

## SIMPLE $(-1, -1)$ BALANCED FREUDENTHAL KANTOR TRIPLE SYSTEMS

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**Abstract.** The simple finite dimensional  $(-1, -1)$  balanced Freudenthal Kantor triple systems over fields of characteristic zero are classified.

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**1. Introduction.** In 1954, H. Freudenthal [10] constructed the exceptional simple Lie algebras of types  $E_7$  and  $E_8$  by means of the exceptional simple Jordan algebras. The construction of  $E_8$  has been extended in several ways to give 5-graded Lie algebras

$$\mathfrak{g} = \mathfrak{g}_{-2} \oplus \mathfrak{g}_{-1} \oplus \mathfrak{g}_0 \oplus \mathfrak{g}_1 \oplus \mathfrak{g}_2$$

starting with some nonassociative algebras or triple systems, which appear as the component  $\mathfrak{g}_1$ .

The concept of  $(\varepsilon, \delta)$ -Freudenthal Kantor triple system covers many of these systems:

**DEFINITION 1.1 [29].** Let  $\varepsilon, \delta = \pm 1$ . A vector space  $V$  over a field  $F$ , endowed with a trilinear operation  $V \times V \times V \rightarrow V$ ,  $(x, y, z) \mapsto xyz$ , is said to be a  $(\varepsilon, \delta)$ -Freudenthal Kantor triple system ( $(\varepsilon, \delta)$ -FKTS for short) if the following two conditions are satisfied

(i)  $[l_{a,b}, l_{c,d}] = l_{l_{a,b}c, d} + \varepsilon l_{c, l_{b,a}d}$ ,

(ii)  $l_{d,c}k_{a,b} - \varepsilon k_{a,b}l_{c,d} = k_{k_{a,b}c, d}$

for any  $a, b, c, d \in V$ , where  $l_{a,b}, k_{a,b} : V \rightarrow V$  are given by  $l_{a,b}c = abc$ ,  $k_{a,b}c = acb - \delta bca$ .

Thus a  $(-1, 1)$ -FKTS is exactly a generalized Jordan triple system of second order in the sense of Kantor [20] (if  $k = 0$  this is just a Jordan triple system), while a

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$(1, -1)$ -FKTS with  $k = 0$  is an anti-Jordan triple system (see [9] for the definition of anti-Jordan pair  $(U^+, U^-)$ ; when  $U^+ = U^-$  one gets an anti-Jordan triple system).

An  $(\varepsilon, \delta)$ -FKTS  $V$  is said to be *balanced* ( $(\varepsilon, \delta)$ -BFKTS for short) if there exists a nonzero bilinear form  $(|) : V \times V \rightarrow F$  such that  $k_{a,b} = (a|b)1_V$  for any  $a, b \in V$  ( $1_V$  denotes the identity map on  $V$ ). Since  $k_{a,b} = -\delta k_{b,a}$  by its own definition,  $(|)$  is either symmetric ( $\delta = -1$ ) or skew-symmetric ( $\delta = 1$ ). On the other hand, condition (ii) in Definition 1.1 gives here that  $(|)$  is either symmetric or skew-symmetric according to  $\varepsilon$  being  $-1$  or  $1$ , so that  $\varepsilon = \delta$  in case  $V$  is balanced.

Any  $(1, 1)$ -BFKTS becomes, by means of minor modifications of its triple product, a symplectic ternary algebra [8], a symplectic triple system [28] or a Freudenthal triple system [21], and conversely. The simple finite dimensional Freudenthal triple systems were classified in [21], with some restrictions which are satisfied if the ground field is algebraically closed, and this amounts to a classification of the simple  $(1, 1)$ -BFKTS (and of the symplectic ternary algebras [8]). The related 5-graded Lie algebras satisfy that  $\mathfrak{g}_{\pm 2}$  is one dimensional.

Further properties of  $(\varepsilon, \delta)$ -FKTS's can be found in [12–18, 24] and the references therein.

Our aim in this paper is to obtain the classification of the finite dimensional simple  $(-1, -1)$ -BFKTS's over fields of characteristic 0. To achieve this, the classification [11] of the finite dimensional simple Lie superalgebras over algebraically closed fields of characteristic 0 will be used, but we will have to look at the known relationship between  $(-1, -1)$ -FKTS's and 5-graded Lie superalgebras [27] in a different way, suitable to our needs. This will be done in Section 2. The relevant examples of  $(-1, -1)$ -BFKTS's will be given in Section 3 and, finally, Section 4 will provide the promised classification (Theorem 4.3), which asserts that the simple finite dimensional  $(-1, -1)$ -BFKTS's fall into six classes, three of them with arbitrarily large dimension: orthogonal, unitarian and symplectic types; and another three classes of four dimensional ( $D_\mu$ -type), seven dimensional ( $G$ -type) and eight dimensional systems ( $F$ -type).

Using Definition 1.1, the defining relations for a  $(-1, -1)$ -BFKTS are

$$ab(xyz) = (abx)yz - x(bay)z + xy(abz), \quad (1.1)$$

$$abx + bax = (a|b)x = axb + bxa, \quad (1.2)$$

for any  $a, b, x, y, z \in V$ , where  $(|)$  is a nonzero symmetric bilinear form. Over fields of characteristic  $\neq 2$ , put  $\langle | \rangle = \frac{1}{2}(|)$  and then (1.2) is equivalent to

$$xxy = \langle x|x \rangle y = xyx \quad (1.3)$$

for any  $x, y \in V$ .

The main motivation for the classification of the simple  $(-1, -1)$ -BFKTS's was provided by the recent paper [19] by two of the authors, where the exceptional simple classical Lie superalgebras were constructed by using the last three classes mentioned above ( $D$ ,  $G$  and  $F$  types). These triple systems are closely related to quaternion and octonion algebras. A different construction of the exceptional simple classical Lie superalgebras has been given in [2] by means of a generalized Tits' construction (which also uses quaternion and octonion algebras).

## 2. $(-1, -1)$ balanced Freudenthal Kantor triple systems and Lie superalgebras.

The relationship between  $(-1, -1)$ -BFKTS and Lie superalgebras has been studied in [19]. A more useful approach for us is obtained as indicated by the next Theorem.

**THEOREM 2.1.** *Let  $\mathfrak{g}$  be a finite dimensional Lie superalgebra over a field  $F$  of characteristic  $\neq 2$  such that  $\mathfrak{g}_0 = \mathfrak{sl}_2(F) \oplus \mathfrak{d}$  (direct sum of ideals) and  $\mathfrak{g}_1 = U \otimes_F V$ , where  $U$  is the two dimensional module for  $\mathfrak{sl}_2(F)$  and  $V$  is a module for  $\mathfrak{d}$ . Let  $\varphi$  be a nonzero skew symmetric form on  $U$ , so that we may identify  $\mathfrak{sl}_2(F) = \mathfrak{sp}(U, \varphi)$  and for any  $a, b \in U$  consider the map  $\varphi_{a,b} \in \mathfrak{sl}_2(F)$  given by*

$$\varphi_{a,b}(c) = \varphi(c, a)b + \varphi(c, b)a$$

for any  $c \in U$ . Then the product of odd elements in  $\mathfrak{g}$  is given by

$$[a \otimes u, b \otimes v] = \langle u \mid v \rangle \varphi_{a,b} + \varphi(a, b)d_{u,v} \tag{2.1}$$

for any  $a, b \in U$  and  $u, v \in V$ , where  $\langle \mid \rangle$  is a symmetric bilinear form and  $V \times V \rightarrow \mathfrak{d}$ ,  $(x, y) \mapsto d_{x,y}$ , is a skew symmetric bilinear map that satisfy

$$\langle d(x) \mid y \rangle + \langle x \mid d(y) \rangle = 0, \tag{2.2a}$$

$$[d, d_{x,y}] = d_{d(x),y} + d_{x,d(y)}, \tag{2.2b}$$

$$d_{x,y}(y) = \langle y \mid x \rangle y - \langle y \mid y \rangle x, \tag{2.2c}$$

for any  $x, y \in V$  and  $d \in \mathfrak{d}$ .

Conversely, let  $V$  be a vector space endowed with a symmetric bilinear form  $\langle \mid \rangle : V \times V \rightarrow F$  and a skew symmetric bilinear map  $V \times V \rightarrow \text{End}_F(V)$   $((u, v) \mapsto d_{u,v})$ . Assume that:

$$\langle d_{u,v}(x) \mid y \rangle + \langle x \mid d_{u,v}(y) \rangle = 0, \tag{2.3a}$$

$$[d_{u,v}, d_{x,y}] = d_{d_{u,v}(x),y} + d_{x,d_{u,v}(y)}, \tag{2.3b}$$

$$d_{x,y}(y) = \langle y \mid x \rangle y - \langle y \mid y \rangle x, \tag{2.3c}$$

for any  $u, v, x, y \in V$ . Let  $\mathfrak{d}$  be  $\text{span}\{d_{u,v} : u, v \in V\}$  (a Lie subalgebra of  $\text{End}_F(V)$  by (2.3b)) and let  $\mathfrak{g} = \mathfrak{g}_0 \oplus \mathfrak{g}_1$  be the superalgebra where  $\mathfrak{g}_0$  is the Lie algebra  $\mathfrak{sl}_2(F) \oplus \mathfrak{d} = \mathfrak{sp}(U, \varphi) \oplus \mathfrak{d}$ ,  $\mathfrak{g}_1$  is the  $\mathfrak{g}_0$ -module  $U \otimes_F V$  and where the product of odd elements is given by (2.1). Then  $\mathfrak{g}$  is a Lie superalgebra.

*Proof.* Since  $\text{Hom}_{\mathfrak{sp}(U, \varphi)}(U \otimes_F U, F)$  is spanned by the form  $\varphi$  and  $\text{Hom}_{\mathfrak{sp}(U, \varphi)}(U \otimes_F U, \mathfrak{sp}(U, \varphi))$  is spanned by the symmetric map  $a \otimes b \mapsto \varphi_{a,b}$ , formula (2.1) follows. Formulae (2.2a) and (2.2b) follow from the Jacobi superidentity applied to the elements  $d \in \mathfrak{d}$  and  $a \otimes x, b \otimes y \in U \otimes_F V$  and (2.2c) follows from the Jacobi superidentity applied to three odd elements.

The converse is a straightforward computation. □

With  $V, V \times V \rightarrow \text{End}_F(V)$ ,  $(x, y) \mapsto d_{x,y}$ , and  $\langle \mid \rangle$  as before, consider the triple product in  $V$  given by

$$xyz = d_{x,y}z + \langle x \mid y \rangle z \tag{2.4}$$

for any  $x, y, z \in V$ . Conditions (2.3a–c) translate into

$$xxy = \langle x \mid x \rangle y = xyx, \tag{2.5a}$$

$$uv(xyz) = (uvx)yz - x(vuy)z + xy(uvz), \tag{2.5b}$$

$$\langle uvx \mid y \rangle = \langle x \mid vuy \rangle, \tag{2.5c}$$

for any  $u, v, x, y, z \in V$ . Let us check (2.5b) for instance. For this, denote by  $l_{x,y}$  the map  $z \mapsto xyz$  for any  $x, y, z \in V$ , then for any  $u, v, x, y \in V$

$$\begin{aligned} [l_{u,v}, l_{x,y}] &= [d_{u,v}, d_{x,y}] \quad (\text{since } l_{u,v} - d_{u,v} \text{ is scalar}) \\ &= d_{d_{u,v}(x),y} + d_{x,d_{u,v}(y)} \\ &= l_{d_{u,v}(x),y} - \langle d_{u,v}(x) \mid y \rangle + l_{x,d_{u,v}(y)} - \langle x \mid d_{u,v}(y) \rangle \\ &= l_{d_{u,v}(x),y} - l_{x,d_{v,u}(y)} \\ &= l_{uvx,y} - \langle u \mid v \rangle l_{x,y} - l_{x,vuy} + \langle v \mid u \rangle l_{x,y} \\ &= l_{uvx,y} - l_{x,vuy} \end{aligned}$$

and this is equivalent to (2.5b). Conversely, conditions (2.5a–c) give conditions (2.3a–c), if (2.4) is used to define  $d_{x,y}$  for  $x, y \in V$ .

