_1\alpha s & q_1\alpha s^{-1} & 1-\alpha \\ q_2\alpha s & p_2\alpha s^{-1} & 1-\alpha \\ \beta s & \gamma s^{-1} & 1-\beta-\gamma \end{bmatrix}$$

and $U_r(t)$ is the coefficient of s^r in $\sum_{n=0}^{\infty} [tP(s)]^n = [I - tP(s)]^{-1}$.

With $\alpha = \beta + \gamma = 1$ and $\beta = \rho_1$, the walk (1) reduces to the one considered by

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Jain [1] for which we, then, get

$$(4) \quad U_0(t) = \frac{(wp_1/p_2)^{1/2}}{p_1 t(1-w)} \begin{bmatrix} 1 - t(wp_1 p_2)^{1/2} & q_1 t(wp_1/p_2)^{1/2} & 0 \\ q_2 t(wp_2/p_1)^{1/2} & 1 - t(wp_1 p_2)^{1/2} & 0 \\ \rho_1 t(wp_2/p_1)^{1/2} & \rho_2 t(wp_1/p_2)^{1/2} & 1 + \delta t^2 \\ +(q_2 - \rho_1)t^2 & +(\rho_1 - p_1)t^2 & -2t(wp_1 p_2)^{1/2} \end{bmatrix}$$

where

$$\delta = p_1 - q_2, \quad w = \frac{1 + \delta t^2 - \{(1 + \delta t^2)^2 - 4p_1 p_2 t^2\}^{1/2}}{1 + \delta t^2 + \{(1 + \delta t^2)^2 - 4p_1 p_2 t^2\}^{1/2}}.$$

In terms of Jain's notations ($w = A_1(t)B_{-1}(t)$), on summing each row in (4), we get the following p.g.fs. of conditional return to origin

$$(5) \quad U_0^{+1}(t) = C[1 - \delta t A_1(t)], \quad U_0^{-1}(t) = C[1 - \delta t B_{-1}(t)] \\ U_0^0(t) = C[1 - t B_1(t)\{\rho_1(p_1 - p_2) + p_1(2p_2 - 1)\}/p_2]$$

where $C = A_1(t)/[1 - A_1(t)B_{-1}(t)] p_1 t$. The p.g.f. of unconditional return to zero, then, is

$$(6) \quad U_0(t) = \sum_{i=-1}^1 U_0^i(t)P(X_0 = i) = \rho_1 U_0^{+1}(t) + (1 - \rho_1)U_0^{-1}(t)$$

For $p_1 = p_2 = p$, (6) verifies (13) in Seth [3].

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