Conditions (2.5a) and (2.5b) are just the defining conditions (1.3) and (1.1) of a  $(-1, -1)$ -BFKTS, while condition (2.5c) is a consequence of (2.5a–b) [13]. We include a proof of this fact by completeness:

Take  $x = y$  in (2.5b) and use (2.5a) to get

$$\begin{aligned} \langle x \mid x \rangle uvz &= (uvx)xz - x(vux)z + \langle x \mid x \rangle uvz \\ &= (uvx)xz + ((vux)xz - 2\langle x \mid vux \rangle z) + \langle x \mid x \rangle uvz \\ &= 2\langle u \mid v \rangle xxz - 2\langle x \mid vux \rangle z + \langle x \mid x \rangle uvz \end{aligned}$$

and this shows that  $\langle x \mid vux \rangle = \langle u \mid v \rangle \langle x \mid x \rangle$  for any  $x, u, v \in V$ . Linearizing this one obtains that  $\langle x \mid vuy \rangle + \langle y \mid vux \rangle = 2\langle u \mid v \rangle \langle x \mid y \rangle$  for any  $x, y, u, v \in V$ , whence

$$\langle x \mid vuy \rangle = \langle 2\langle u \mid v \rangle x - vux \mid y \rangle = \langle uvx \mid y \rangle,$$

as desired. In the same way, (2.3a) follows from (2.3b) and (2.3c).

Because of (2.3a–b),  $\mathfrak{d} = d_{V,V}$  is a Lie algebra of derivations of the  $(-1, -1)$ -BFKTS, which will be said to be the Lie algebra of inner derivations of  $V$ .

Given a vector space  $V$  endowed with a nonzero symmetric bilinear form  $\langle \mid \rangle$  and a skew symmetric map  $V \times V \rightarrow \text{End}_F(V)$ ,  $(x, y) \mapsto d_{x,y}$  for any  $x, y \in V$ , satisfying conditions (2.3), denote by  $\mathfrak{g}(V)$  the Lie superalgebra constructed in Theorem 2.1. Also, consider the triple product  $xyz$  defined on  $V$  by (2.4) and the triple product given by  $\{xyz\} = d_{x,y}(z)$  for any  $x, y, z \in V$ .

**THEOREM 2.2.** *Under the hypotheses above, the following conditions are equivalent:*

- (i)  $\langle \mid \rangle$  is nondegenerate,
- (ii)  $(V, \{xyz\})$  is a simple triple system,
- (iii)  $(V, xyz)$  is a simple triple system,
- (iv)  $\mathfrak{g}(V)$  is a simple Lie superalgebra.

*Proof.* Assume that (i) is satisfied and let  $I$  be a nonzero ideal of the triple system  $(V, \{xyz\})$ . Then for any  $x \in I$  and  $y \in V$ ,  $\{xyy\} = d_{x,y}(y) = -\langle y \mid y \rangle x + \langle x \mid y \rangle y \in I$ , by (2.3c), and hence  $\langle x \mid y \rangle y \in I$  for any  $y \in V$ . Since  $\langle \mid \rangle$  is nondegenerate, there is a basis of  $V$  formed by elements  $y$  with  $\langle x \mid y \rangle \neq 0$  and this shows that  $I = V$ . Conversely,  $V^\perp = \{x \in V : \langle x \mid V \rangle = 0\}$  is an ideal of  $(V, \{xyz\})$  because of (2.3a) and the linearization of (2.3c). Hence (ii) implies (i).

Similarly, condition (i) and the linearization of (2.5a) imply (iii), and conversely (iii) implies (i) since  $V^\perp$  is an ideal of  $(V, xyz)$  because of (2.5a) and (2.5c).

Now assume that (i) is satisfied and that  $0 \neq I = I_{\bar{0}} \oplus I_{\bar{1}}$  is an ideal of the Lie superalgebra  $\mathfrak{g}(V)$ . By  $\mathfrak{sl}_2(F)$ -invariance,  $I_{\bar{1}} = U \otimes_F W$  for a subspace  $W$  of  $V$ . Let  $x \in V$  and  $y \in W$  with  $\langle x | y \rangle \neq 0$ , then for any  $a \in U$ ,  $[a \otimes x, a \otimes y] = -\langle x | y \rangle \varphi_{a,a}$ , so  $\varphi_{a,a} \in I_{\bar{0}}$  for any  $a$  and  $\mathfrak{sl}_2(F) \subseteq I_{\bar{0}}$ . But then  $\mathfrak{g}_{\bar{1}} = [\mathfrak{sl}_2(F), \mathfrak{g}_{\bar{1}}] \subseteq I$  and  $\mathfrak{g}_{\bar{0}} = [\mathfrak{g}_{\bar{1}}, \mathfrak{g}_{\bar{1}}] \subseteq I$ , so  $I = \mathfrak{g}$ . Otherwise  $W = 0$ , so  $I_{\bar{1}} = 0$ , but then it is easy to show that  $I = 0$ .

Conversely, the graded subspace  $d_{V,V^\perp} \oplus (U \otimes_F V^\perp)$  is an ideal of  $\mathfrak{g}(V)$ , so (iv) implies (i). □

Since the nondegeneracy of a bilinear form is preserved under scalar extensions, it immediately follows that:

**COROLLARY 2.3.** *With the same notation as above, if  $\langle | \rangle$  is nondegenerate, then  $(V, \{xyz\})$ ,  $(V, xyz)$  and  $\mathfrak{g}(V)$  are central simple.*

**3. Examples.** This section is devoted to constructing the examples of simple  $(-1, -1)$  balanced Freudenthal Kantor triple systems that will appear in the classification. Throughout this section, the ground field  $F$  will be assumed of characteristic  $\neq 2$ .

**3.1. Hermitian type.** Let  $R$  be a unital separable associative algebra over  $F$  of degree  $\leq 2$ . Therefore,  $R$  is, up to isomorphism, either the ground field  $F$ ,  $F \times F$ , a quadratic separable field extension  $K$  of  $F$  or a quaternion algebra  $Q$  over  $F$ . In any case,  $R$  is endowed with an involution of the first kind,  $x \mapsto \bar{x}$ , such that  $x + \bar{x}$ ,  $x\bar{x} = \bar{x}x \in F$  for any  $x \in R$ . Let  $V$  be a left module over  $R$  endowed with a nondegenerate hermitian form  $h : V \times V \rightarrow R$ . That is,  $h$  is  $F$ -bilinear and satisfies for any  $x, y \in V$  and  $r \in R$ :

$$\begin{aligned} h(rx, y) &= rh(x, y), \\ h(x, y) &= \overline{h(y, x)}, \\ h(x, V) &= 0 \text{ if and only if } x = 0. \end{aligned} \tag{3.1}$$

Then the symmetric bilinear form  $V \times V \rightarrow F$  defined by means of

$$\langle x | y \rangle = \frac{1}{2}(h(x, y) + h(y, x)), \tag{3.2}$$

for any  $x, y \in V$ , is nondegenerate and determines  $h$ .

Define now the triple product on  $V$  by means of

$$xyz = h(z, x)y - h(z, y)x + h(x, y)z, \tag{3.3}$$

for any  $x, y, z \in V$ .

It is clear that  $xxxy = h(x, x)y = \langle x | x \rangle y = xyx$  for any  $x, y \in V$  and a straightforward computation shows that this triple product satisfies (2.5b) too. Therefore  $V$  is a  $(-1, -1)$ -BFKTS which will be said to be of *hermitian type*. Depending on  $\dim_F R$  being either 1, 2 or 4,  $V$  will be said to be of *orthogonal*, *unitarian* or *symplectic* type, respectively, for reasons that will become clear later on.

Let us compute the Lie algebra  $\mathfrak{d} = d_{V,V}$  in this case. Assume first that  $R = F$ , the ground field, then  $d_{x,y} = \langle - | x \rangle y - \langle - | y \rangle x =: \sigma_{x,y}$  for any  $x, y \in V$ , and these maps span the orthogonal Lie algebra  $\mathfrak{o}(V)$ . From the construction in [11, Supplement to 2.1.2],  $\mathfrak{g}(V)$  is the orthosymplectic Lie superalgebra  $\mathfrak{osp}(V \oplus U)$ . A word of caution

is needed here: the multiplication of odd elements in [11, Supplement to 2.1.2] should read  $[a \otimes c, b \otimes d] = -(a, b)_0 c \circ d + (c, d)_1 a \wedge b$  (a minus sign has been added).

Now, in case  $R$  is a quadratic étale algebra, that is, either  $K = F \times F$  or  $K$  is a quadratic field extension of  $F$ , then for any  $x, y \in V$ ,

$$d_{x,y} = h_{x,y} + h_0(x, y)1_V, \tag{3.4}$$

where

$$h_{x,y} = h(-, x)y - h(-, y)x \tag{3.5}$$

and

$$h_0(x, y) = h(x, y) - \langle x | y \rangle = \frac{1}{2}(h(x, y) - h(y, x)). \tag{3.6}$$

Note that

$$h_{x,y} \in \mathfrak{u}(V, h) = \{f \in \text{End}_K(V) : h(f(x), y) + h(x, f(y)) = 0 \text{ for any } x, y \in V\}.$$

Since  $\overline{h_0(x, y)} = -h_0(x, y)$ , it follows that  $\mathfrak{d} \subseteq \mathfrak{u}(V, h)$ .

In the split case:  $K = F \times F = Fe_1 \oplus Fe_2$ , for orthogonal idempotents  $e_1$  and  $e_2$  ( $e_1 + e_2 = 1$ ), let  $W = e_1 V$  and  $\tilde{W} = e_2 V$ . Then  $h(W, W) = 0 = h(\tilde{W}, \tilde{W})$  and for any  $a \in W$  and  $u \in \tilde{W}$ ,  $h(a, u) \in Fe_1$ . Hence there is a bilinear nondegenerate form  $(|) : W \times \tilde{W} \rightarrow F$ , such that  $h(a, u) = (a | u)e_1$  for any  $a \in W$  and  $u \in \tilde{W}$ . This bilinear form determines  $h$  and allows us to identify  $\tilde{W}$  with the dual  $W^*$ . Therefore we may assume that  $V = W \times W^*$ , with the natural structure of module over  $K = F \times F$ , and with  $h((a, \alpha), (b, \beta)) = (\beta(a), \alpha(b))$  for any  $a, b \in W$  and  $\alpha, \beta \in W^*$ . Moreover, in this case  $\mathfrak{u}(V, h)$  is isomorphic to  $\mathfrak{gl}(W)$  by means of the isomorphism that takes any  $f \in \text{End}_F(W) = \mathfrak{gl}(W)$  to the endomorphism of  $V = W \times W^*$  given by  $(a, \alpha) \mapsto (f(a), -\alpha \circ f)$ . Through this isomorphism,  $h_{(a,0),(0,\alpha)}$  corresponds to the endomorphism of  $W$  given by  $c \mapsto -\alpha(c)a$ , and hence  $d_{(a,0),(0,\alpha)}$  corresponds to  $c \mapsto -\alpha(c)a + \frac{1}{2}\alpha(a)c$ . If the dimension of  $W$  is not 2, this shows that  $\mathfrak{d} = \mathfrak{u}(V, h) \cong \mathfrak{gl}(W)$ , while if the dimension is 2,  $\mathfrak{d} = \mathfrak{su}(V, h) \cong \mathfrak{sl}(W)$ .

By scalar extension, we have that  $\mathfrak{d} = \mathfrak{u}(V, h)$  if  $\dim_K V \neq 2$  ( $\dim_F V \neq 4$ ) and  $\mathfrak{d} = \mathfrak{su}(V, h)$  if  $\dim_K V = 2$ .

Finally, assume that  $R$  is a quaternion algebra  $Q$ . Again  $d_{x,y} = h_{x,y} + h_0(x, y)1_V$ , but now  $h_{x,y}$  is  $Q$ -linear, while  $h_0(x, y)1_V$  is not in general, since the center of  $Q$  is  $F$ . It is easily checked here that  $[h_{x,y}, h_{u,v}] = h_{h_{x,y}(u),v} + h_{u,h_{x,y}(v)}$  for any  $x, y, u, v \in V$ , and thus  $h_{V,V} = \text{span} \{h_{x,y} : x, y \in V\}$  is a Lie algebra contained in

$$\mathfrak{sp}(V, h) = \{f \in \text{End}_Q(V) : h(f(x), y) + h(x, f(y)) = 0 \text{ for any } x, y \in V\},$$

and  $\mathfrak{d} = d_{V,V}$  is contained in  $\mathfrak{sp}(V, h) \oplus Q_0 1_V$ , where  $Q_0 = [Q, Q]$  is the set of skew symmetric elements in  $Q$  relative to its involution, which form a three dimensional simple Lie algebra.

Again, consider the split case:  $Q = \text{End}_F(U)$  for a two dimensional vector space  $U$  endowed with a nonzero skew symmetric bilinear map  $\varphi$  which induces the involution in  $Q$ . Standard arguments of complete reducibility as a module over  $Q$  show that  $V = U \otimes_F W$  for some vector space  $W$  over  $F$ . For any  $q \in Q_0 = \mathfrak{sl}(U) = \mathfrak{sp}(U, \varphi)$

and for any  $x, y \in V$ ,

$$\begin{aligned} \langle qx \mid y \rangle &= \frac{1}{2}(h(qx, y) + h(y, qx)) = \frac{1}{2}(qh(x, y) + \overline{qh(x, y)}) \\ &= \frac{1}{2}(h(x, y)q + \overline{h(x, y)q}) = -\langle x \mid qy \rangle, \end{aligned}$$

so  $Q_0$  embeds into the orthogonal Lie algebra  $\mathfrak{o}(V, \langle \mid \rangle)$  and, therefore,  $\langle \mid \rangle$  is invariant under the action of  $\mathfrak{sl}(U) = \mathfrak{sp}(U, \varphi)$ . But, up to scalars,  $\varphi$  is the unique bilinear form on  $U$  which is  $\mathfrak{sp}(U, \varphi)$ -invariant, so  $\langle a \otimes u \mid b \otimes v \rangle = \frac{1}{2}\varphi(a, b)\psi(u, v)$ , for any  $a, b \in U, u, v \in W$ , for a skew-symmetric nondegenerate bilinear form  $\psi : W \times W \rightarrow F$ .

Since the hermitian form  $h$  is completely determined by  $\langle \mid \rangle$ , it turns out that  $h : V \times V \rightarrow Q = \text{End}_F(U)$  is given by  $h(a \otimes u, b \otimes v) = \psi(u, v)\varphi(-, b)a$ , for any  $a, b \in U$  and  $u, v \in W$ . Note that  $h$  thus defined is hermitian and

$$\frac{1}{2}(h(a \otimes u, b \otimes v) + h(b \otimes v, a \otimes u)) = \frac{1}{2}\psi(u, v)(\varphi(-, b)a - \varphi(-, a)b).$$

But  $\varphi(a, b)c + \varphi(b, c)a + \varphi(c, a)b = 0$  for any  $a, b, c \in U$ , so

$$\frac{1}{2}(h(a \otimes u, b \otimes v) + h(b \otimes v, a \otimes u)) = \frac{1}{2}\psi(u, v)\varphi(a, b)1_V.$$

Hence, for any  $a, b \in U$  and  $u, v \in W$ :

$$\begin{aligned} h_0(a \otimes u, b \otimes v) &= \frac{1}{2}(h(a \otimes u, b \otimes v) - h(b \otimes v, a \otimes u)) \quad (\text{see (3.6)}) \\ &= \frac{1}{2}\psi(u, v)(\varphi(-, b)a + \varphi(-, a)b) = \frac{1}{2}\psi(u, v)\varphi_{a,b}, \end{aligned}$$

and thus, for any  $a, b, c \in U$  and  $u, v, w \in W$ :

$$\begin{aligned} h_{a \otimes u, b \otimes v}(c \otimes w) &= \psi(w, u)\varphi(b, a)c \otimes v - \psi(w, v)\varphi(a, b)c \otimes u \\ &= -\varphi(a, b)c \otimes (\psi(w, u)v + \psi(w, v)u) = -\varphi(a, b)c \otimes \psi_{u,v}(w). \end{aligned}$$

Therefore,  $h_{V,V} = \mathfrak{sp}(V, h) := \{f \in \text{End}_Q(V) : h(f(x), y) + h(x, f(y)) = 0 \text{ for any } x, y \in V\} \cong \mathfrak{sp}(W, \psi)$  (which acts on  $V = U \otimes_F W$  in a natural way: on the second factor). Moreover, from (3.4),

$$d_{a \otimes u, b \otimes v} = h_{a \otimes u, b \otimes v} + h_0(a \otimes u, b \otimes v)1_V = \frac{1}{2}\varphi_{a,b} \otimes \psi(u, v)1_W - \varphi(a, b)1_U \otimes \psi_{u,v},$$

so  $\mathfrak{d} = d_{V,V} = \mathfrak{sp}(U, \varphi) \oplus \mathfrak{sp}(W, \psi) = \mathfrak{sl}(U) \oplus \mathfrak{sp}(W, \psi)$ .

For general  $Q$ , again extending scalars we arrive at  $h_{V,V} = \mathfrak{sp}(V, h)$  (which is a simple Lie algebra of type C) and  $\mathfrak{d}$  is the direct sum of the three dimensional simple Lie algebra  $Q_0$  and of the simple Lie algebra  $\mathfrak{sp}(V, h)$ .

Summarizing the above discussion:

**PROPOSITION 3.1.** *Let  $R$  be a unital separable associative algebra of degree  $\leq 2$  over a field  $F$  of characteristic  $\neq 2$ , and let  $V$  be a left module over  $R$  endowed with a nondegenerate hermitian form  $h : V \times V \rightarrow R$ . Endow  $V$  with the structure of a simple  $(-1, -1)$ -BFKTS of hermitian type (with associated symmetric bilinear form given by*

$\langle x | y \rangle = \frac{1}{2}(h(x, y) + h(y, x))$  for any  $x, y \in V$  and let  $\mathfrak{d} = d_{V,V}$  be the associated Lie algebra of inner derivations. Then:

- (i) If  $R = F$ , then  $\mathfrak{d} = \mathfrak{o}(V, \langle | \rangle)$ .
- (ii) If  $R = K$  is a quadratic étale algebra, then  $\mathfrak{d} = \mathfrak{u}(V, h)$  unless  $\dim_F(V) = 4$ . In this latter case,  $\mathfrak{d} = \mathfrak{su}(V, h)$ .
- (iii) If  $R$  is a quaternion algebra  $Q$ , then  $\mathfrak{d} \cong Q_0 \oplus \mathfrak{sp}(V, h)$ , where  $\mathfrak{sp}(V, h)$  acts naturally on  $V$ , and the simple three dimensional Lie algebra  $Q_0$  acts by left multiplication on the  $Q$  module  $V$ .

**3.2.  $D_\mu$ -type.** Let  $V$  be a four dimensional vector space, endowed with a nondegenerate symmetric bilinear form  $\langle | \rangle$ . Let  $\Phi$  be a nonzero skew symmetric multilinear form:  $\Phi : V \times V \times V \times V \rightarrow F$ . Define a skew symmetric triple product  $[xyz]$  on  $V$  by means of:

$$\Phi(x, y, z, t) = \langle [xyz] | t \rangle, \tag{3.7}$$

for any  $x, y, z, t \in V$ . The proof of the next result is left to the reader.

LEMMA 3.2. *With the hypotheses above, there exists a nonzero scalar  $\mu \in F$  such that*

$$\langle [a_1 a_2 a_3] | [b_1 b_2 b_3] \rangle = \mu \det(\langle a_i | b_j \rangle), \tag{3.8}$$

for any  $a_i, b_i \in V$  ( $i = 1, 2, 3$ ).

Now, for any such  $V$  and  $\Phi$ , and for any  $x, y \in V$ , consider the endomorphism  $d_{x,y} \in \text{End}_F(V)$  defined by

$$d_{x,y}z = [xyz] + \langle z | x \rangle y - \langle z | y \rangle x. \tag{3.9}$$

As shown in [22, §5], conditions (2.3a–b) are satisfied, so if the triple product  $xyz$  on  $V$  is defined by means of

$$xyz = [xyz] + \langle z | x \rangle y - \langle z | y \rangle x + \langle x | y \rangle z. \tag{3.10}$$

for any  $x, y, z \in V$ , then  $V$  becomes a  $(-1, -1)$ -BFKTS, which will be said to be of  $D_\mu$ -type.

Assume for a while that the scalar  $\mu$  in (3.8) is a square,  $\mu = v^2$ ,  $0 \neq v \in F$ , and that  $\langle | \rangle$  represents 1. Then, by [4, Theorem 2],  $V$  is endowed with a binary multiplication that makes it a quaternion algebra  $Q$  over  $F$ , with involution  $x \mapsto \bar{x}$  such that  $x\bar{x} = \langle x | x \rangle$  for any  $x \in V$ , satisfying

$$v^{-1}[xyz] = x\bar{y}z - \langle x | y \rangle z + \langle z | x \rangle y - \langle z | y \rangle x$$

for any  $x, y, z \in V$ . Therefore, for any  $x, y, z \in V$ , (3.9) shows that:

$$\begin{aligned} d_{x,y}(z) &= vx\bar{y}z + (1 + v)(\langle z | x \rangle y - \langle z | y \rangle x) - v\langle x | y \rangle z \\ &= vx\bar{y}z + \frac{1 + v}{2}((x\bar{z} + z\bar{x})y - x(\bar{y}z + \bar{z}y)) - \frac{v}{2}(x\bar{y} + y\bar{x})z \\ &= \left( vx\bar{y} - \frac{1 + v}{2}x\bar{y} - \frac{v}{2}(x\bar{y} + y\bar{x}) \right) z + \frac{1 + v}{2}z\bar{x}y \\ &= \left( -\frac{1}{2}x\bar{y} - \frac{v}{2}y\bar{x} \right) z + \frac{1 + v}{2}z\bar{x}y = \frac{v - 1}{4}(x\bar{y} - y\bar{x})z + \frac{1 + v}{4}z(\bar{x}y - \bar{y}x), \end{aligned}$$

because  $\bar{x}y + \bar{y}x = x\bar{y} + y\bar{x} = 2\langle x | y \rangle \in F$ , so  $\bar{x}y - \bar{y}x = 2\bar{x}y - (x\bar{y} + y\bar{x})$ . Hence, for any  $x, y \in V$ ,  $d_{x,y} = L_p - R_q$ , with  $p = \frac{\nu-1}{4}(x\bar{y} - y\bar{x})$ ,  $q = -\frac{\nu+1}{4}(x\bar{y} - \bar{y}x) \in Q_0$ , where  $L$  and  $R$  denote left and right multiplications in  $V = Q$ . Therefore, if  $\mu = 1$  ( $\nu = \pm 1$ ),  $\mathfrak{d} = d_{V,V}$  is isomorphic to the three dimensional simple Lie algebra  $Q_0$ . However, if  $\mu \neq 0, 1$  ( $\nu \neq 0, \pm 1$ ), then  $\mathfrak{d} = L_{Q_0} \oplus R_{Q_0}$ , a direct sum of two copies of the three dimensional Lie algebra  $Q_0$ , which coincides with the orthogonal Lie algebra  $\mathfrak{o}(V, \langle | \rangle)$ . Moreover, in this latter case, [2, Lemma 3.1 and its proof],  $\mathfrak{g}(V)$  is a form of the simple Lie superalgebra  $\Gamma(-\frac{1}{2}, \frac{1-\nu}{4}, \frac{1+\nu}{4})$  (notation as in [26, pp. 16–17]). That is, it is a form of  $D(2, 1; \frac{\nu-1}{2})$  (see also [19]).

Simply by extending scalars, we obtain:

**PROPOSITION 3.3.** *Let  $V$  be a four dimensional vector space over a field  $F$  of characteristic  $\neq 2$  with a nondegenerate symmetric bilinear form  $\langle | \rangle$ . Let  $\Phi$  be a nonzero skew symmetric 4-linear form and let the triple product  $[xyz]$  be defined by means of  $\langle [xyz] | t \rangle = \Phi(x, y, z, t)$  for any  $x, y, z, t \in V$ . Let  $0 \neq \mu \in F$  be given by (3.8). Endow  $V$  with the structure of a simple  $(-1, -1)$ -BFKTS by means of (3.10) and let  $\mathfrak{d} = d_{V,V}$  be the corresponding Lie algebra of inner derivations. Then:*

- (i) *If  $\mu = 1$ , then  $\mathfrak{d}$  is a three dimensional simple ideal of the orthogonal Lie algebra  $\mathfrak{o}(V, \langle | \rangle)$ .*
- (ii) *If  $\mu \neq 0, 1$ , then  $\mathfrak{d}$  coincides with the orthogonal Lie algebra  $\mathfrak{o}(V, \langle | \rangle)$ .*

There is some overlapping in the types considered up to now.

To begin with, let  $V$  be any four dimensional simple  $(-1, -1)$ -BFKTS and let  $[xyz]$  be defined by  $[xyz] = xyz - \langle z | x \rangle y + \langle z | y \rangle x - \langle x | y \rangle z$ , for any  $x, y, z \in V$ . Because of (2.5a),  $[xyz]$  is skew symmetric on its arguments. In case  $[xyz]$  is identically zero, we are in presence of a system of orthogonal type. Otherwise, this is a system of D-type. This means that the systems of hermitian type with  $R = K$  or  $Q$  and with  $\dim_F V = 4$  are systems of D-type. Let us check which  $\mu$ 's are involved in these cases. To do so, it is enough to consider the split cases.

Assume  $K = F \times F$  and  $V = W \times W^*$  with  $h((a, \alpha), (b, \beta)) = (\beta(a), \alpha(b))$  for any  $a, b \in W$  and  $\alpha, \beta \in W^*$  and with  $\dim_F W = 2$ . Take  $a, b \in W$  and  $\alpha, \beta \in W^*$  with  $\alpha(a) = 1 = \beta(b)$ ,  $\alpha(b) = 0 = \beta(a)$ . Then with  $(a_1, \alpha_1) = (a, 0)$ ,  $(a_2, \alpha_2) = (0, \alpha)$  and  $(a_3, \alpha_3) = (b, \beta)$ ,

$$\det(\langle (a_i, \alpha_i) | (a_j, \alpha_j) \rangle) = \begin{vmatrix} 0 & \frac{1}{2} & 0 \\ \frac{1}{2} & 0 & 0 \\ 0 & 0 & 1 \end{vmatrix} = -\frac{1}{4},$$

while  $\langle (a, 0)(0, \alpha)(b, \beta) \rangle = \frac{1}{2}\langle b, \beta \rangle$  and

$$\langle \langle (a, 0)(0, \alpha)(b, \beta) \rangle | \langle (a, 0)(0, \alpha)(b, \beta) \rangle \rangle = \frac{1}{4}\langle (b, -\beta) | (b, -\beta) \rangle = -\frac{1}{4}.$$

Hence,  $\mu = 1$  in this case. (This can also be deduced directly from the size of the Lie algebras  $\mathfrak{d}$ .)

Assume now that  $R = Q$  is a quaternion algebra and  $\dim_F V = 4$ , then  $V$  is a free  $Q$ -module of rank 1 and hence we may assume that  $V = Q$  and that  $h(x, y) = \alpha x\bar{y}$  for any  $x, y \in Q$ , where  $0 \neq \alpha = h(1, 1) \in F$ . Then for any  $x_1, x_2, x_3 \in Q$ ,

$$[x_1x_2x_3] = h_0(x_3, x_1)x_2 - h_0(x_3, x_2)x_1 + h_0(x_1, x_2)x_3$$

where  $h_0(x, y) = \frac{1}{2}(h(x, y) - h(y, x)) = \alpha(x\bar{y} - y\bar{x}) \in Q_0$ . By skew symmetry of  $h_0$ ,

$$[x_1x_2x_3] = \frac{1}{2} \sum_{\sigma} h_0(x_{\sigma(1)}, x_{\sigma(2)})x_{\sigma(3)} = \frac{\alpha}{2}(-1)^{\sigma} x_{\sigma(1)}\bar{x}_{\sigma(2)}x_{\sigma(3)}$$

where the sum is over all the permutations of 1, 2, 3. Take  $x_1 = 1$ ,  $x_2$ , and  $x_3$  mutually orthogonal to get  $\langle 1 | 1 \rangle = h(1, 1) = \alpha$ ,  $\det(\langle x_i | x_j \rangle) = \alpha \langle x_2 | x_2 \rangle \langle x_3 | x_3 \rangle$ , while  $[x_1x_2x_3] = -3\alpha x_2x_3$  since  $x_2x_3 = -x_3x_2$ ,  $\bar{x}_i = -x_i$  for  $i = 2, 3$ , and  $\bar{1} = 1$ . Thus,  $\langle [x_1x_2x_3] | [x_1x_2x_3] \rangle = 9\alpha^3 \langle x_2x_3 | x_2x_3 \rangle = 9\alpha \langle x_2 | x_2 \rangle \langle x_3 | x_3 \rangle$ , and  $\mu = 9$  in this case.

A final overlap occurs if  $V$  is of hermitian type with  $R = K$  quadratic and with  $\dim_F V = 2$ . As above,  $[x_1x_2x_3] = \frac{1}{2} \sum_{\sigma} h_0(x_{\sigma(1)}, x_{\sigma(2)})x_{\sigma(3)}$  for any  $x_1, x_2, x_3 \in V$ . By skew symmetry and dimension, this is zero, and therefore we are in the situation of  $R = F$ . We summarize the above arguments in the following remark, whose last part follows from the structure of the Lie algebras of inner derivations.

REMARK 3.4.

- The simple  $(-1, -1)$ -BFKTS  $V$  of unitarian type and  $\dim_F V = 2$  are also of orthogonal type.
- The simple  $(-1, -1)$ -BFKTS  $V$  of unitarian type and  $\dim_F V = 4$  are of  $D_1$ -type.
- The simple  $(-1, -1)$ -BFKTS  $V$  of symplectic type and  $\dim_F V = 4$  are of  $D_9$ -type.
- There are no more overlaps among different types.

**3.3. G-type.** Let  $C$  be an eight-dimensional Cayley-Dickson (or octonion) algebra over  $F$  with norm  $n$  and trace  $t$ . Let  $C_0$  be the set of trace zero elements. For any  $x, y \in C$ , the linear map

$$D_{x,y} = [L_x, L_y] + [L_x, R_y] + [R_x, R_y] \tag{3.11}$$

(where  $L_x$  and  $R_x$  denote the left and right multiplication by  $x$ ) is known to be a derivation of  $C$  [25, Ch. III.8], and hence it leaves  $C_0$  invariant. Consider then, for any  $0 \neq \alpha \in F$ , the nondegenerate symmetric bilinear form and the triple product on  $V = C_0$  given by  $\langle x | y \rangle = -2\alpha t(xy)$  and  $xyz = \alpha(D_{x,y}(z) - 2t(xy)z)$ , for any  $x, y, z \in V$ . Since  $D_{x,y}$  is a derivation and

$$\begin{aligned} D_{x,y}(y) &= xy^2 - y(xy) + xy^2 - (xy)y + y^2x - (yx)y = 4y^2x - 2(xy + yx)y \\ &= -4n(y)x - 2t(xy)y = -\langle y | y \rangle x + \langle x | y \rangle y, \end{aligned}$$

where we have used that  $x^2 = -n(x)1 = -\frac{1}{2}t(x^2)1$  for any  $x \in V = C_0$ ; it follows from (2.3) that  $V$  is a  $(-1, -1)$ -BFKTS (see also [19]), which will be said to be of G-type. It is clear here that the Lie algebra  $\mathfrak{d}$  is the span of the  $D_{x,y}$ 's, which is precisely the Lie algebra of derivations of the Cayley-Dickson algebra  $C$  in case the characteristic is  $\neq 3$  [25, Ch. III.8], a simple Lie algebra of type  $G_2$ . (If the characteristic is 3, then this is a seven dimensional simple Lie algebra which is a form of  $\mathfrak{psl}(7)$  [1].)

**3.4. F-type.** Let  $X$  be a 3-fold vector cross product on a vector space  $V$  of dimension 8, endowed with a nondegenerate symmetric bilinear form  $\langle | \rangle$ . That is,  $X$  is a trilinear map  $X : V \times V \times V \rightarrow V$ ,  $(a, b, c) \mapsto X(a, b, c)$ , satisfying (see [4], [23],

Ch. 8] and the references therein):

$$\begin{aligned} \langle X(a_1, a_2, a_3) \mid a_i \rangle &= 0 \text{ for any } i = 1, 2, 3, \\ \langle X(a_1, a_2, a_3) \mid X(a_1, a_2, a_3) \rangle &= \det(\langle a_i \mid a_j \rangle), \end{aligned} \tag{3.12}$$

for any  $a_1, a_2, a_3 \in V$ .

It is known that (3.12) implies the skew symmetry of  $X$ . Moreover,  $X$  satisfies:

$$\begin{aligned} \langle X(a_1, a_2, a_3) \mid X(b_1, b_2, b_3) \rangle \\ = \det(\langle a_i \mid b_j \rangle) + \epsilon \sum_{\sigma \text{ even}} \sum_{\tau \text{ even}} \langle a_{\sigma(1)} \mid b_{\tau(1)} \rangle \Phi(a_{\sigma(2)}, a_{\sigma(3)}, b_{\tau(2)}, b_{\tau(3)}) \end{aligned} \tag{3.13}$$

for any  $a_i, b_i \in V$  ( $i = 1, 2, 3$ ), where  $\Phi(a, b, c, d) = \langle a \mid X(b, c, d) \rangle$  for any  $a, b, c, d \in V$ , and  $\epsilon = \pm 1$ . In case  $\epsilon = 1$  (resp.  $-1$ ),  $X$  is said to be of type I (resp. II). Also, if  $\dim_F V = 8$  and  $X$  is of type I, then  $-X$  is of type II, and conversely.

Assume now that the characteristic of the ground field  $F$  is  $\neq 2, 3$ . Given a 3-fold vector cross product  $X$  of type I, define  $d_{x,y} \in \text{End}_F(V)$ ,  $x, y \in V$ , by means of:

$$d_{x,y}z = \frac{1}{3}X(x, y, z) + \langle z \mid x \rangle y - \langle z \mid y \rangle x. \tag{3.14}$$

As shown in [22, §5], condition (2.3b) is satisfied, so if the triple product  $xyz$  on  $V$  is defined by means of

$$xyz = \frac{1}{3}X(x, y, z) + \langle z \mid x \rangle y - \langle z \mid y \rangle x + \langle x \mid y \rangle z. \tag{3.15}$$

for any  $x, y, z \in V$ , then  $V$  becomes a  $(-1, -1)$ -BFKTS, which will be said to be of F-type.

Since  $d_{x,y}$  is a derivation of the triple system and it is skew symmetric relative to  $\langle \mid \rangle$ , it follows that  $d_{x,y}$  is a derivation of the 3-fold vector cross product  $X$ . According to [4, Theorem 12], if  $e$  is an element of  $V$  with  $\langle e \mid e \rangle \neq 0$ ,  $W = \{v \in V : \langle e \mid x \rangle = 0\}$ , and  $q$  is the nondegenerate quadratic form on  $V$  defined by  $q(v) = -\langle e \mid e \rangle^{-1} \langle v \mid v \rangle$ , then the Lie algebra of derivations of  $X$  is isomorphic to the orthogonal Lie algebra  $\mathfrak{o}(W, q)$ . Actually,  $V$  has the structure of an eight dimensional Cayley-Dickson algebra  $C$  with unit  $1 = e$ , so that there is an scalar  $0 \neq \alpha \in F$  such that  $X(a, b, c) = \alpha((ab)c + (a \mid c)b - (b \mid c)a - (a \mid b)c)$  and  $\langle a \mid b \rangle = \alpha(a \mid b)$ , for any  $a, b, c \in V = C$ . Here  $x \mapsto \bar{x}$  denotes the involution and  $(a \mid a) = a\bar{a}$  is the norm of  $C$ . Note that  $\alpha = \langle e \mid e \rangle$ . Hence for any  $x, y \in V$ ,  $d_{x,y}$  is a derivation of the 3C-product given by  $(a\bar{b})c$  (see [4]). But for any  $x, y, z \in V = C$ ,  $\frac{3}{\alpha}d_{x,y}(z) = (x\bar{y})z + 4(z \mid x)y - 4(z \mid x)x - (x \mid y)z$ , in particular, for a traceless  $x$  ( $\bar{x} = -x$ ),  $\frac{3}{\alpha}d_{e,x}(y) = -xy + 2x(y + \bar{y}) - 2(x\bar{y} - yx) = xy + 2yx = (L + 2R)_x(y)$ , that is,  $d_{e,x} = (L + 2R)_x$ , where  $L$  and  $R$  denote the left and right multiplications in  $C$ . But these operators generate the Lie algebra of derivations of the triple product given by  $(a\bar{b})c$  [7, 4] (see also [5]), so we conclude that  $\mathfrak{d}$  is isomorphic to  $\mathfrak{o}(W, q)$ .

Note that in [19] it is already proved that, after scalar extension,  $\mathfrak{d}$  is isomorphic to  $\mathfrak{o}(7)$ , by an explicit computation.

**4. Classification.** Given a  $(-1, -1)$ -BFKTS  $V$  over a field of characteristic  $\neq 2$ , in Section 2 a simple Lie superalgebra  $\mathfrak{g} = \mathfrak{g}(V)$  has been defined that contains a copy  $\mathfrak{s} = \mathfrak{s}(V)$  of  $\mathfrak{sl}_2(F)$ , which is an ideal of  $\mathfrak{g}_0$  that is complemented by the ideal  $\mathfrak{d} = \mathfrak{d}(V) = d_{V,V}$ . In this situation  $\mathfrak{d} = \{d \in \mathfrak{g}_0 : [d, \mathfrak{s}] = 0\}$  is completely determined by  $\mathfrak{g}$  and  $\mathfrak{s}$ . Moreover, as a module for  $\mathfrak{g}_0$ ,  $\mathfrak{g}_1$  is the tensor product of the two dimensional irreducible module for  $\mathfrak{s}$  and the module  $V$  for  $\mathfrak{d}$ .

Consider a ground field  $F$  of characteristic  $\neq 2$  and the pairs  $(\mathfrak{g}, \mathfrak{s})$ , where  $\mathfrak{g}$  is a Lie superalgebra over  $F$  and  $\mathfrak{s}$  is a complemented ideal of  $\mathfrak{g}_0$  isomorphic to  $\mathfrak{sl}_2(F)$ . Two such pairs  $(\mathfrak{g}^1, \mathfrak{s}^1), (\mathfrak{g}^2, \mathfrak{s}^2)$  are said to be isomorphic if there is an isomorphism of Lie superalgebras  $\phi : \mathfrak{g}^1 \rightarrow \mathfrak{g}^2$  such that  $\phi(\mathfrak{s}^1) = \mathfrak{s}^2$ .

Given a Lie superalgebra  $\mathfrak{g} = \mathfrak{g}_0 \oplus \mathfrak{g}_1$  and a nonzero scalar  $\alpha$ , the new Lie superalgebra defined over  $\mathfrak{g}$  with the new product  $[\cdot, \cdot]_\alpha$  given, for homogeneous elements, by

$$\begin{cases} [x, y]_\alpha = \alpha[x, y] & \text{if both } x \text{ and } y \text{ are odd} \\ [x, y]_\alpha = [x, y] & \text{otherwise} \end{cases}$$

will be denoted by  $\mathfrak{g}_\alpha$ . Also, given a  $(-1, -1)$ -BFKTS  $V$ , we will denote by  $V_\alpha$  the new  $(-1, -1)$ -BFKTS defined on  $V$  but with the new product given by  $(xyz)_\alpha = \alpha xyz$ , and new symmetric bilinear form given by  $\langle x | y \rangle_\alpha = \alpha \langle x | y \rangle$ , for any  $x, y, z \in V$ . From the definitions, it is clear that  $\mathfrak{g}(V_\alpha) = \mathfrak{g}(V)_\alpha$ . Two  $(-1, -1)$ -BFKTS  $V^1$  and  $V^2$  will be said to be *equivalent* in case there is a nonzero scalar  $\alpha$  such that  $V^1$  and  $V^2_\alpha$  are isomorphic.

**THEOREM 4.1.** *Let  $V^1$  and  $V^2$  be two  $(-1, -1)$ -BFKTS's. Then  $V^1$  is equivalent to  $V^2$  if and only if  $(\mathfrak{g}(V^1), \mathfrak{s}(V^1))$  is isomorphic to  $(\mathfrak{g}(V^2), \mathfrak{s}(V^2))$ .*

*Proof.* Let  $\mathfrak{g}^i = \mathfrak{g}(V^i)$  and  $\mathfrak{d}^i = \mathfrak{d}(V^i) = d_{V^i, V^i}$  for  $i = 1, 2$ . Also,  $\mathfrak{s}(V^1) = \mathfrak{s}(V^2) = \mathfrak{sp}(U, \varphi)$  as in Section 2. Thus  $\mathfrak{g}^i_0 = \mathfrak{sp}(U, \varphi) \oplus \mathfrak{d}^i$  and  $\mathfrak{g}^i_1 = U \otimes_F V^i$ , for  $i = 1, 2$ . Let  $\Phi : \mathfrak{g}^1 \rightarrow \mathfrak{g}^2$  be an isomorphism such that it restricts to an automorphism of  $\mathfrak{sp}(U, \varphi)$ . But any automorphism  $\xi$  of  $\mathfrak{sp}(U, \varphi)$  can be extended as in [6, proof of Lemma 2.1] to an isomorphism from  $\mathfrak{g}^2$  onto  $\mathfrak{g}^2_\alpha$  for some nonzero scalar  $\alpha$  and, therefore, we may (and will) assume that  $\Phi$  is the identity on  $\mathfrak{sp}(U, \varphi)$ . Since  $\mathfrak{d}^i$  is the centralizer of  $\mathfrak{sp}(U, \varphi)$  in  $\mathfrak{g}^i_0$ ,  $i = 1, 2$ ,  $\Phi$  restricts to an isomorphism  $\Psi : \mathfrak{d}^1 \rightarrow \mathfrak{d}^2$ . Also,  $\Phi$  restricts then to an isomorphism of  $\mathfrak{sp}(U, \varphi)$ -modules  $\Phi_1 : U \otimes_F V^1 \rightarrow U \otimes_F V^2$ . Since  $U$  is absolutely irreducible as a module for  $\mathfrak{sp}(U, \varphi)$ , there is an isomorphism of vector spaces  $\psi : V^1 \rightarrow V^2$  such that  $\Phi(a \otimes x) = a \otimes \psi(x)$  for any  $a \in U$  and  $x \in V^1$ .

Now, for any  $x, y, z \in V^1$  and any  $a \in U$ , we have  $a \otimes \psi(d_{x,y}(z)) = \Phi([d_{x,y}, a \otimes z]) = [\Psi(d_{x,y}), a \otimes \psi(z)] = a \otimes \Psi(d_{x,y})(\psi(z))$ , so

$$\psi(d_{x,y}(z)) = \Psi(d_{x,y})(\psi(z)), \tag{4.1}$$

for any  $x, y, z \in V^1$ . Also, for any  $a, b \in U$  and  $x, y \in V^1$  we have  $\Phi([a \otimes x, b \otimes y]) = [a \otimes \psi(x), b \otimes \psi(y)] = \langle \psi(x) | \psi(y) \rangle \varphi_{a,b} + \varphi(a, b) d_{\psi(x), \psi(y)}$ , but also  $\Phi([a \otimes x, b \otimes y]) = \Phi(\langle x | y \rangle \varphi_{a,b} + \varphi(a, b) d_{x,y}) = \langle x | y \rangle \varphi_{a,b} + \varphi(a, b) \Psi(d_{x,y})$ . So

$$\begin{cases} \Psi(d_{x,y}) = d_{\psi(x), \psi(y)}, \\ \langle \psi(x) | \psi(y) \rangle = \langle x | y \rangle, \end{cases} \tag{4.2}$$

for any  $x, y \in V^1$ , which, together with (4.1), shows that  $\psi$  is an isomorphism between the triple systems  $V^1$  and  $V^2$ .

For the converse, if  $V^1$  and  $V^2$  are equivalent, there is a  $0 \neq \alpha \in F$  such that  $V^1$  and  $V_\alpha^2$  are isomorphic. From here it is easy to deduce that the pairs  $(\mathfrak{g}(V^1), \mathfrak{s}(V^1))$  and  $(\mathfrak{g}(V_\alpha^2), \mathfrak{s}(V_\alpha^2))$  are isomorphic. But  $\mathfrak{g}(V_\alpha^2)$  is isomorphic to  $\mathfrak{g}(V^2)$  by means of an isomorphism taking  $\mathfrak{s}(V^2)$  into itself (see [6, proof of Lemma 2.1]).  $\square$

In order to classify the simple  $(-1, -1)$ -BFKTS of finite dimension over a field of characteristic zero, we will first assume that the ground field  $F$  is algebraically closed. Following Theorems 2.1, 2.2 and 4.1, we will determine, up to isomorphism, the pairs  $(\mathfrak{g}, \mathfrak{s})$ , where  $\mathfrak{g}$  is a simple finite dimensional Lie superalgebra and  $\mathfrak{s}$  is an ideal of  $\mathfrak{g}_0$  isomorphic to  $\mathfrak{sl}(2)$ :

**THEOREM 4.2.** *Let  $F$  be an algebraically closed field of characteristic zero. The following list exhausts, up to isomorphism, the pairs  $(\mathfrak{g}, \mathfrak{s})$ , where  $\mathfrak{g}$  is a simple finite dimensional Lie superalgebra over  $F$  ( $\mathfrak{g}_1 \neq 0$ ) and  $\mathfrak{s}$  is a three dimensional simple ideal of  $\mathfrak{g}_0$ .*

- (i)  $\mathfrak{g} = \mathfrak{sl}(m, 2)$ ,  $m \geq 3$ , and  $\mathfrak{s}$  is the (unique) ideal of  $\mathfrak{g}_0$  isomorphic to  $\mathfrak{sl}(2)$ .
- (ii)  $\mathfrak{g} = \mathfrak{psl}(2, 2)$  and  $\mathfrak{s}$  is any of the two simple ideals of  $\mathfrak{g}_0$ .
- (iii)  $\mathfrak{g} = \mathfrak{osp}(m, 2)$ ,  $m \geq 1$ ,  $m \neq 4$ , so that  $\mathfrak{g}_0 = \mathfrak{o}(m) \oplus \mathfrak{sp}(2)$ , and  $\mathfrak{s}$  is the copy of  $\mathfrak{sp}(2)$ .
- (iv)  $\mathfrak{g} = \mathfrak{osp}(4, 2r)$ ,  $r \geq 2$ , so that  $\mathfrak{g} = \mathfrak{o}(4) \oplus \mathfrak{sp}(2r)$  and  $\mathfrak{s}$  is any of the two simple simple ideals of  $\mathfrak{o}(4) \cong \mathfrak{sl}(2) \oplus \mathfrak{sl}(2)$ .
- (v)  $\mathfrak{g} = D(2, 1; \alpha)$ ,  $\alpha \neq 0, -1$ , so that  $\mathfrak{g}_0 = \mathfrak{sp}(U, \varphi) \oplus \mathfrak{sp}(U, \varphi) \oplus \mathfrak{sp}(U, \varphi)$ ,  $U$  being a two dimensional vector space and  $\varphi$  a nonzero skew symmetric bilinear form on  $U$ ,  $\mathfrak{g}_1 = U \otimes_F U \otimes_F U$ , with the natural multiplication in  $\mathfrak{g}_0$  and natural action of  $\mathfrak{g}_0$  on  $\mathfrak{g}_1$  in which the  $i^{\text{th}}$  copy of  $\mathfrak{sp}(U, \varphi)$  acts on the  $i^{\text{th}}$  factor of  $U$ , and with the multiplication of odd elements given by:

$$[u_1 \otimes u_2 \otimes u_3, v_1 \otimes v_2 \otimes v_3] = \varphi(u_2, v_2)\varphi(u_3, v_3)\varphi_{u_1, v_1} + \alpha\varphi(u_1, v_1)\varphi(u_3, v_3)\varphi_{u_2, v_2} - (1 + \alpha)\varphi(u_1, v_1)\varphi(u_2, v_2)\varphi_{u_3, v_3}$$

for any  $u_i, v_i \in U$ ,  $i = 1, 2, 3$ . Here  $\mathfrak{s}$  is the first copy of  $\mathfrak{sp}(U, \varphi)$ .

- (vi)  $\mathfrak{g} = G(3)$  and  $\mathfrak{s}$  is the (unique) ideal of  $\mathfrak{g}_0$  isomorphic to  $\mathfrak{sl}(2)$ .
- (vii)  $\mathfrak{g} = F(4)$  and  $\mathfrak{s}$  is the (unique) ideal of  $\mathfrak{g}_0$  isomorphic to  $\mathfrak{sl}(2)$ .
- (viii)  $\mathfrak{g} = \mathfrak{sp}(3, 2r)$ ,  $r \geq 1$ , and  $\mathfrak{s}$  is the copy of  $\mathfrak{o}(3)$  in  $\mathfrak{g}_0$ .

Moreover, different choose of the simple ideal  $\mathfrak{s}$  in (ii) or (iv) give isomorphic pairs and two pairs in (v) corresponding to the values  $\alpha_1$  and  $\alpha_2$  are isomorphic if and only if either  $\alpha_1 = \alpha_2$  or  $\alpha_1 + \alpha_2 = -1$ .

*Proof.* A careful look at the list of simple Lie superalgebras in [11, Theorem 5] shows that the semisimple part of  $\mathbf{W}(n)_0$  ( $n \geq 2$ ), of  $\mathbf{S}(n)$  ( $n \geq 3$ ) and of  $\tilde{\mathbf{S}}(n)$  ( $n \geq 3$ ), is isomorphic to  $\mathfrak{sl}(n)$  [11, Propositions 3.1.1 and 3.3.1], while  $\mathbf{W}(2)$  is isomorphic to  $\mathfrak{sl}(1, 2)$ . Also, the semisimple part of  $\mathbf{H}(n)$  ( $n \geq 4$ ) is isomorphic to  $\mathfrak{o}(n)$  [11, Proposition 3.3.6], while  $\mathbf{H}(4)$  is isomorphic to  $\mathfrak{psl}(2, 2)$ . Hence, it is enough to deal with the classical algebras. One checks easily that the simple classical Lie superalgebras with  $\mathfrak{g}_0$  containing a three dimensional simple ideal are those listed above. Since  $\mathfrak{osp}(4, 2)$  is isomorphic to  $D(2, 1; 1)$ , this has been excluded from (iii) and included in (v), and since  $\mathfrak{sl}(1, 2)$  is isomorphic to  $\mathfrak{osp}(2, 2)$ , this has been included in (iii).

The last assertion about cases (ii) and (iv) is clear. Also, the Lie algebras in (v) are the ones denoted by  $\Gamma(1, \alpha, -(1 + \alpha))$  in [26, p. 16–17]. Here we have three

copies of  $\mathfrak{sl}(2)$  in  $\mathfrak{g}_0$ , but there are isomorphisms preserving the three copies from  $\Gamma(\sigma_1, \sigma_2, \sigma_3)$  ( $\sigma_1 + \sigma_2 + \sigma_3 = 0$ ) onto  $\Gamma(\eta\sigma_1, \eta\sigma_2, \eta\sigma_3)$  for any  $0 \neq \eta \in F$ , and also natural isomorphisms permuting the three copies of  $\mathfrak{sl}(2)$  (and the corresponding  $\sigma_i$ 's). Therefore, the distinguished copy of  $\mathfrak{sl}(2)$  can always be taken to be the first one. Finally, if there is an isomorphism from  $\Gamma(1, \alpha, -1 - \alpha)$  onto  $\Gamma(1, \beta, -1 - \beta)$  that takes the first copy of  $\mathfrak{sl}(2)$  in  $\Gamma(1, \alpha, -1 - \alpha)$  to the first copy of  $\mathfrak{sl}(2)$  in  $\Gamma(1, \beta, -1 - \beta)$ , then it takes the second copy of  $\mathfrak{sl}(2)$  in  $\Gamma(1, \alpha, -1 - \alpha)$  to either the second or the third copy of  $\mathfrak{sl}(2)$  in  $\Gamma(1, \beta, -1 - \beta)$ , whence the last assertion of the Theorem.  $\square$

Now we are ready for our main Theorem, it asserts that the examples in Section 3 exhaust all the simple  $(-1, -1)$ -BFKTS's:

**THEOREM 4.3.** *Let  $V$  be a finite dimensional simple  $(-1, -1)$ -BFKTS over a field  $F$  of characteristic zero with associated symmetric bilinear form  $\langle | \rangle$ . Either:*

- (i) *The multiplication in  $V$  is given by*

$$xyz = \langle z | x \rangle y - \langle z | y \rangle x + \langle x | y \rangle z,$$

for any  $x, y, z \in V$  (orthogonal type), or

- (ii) *There is a quadratic étale algebra  $K$  over  $F$  such that  $V$  is a free  $K$ -module of rank at least 3, endowed with a hermitian form  $h : V \times V \rightarrow K$  such that*

$$\begin{cases} \langle x | y \rangle = \frac{1}{2}(h(x, y) + h(y, x)), \\ xyz = h(z, x)y - h(z, y)x + h(x, y)z, \end{cases}$$

for any  $x, y, z \in V$  (unitarian type).

- (iii) *There is a quaternion algebra  $Q$  over  $F$  such that  $V$  is a free left  $Q$ -module of rank  $\geq 2$ , endowed with a hermitian form  $h : V \times V \rightarrow Q$  such that*

$$\begin{cases} \langle x | y \rangle = \frac{1}{2}(h(x, y) + h(y, x)) \\ xyz = h(z, x)y - h(z, y)x + h(x, y)z \end{cases}$$

for any  $x, y, z \in V$  (symplectic type).

- (iv)  $\dim_F V = 4$  and there is a nonzero skew symmetric multilinear form  $\Phi : V \times V \times V \times V \rightarrow F$  such that for any  $x, y, z \in V$ :

$$xyz = [xyz] + \langle z | x \rangle y - \langle z | y \rangle x + \langle x | y \rangle z,$$

where  $[xyz]$  is defined by means of  $\Phi(x, y, z, t) = \langle [xyz] | t \rangle$  for any  $x, y, z, t \in V$ . In this case, there is a nonzero scalar  $\mu \in F$  such that (3.8) holds ( $D_\mu$ -type).

- (v)  $\dim_F V = 7$  and there is an eight dimensional Cayley-Dickson algebra  $C$  over  $F$  with trace  $t$  and a nonzero scalar  $\alpha \in F$  such that  $V = C_0 = \{x \in C : t(x) = 0\}$ , and for any  $x, y, z \in V$ :

$$\begin{cases} \langle x | y \rangle = -2\alpha t(xy) \\ xyz = \alpha(D_{x,y}(z) - 2t(xy)z) \end{cases}$$

where  $D_{x,y}$  is the inner derivation of  $C$  given by (3.11) ( $G$ -type).

(vi)  $\dim_F V = 8$  and  $(V, \langle | \rangle)$  is endowed with a 3-fold vector cross product  $X$  of type I such that

$$xyz = \frac{1}{3}X(x, y, z) + \langle z | x \rangle y - \langle z | y \rangle x + \langle x | y \rangle z$$

for any  $x, y, z \in V$ . (*F*-type.)

Moreover, two triple systems in different items cannot be isomorphic and:

(i') Two triple systems of orthogonal type are isomorphic if and only if the corresponding symmetric bilinear forms are isometric.

(ii') Two triple systems of unitarian type  $V_1$  and  $V_2$ , with associated quadratic étale algebras  $K_1$  and  $K_2$  and hermitian forms  $h_1$  and  $h_2$ , are isomorphic if and only if the hermitian pairs  $(V_1, h_1)$  and  $(V_2, h_2)$  are isomorphic; that is, there is an isomorphism of *F*-algebras  $\sigma : K_1 \rightarrow K_2$  and a linear bijection  $\varphi : V_1 \rightarrow V_2$  such that  $h_2(\varphi(x), \varphi(y)) = \sigma(h_1(x, y))$  for any  $x, y \in V_1$ .

(iii') Two triple systems of symplectic type  $V_1$  and  $V_2$ , with associated quaternion algebras  $Q_1$  and  $Q_2$  and hermitian forms  $h_1$  and  $h_2$ , are isomorphic if and only if the hermitian pairs  $(V_1, h_1)$  and  $(V_2, h_2)$  are isomorphic.

(iv') Two triple systems of  $D_\mu$ -type, with associated scalars  $\mu_1$  and  $\mu_2$ , are isomorphic if and only if the corresponding symmetric bilinear forms are isometric and  $\mu_1 = \mu_2$ .

(v') Two triple systems of *G*-type, with associated Cayley-Dickson algebras  $C_1$  and  $C_2$  and scalars  $\alpha_1$  and  $\alpha_2$ , are isomorphic if and only if so are  $C_1$  and  $C_2$  and  $\alpha_1 = \alpha_2\gamma^2$  for some  $0 \neq \gamma \in F$ .

(vi') Two triple systems of *F*-type  $V_1$  and  $V_2$ , with associated type I 3-fold vector cross products  $X_1$  and  $X_2$ , are isomorphic if and only if so are the triple systems  $(V_1, X_1)$  and  $(V_2, X_2)$ .

*Proof.* First, the new triple product defined on  $V$  by  $[xyz] = xyz - \langle z | x \rangle y + \langle z | y \rangle x - \langle x | y \rangle z$  for any  $x, y, z \in V$  is skew symmetric because of (2.5a). If this is identically zero,  $V$  is of orthogonal type. Otherwise, if the dimension of  $V$  is 4,  $V$  is of  $D_\mu$ -type.

Hence, in what follows, assume that  $\dim_F V \neq 4$ . Then, after extending scalars to an algebraic closure  $\bar{F}$  of  $F$ , if  $\bar{V} = \bar{F} \otimes_F V$ ,  $(\mathfrak{g}(\bar{V}), \mathfrak{s}(\bar{V}))$  is one of the pairs considered in cases (i), (iii), (iv), (vi) or (vii) in Theorem 4.2. Note that case (viii) does not appear since there  $\mathfrak{g}_{\bar{1}}$  is a direct sum of adjoint modules for  $\mathfrak{s}$  instead of a direct sum of two dimensional irreducible modules.

Because of Theorem 4.1 and the computations in Section 3, and since the classical Lie superalgebras other than  $D(2, 1; \alpha)$ 's are determined by its even part and the structure of  $\mathfrak{g}_{\bar{1}}$  as a  $\mathfrak{g}_{\bar{0}}$ -module [11, Proposition 2.1.4], it follows that case (i) in Theorem 4.2 corresponds to the unitarian type with  $\bar{K} = \bar{F} \times \bar{F}$  and  $\dim_F V \geq 6$ , case (iii) in 4.2 corresponds to the orthogonal type, case (iv) to the symplectic type and  $\dim_F V \geq 8$  and cases (vi) and (vii) to *G* and *F* types.

Therefore, it is enough to deal with the forms over  $F$  of the simple  $(-1, -1)$ -BFKTS's over  $\bar{F}$  considered in Section 3 with dimension  $\neq 4$ .

It is clear that if  $\bar{V}$  is of orthogonal type, so is  $V$ . If  $\bar{V}$  is of unitarian type with  $\dim_F V \geq 6$ , then since  $\bar{K} = \text{End}_{\mathfrak{s}}(\bar{V}) = \bar{F} \otimes_F \text{End}_{\mathfrak{o}}(V)$ ,  $K = \text{End}_{\mathfrak{o}}(V)$  is a quadratic étale algebra over  $F$ ; besides, there is a  $\bar{K}$ -hermitian form  $\bar{h} : \bar{V} \times \bar{V} \rightarrow \bar{K}$  such that  $xyz = \bar{h}(z, x)y - \bar{h}(z, y)x + \bar{h}(x, y)z$  for any  $x, y, z \in \bar{V}$ . But if  $\{1, i\}$  is an  $F$ -basis of  $K$  with  $i^2 = \alpha \in F$ , then  $\bar{h}(x, y) = \langle x | y \rangle - \alpha^{-1}\langle x | iy \rangle i$  for any  $x, y \in \bar{V}$ . Since both

$\langle x | y \rangle$  and  $\langle x | iy \rangle$  are in  $F$  in case  $x, y \in V$ , it follows that  $\bar{h}$  restricts to an hermitian form  $h : V \times V \rightarrow K$  and  $V$  is the corresponding simple  $(-1, -1)$ -BFKTS of unitarian type. A similar argument works in case  $\bar{V}$  is of symplectic type and  $\dim_F V \geq 8$ . In this case  $\bar{\mathfrak{d}} = \bar{\mathfrak{b}} \oplus \bar{\mathfrak{s}}$  with  $\bar{\mathfrak{s}} \cong \mathfrak{sl}(2, \bar{F}) \not\cong \bar{\mathfrak{b}}$ , so that  $\mathfrak{d} = \mathfrak{b} \oplus \mathfrak{s}$  for a suitable unique ideal  $\mathfrak{b}$  and  $\bar{Q} = \text{End}_{\bar{\mathfrak{b}}}(\bar{V}) = \bar{F} \otimes_F \text{End}_{\mathfrak{b}}(V)$ . Hence  $\text{End}_{\mathfrak{b}}(V) = Q$  is a quaternion algebra and  $V$  is a free  $Q$ -module. Now one takes a suitable  $F$ -basis  $\{1, i, j, k\}$  of  $Q$  and argues as above.

If  $\bar{V}$  is of G-type, then  $\mathfrak{d}$  is a form of  $G_2$ , so there is an eight-dimensional Cayley-Dickson algebra  $C$  over  $F$  such that  $\mathfrak{d} \cong \text{Der } C$  and  $V$  is, up to isomorphism, its seven dimensional irreducible module for  $\mathfrak{d}$ , that is  $C_0$ , the set of traceless elements in  $C$ . Since  $\text{Hom}_{\mathfrak{d}}(V \otimes_F V, \mathfrak{d})$  is one-dimensional, after identifying  $V$  with  $C_0$  there exists a nonzero  $\alpha \in F$  such that  $d_{x,y} = \alpha D_{x,y}$  for any  $x, y \in C_0 = V$ . From here, using (2.3c), it follows that  $V$  is of G-type.

Finally, if  $\bar{V}$  is of  $F$ -type, define  $X : V \times V \times V \rightarrow F$  by  $X(x, y, z) = 3(xyz - \langle z | x \rangle y + \langle z | y \rangle x - \langle x | y \rangle z)$ , for any  $x, y, z \in V$ . Then  $X$  is a 3-fold vector cross product of type I (because it is so after extending scalars) and hence  $V$  is of F-type.

Moreover, two simple  $(-1, -1)$ -BFKTS's of different types cannot be isomorphic because the corresponding Lie algebras of inner derivations are not. Also note that, because of (2.5a), any isomorphism among two  $(-1, -1)$ -BFKTS's is an isometry of the corresponding symmetric bilinear forms. Now (i') is clear and (ii') (respectively (iii')) follows from the fact that  $K_1$  and  $K_2$  (resp.  $Q_1$  and  $Q_2$ ) are determined as centralizers of the action of a suitable ideal of the Lie algebra of inner derivations.

Let us check (iv'), so let  $(V_i, (xyz)_i)$  be two simple  $(-1, -1)$ -BFKTS's of  $D_{\mu_i}$ -type ( $i = 1, 2$ ). If  $\varphi : V_1 \rightarrow V_2$  is an isomorphism, then it is an isometry and thus  $\varphi([xyz]_1) = [\varphi(x)\varphi(y)\varphi(z)]_2$  for any  $x, y, z \in V_1$ . Hence

$$\langle \varphi([x_1x_2x_3]_1) | \varphi([x_1x_2x_3]_1) \rangle_2 = \langle [x_1x_2x_3]_1 | [x_1x_2x_3]_1 \rangle_1 = \mu_1 \det(\langle x_i | x_j \rangle_1),$$

but also

$$\begin{aligned} \langle \varphi([x_1x_2x_3]_1) | \varphi([x_1x_2x_3]_1) \rangle_2 &= \langle [\varphi(x_1)\varphi(x_2)\varphi(x_3)]_2 | [\varphi(x_1)\varphi(x_2)\varphi(x_3)]_2 \rangle_2 \\ &= \mu_2 \det(\langle \varphi(x_i) | \varphi(x_j) \rangle_2) \\ &= \mu_2 \det(\langle x_i | x_j \rangle_1). \end{aligned}$$

Therefore,  $\mu_1 = \mu_2$ . Conversely, assume that  $\varphi : V_1 \rightarrow V_2$  is an isometry and that  $\mu_1 = \mu_2 = \mu$ . Consider  $\Phi_i : V_i^4 \rightarrow F$  ( $i = 1, 2$ ) given by  $\Phi_i(x_1, x_2, x_3, x_4) = \langle [x_1x_2x_3]_i | x_4 \rangle_i$ . Also, let  $\tilde{\Phi}_1 : V_1^4 \rightarrow F$  be defined by

$$\tilde{\Phi}_1(x_1, x_2, x_3, x_4) = \Phi_2(\varphi(x_1), \varphi(x_2), \varphi(x_3), \varphi(x_4))$$

for any  $x_1, x_2, x_3, x_4 \in F$ . Since  $\dim_F V_1 = 4$  and both  $\Phi_1$  and  $\tilde{\Phi}_1$  are skew symmetric, they are proportional, and hence there is a nonzero scalar  $\alpha \in F$  such that  $\tilde{\Phi}_1 = \alpha \Phi_1$ . For any  $x_1, x_2, x_3, y_1, y_2, y_3 \in F$ :

$$\begin{aligned} \Phi_2(\varphi(x_1), \varphi(x_2), \varphi(x_3), \varphi([y_1y_2y_3]_1)) &= \tilde{\Phi}_1(x_1, x_2, x_3, [y_1y_2y_3]_1) \\ &= \alpha \Phi_1(x_1, x_2, x_3, [y_1y_2y_3]_1) \\ &= \alpha \mu \det(\langle x_i | y_j \rangle_1) \\ &= \alpha \mu \det(\langle \varphi(x_i) | \varphi(y_j) \rangle_2) \\ &= \Phi_2(\varphi(x_1), \varphi(x_2)\varphi(x_3), \alpha[\varphi(y_1)\varphi(y_2)\varphi(y_3)]_2), \end{aligned}$$

where we have used (3.8) and the fact that  $\varphi$  is an isometry. Thus  $\varphi([y_1y_2y_3]_1) = \alpha[\varphi(y_1)\varphi(y_2)\varphi(y_3)]_2$  for any  $y_1, y_2, y_3 \in V_1$ . But now, again by (3.8), this shows that  $\mu \det((y_i | y_j)_1) = \alpha^2 \mu \det((y_i | y_j)_2)$  for any  $y_i$ 's, so that  $\alpha^2 = 1$ . If  $\alpha = 1$  we are done, otherwise  $\alpha = -1$ . In this latter case, choose any isometry  $\sigma$  of  $(|)_1$  with  $\det \sigma = -1$  and consider  $\hat{\varphi} = \varphi \sigma : V_1 \rightarrow V_2$ . Then if  $\hat{\Phi}_1(x_1, x_2, x_3, x_4) = \Phi_2(\hat{\varphi}(x_1), \hat{\varphi}(x_2), \hat{\varphi}(x_3), \hat{\varphi}(x_4))$  for any  $x_i \in V_1$  ( $i = 1, 2, 3, 4$ ), we have:

$$\begin{aligned} \hat{\Phi}_1(x_1, x_2, x_3, x_4) &= \Phi_2(\hat{\varphi}(x_1), \hat{\varphi}(x_2), \hat{\varphi}(x_3), \hat{\varphi}(x_4)) \\ &= \tilde{\Phi}_1(\sigma(x_1), \sigma(x_2), \sigma(x_3), \sigma(x_4)) = \alpha(\det \sigma)\Phi_1(x_1, x_2, x_3, x_4) = \Phi_1(x_1, x_2, x_3, x_4), \end{aligned}$$

because  $\alpha = -1 = \det \sigma$  and  $\Phi_1$  is multilinear and alternating. The same argument as above, with  $\tilde{\Phi}_1$  replaced by  $\hat{\Phi}_1$  shows that  $\hat{\varphi}$  is an isomorphism between the two triple systems.

With regard to (v'), if  $\varphi : V^1 \rightarrow V^2$  is an isomorphism of two triple systems of G-type with associated Cayley-Dickson algebras  $C^1$  and  $C^2$  and scalars  $\alpha_1$  and  $\alpha_2$ , then  $\varphi$  is an isometry of the associated symmetric bilinear forms and for any  $x, y, z \in V_1$

$$\varphi(d_{x,y}z) = d_{\varphi(x),\varphi(y)}\varphi(z). \tag{4.2}$$

Also,  $\phi : \mathfrak{d}^1 = d_{V^1, V^1} \rightarrow \mathfrak{d}^2: d \mapsto \varphi d \varphi^{-1}$  is an isomorphism of Lie algebras and  $\varphi$  becomes an isomorphism of  $\mathfrak{d}^1$ -modules, where  $V^2$  is a  $\mathfrak{d}^1$ -module through  $\phi$ . Since  $\text{Hom}_{\mathfrak{d}^1}(\Lambda^2(V^1), V^1)$  is spanned by  $x \wedge y \mapsto [x, y] = xy - yx$  (multiplication in  $C^1$ ), there is a nonzero scalar  $\mu \in F$  such that

$$\varphi([x, y]) = \mu[\varphi(x), \varphi(y)] \tag{4.3}$$

for any  $x, y \in V^1 = C_0^1 = \{z \in C^1 : t(z) = 0\}$ . In particular,  $\mu\varphi : (C_0^1, [, ]) \rightarrow (C_0^2, [, ]) \rightarrow (C_0^2, [, ]) \rightarrow (C_0^2, [, ]) \rightarrow (C_0^2, [, ])$  is an isomorphism of Malcev algebras and hence  $C^1$  and  $C^2$  are isomorphic (see, for instance, [3, (3.1)]). But the associator  $(x, y, z) = (xy)z - x(yz)$  in  $C^1$  is skew symmetric on its arguments, so for any  $x, y, z \in C^1$ ,  $(x, y, z) = -(x, z, y) = (z, x, y) = (y, z, x)$ , so that  $L_{xy} - L_xL_y = [L_x, R_y] = R_yR_x - R_{xy} = [R_x, L_y]$ , hence  $ad_{xy} - L_xL_y + R_yR_x = 2[L_x, R_y]$  for any  $x, y \in C^1$ , where  $ad_{x,y} = [x, y] = (L_x - R_x)(y)$ . Permuting  $x$  and  $y$  and subtracting we get  $ad_{[x,y]} = [L_x, L_y] + [R_x, R_y] + 4[L_x, R_y] = D_{x,y} + 3[L_x, R_y]$ . On the other hand,

$$\begin{aligned} [ad_x, ad_y] &= [L_x - R_x, L_y - R_y] = [L_x, L_y] + [R_x, R_y] - 2[L_x, R_y] \\ &= D_{x,y} - 3[L_x, R_y], \end{aligned}$$

and from here we conclude that  $2D_{x,y} = ad_{[x,y]} + [ad_x, ad_y]$  for any  $x, y \in C^1$ . Since  $d_{x,y} = \alpha_1 D_{x,y}$  and  $d_{\varphi(x),\varphi(y)} = \alpha_2 D_{\varphi(x),\varphi(y)}$  for any  $x, y \in V^1$ , equation (4.3) gives:

$$\begin{aligned} \varphi d_{x,y} &= \frac{\alpha_1}{2}\varphi(ad_{[x,y]} + [ad_x, ad_y]) = \frac{\alpha_1}{2}\mu^2(ad_{[\varphi(x),\varphi(y)]} + [ad_{\varphi(x)}, ad_{\varphi(y)}])\varphi \\ &= \frac{\alpha_1}{2}\mu^2 D_{\varphi(x),\varphi(y)}\varphi, \end{aligned}$$

while  $d_{\varphi(x),\varphi(y)} = \frac{\alpha_2}{2}D_{\varphi(x),\varphi(y)}$  for any  $x, y \in V^1$ , so that equation (4.2) gives  $\alpha_1\mu^2 = \alpha_2$ , as desired. Conversely, if  $\psi : C^1 \rightarrow C^2$  is an isomorphism and  $\alpha_2 = \alpha_1\mu^2$ , then the map  $\varphi : V^1 = C_0^1 \rightarrow V^2 = C_0^2$ , given by  $\varphi(x) = \mu^{-1}\psi(x)$  for any  $x \in V^1$ , is an isomorphism of triple systems.

We are left with the isomorphism problem for the  $(-1, -1)$ -BFKTS's of F-type. For these we need some preliminaries, which have their own independent interest:

LEMMA 4.4. *Let  $X$  be a 3-fold vector cross product of type I on an eight dimensional vector space  $V$  over a field  $F$  of characteristic  $\neq 2$ , and let  $\langle | \rangle$  be the associated nondegenerate symmetric bilinear form (so that (3.11) is satisfied). Then  $\langle | \rangle$  is determined by  $X$ .*

*Proof.* Because of (3.12), for any  $a, b, c, d \in V$ :

$$\begin{aligned}
 -(d | X(a, b, X(a, b, c))) &= \langle X(a, b, c) | X(a, b, d) \rangle = \begin{vmatrix} \langle a | a \rangle & \langle a | b \rangle & \langle a | d \rangle \\ \langle b | a \rangle & \langle b | b \rangle & \langle b | d \rangle \\ \langle c | a \rangle & \langle c | b \rangle & \langle c | d \rangle \end{vmatrix} \\
 &= \langle (a \wedge b | a \wedge b)c - (a \wedge b | a \wedge c)b + (a \wedge b | b \wedge c)a | d \rangle
 \end{aligned}$$

where  $\langle a \wedge b | u \wedge v \rangle = \begin{vmatrix} \langle a | u \rangle & \langle a | v \rangle \\ \langle b | u \rangle & \langle b | v \rangle \end{vmatrix}$  for any  $a, b, u, v \in V$ . By nondegeneracy of  $\langle | \rangle$ , this gives:

$$X(a, b, X(a, b, c)) = \langle a \wedge b | c \wedge b \rangle a + \langle a \wedge b | a \wedge c \rangle b - \langle a \wedge b | a \wedge b \rangle c. \tag{4.4}$$

Hence, for any  $a, b, c \in V$ , if  $d = X(a, b, c)$ , then  $X(a, b, d) \in Fa + Fb + Fc$  and, similarly (since  $d = X(b, c, a) = X(c, a, b)$ ),  $X(b, c, d), X(a, c, d) \in Fa + Fb + Fc$ , so that  $W = Fa + Fb + Fc + Fd$  is closed under  $X$ . Let us prove now that for any  $0 \neq v \in V$ :

$$X(v, V, V) = \{x \in V : \langle v | x \rangle = 0\}. \tag{4.5}$$

Because of (3.12),  $X(v, V, V) \subseteq \{x \in V : \langle x | v \rangle = 0\}$ . Now, take  $a = v$  and let  $b \in V$  linearly independent with  $a$  and such that  $\langle | \rangle$  is nondegenerate on  $W_b = Fa + Fb$ . By (4.4)  $c \in X(a, b, V) \subseteq X(v, V, V)$  for any  $c \in W_b^\perp = \{x \in V : \langle x | a \rangle = 0 = \langle x | b \rangle\}$ . Take any two such  $b$ 's with different  $W_b$ 's, then the sum of the  $W_b^\perp$ 's is  $\{x \in V : \langle x | v \rangle = 0\}$ , so (4.5) follows.

Thus, assume that  $X$  is also a 3-fold vector cross product of type I relative to another nondegenerate symmetric bilinear form  $(|)$  on  $V$ . Then for any  $0 \neq u, v \in V$ , if  $\langle u | v \rangle = 0$ , then  $u \in X(v, V, V)$  by (4.5), so by (3.12), also  $(u | v) = 0$ . The only possibility then is that  $(|) = \alpha \langle | \rangle$  for some nonzero scalar  $\alpha \in F$ . But then (3.12) implies that  $\alpha^3 = \alpha$ , so  $\alpha = \pm 1$ , and (3.13) that  $\alpha = 1$ . □

Note that if  $X$  is a 3-fold vector cross product of type I on an eight dimensional vector space  $V$  relative to the nondegenerate symmetric bilinear form  $\langle | \rangle$ , then  $X$  is a 3-fold vector cross product of type II relative to  $-\langle | \rangle$ . Also note that  $\langle | \rangle$  does not determine  $X$ , since not every orthogonal transformation relative to  $\langle | \rangle$  is an automorphism of  $X$  ([4]).

COROLLARY 4.5. *Let  $X_i$  be a 3-fold vector cross product on an eight dimensional vector space  $V_i$  over a field  $F$  of characteristic  $\neq 2$  with associated nondegenerate symmetric bilinear form  $\langle | \rangle_i$  ( $i = 1, 2$ ). Then if  $\varphi : (V_1, X_1) \rightarrow (V_2, X_2)$  is an isomorphism, then it is also an isometry  $\varphi : (V_1, \langle | \rangle_1) \rightarrow (V_2, \langle | \rangle_2)$ .*

Now, the proof of item (vi') in Theorem 4.3 follows immediately from the Corollary above and this finishes its proof.

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