FLOW OF A VALLEY GLACIER WITH A SOLID FRICTION LAW

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ABSTRACT. Friction on the bed is assumed to obey Coulomb's law of solid friction in the presence of interstitial pressure (Lliboutry, 1968). According to this, the friction is a maximum at certain places in the bottom of the valley. Assuming Glen's non-linear creep law, the steady-state flow of ice along a regular cylindrical channel of parabolic section has been calculated. The results reproduce to high accuracy the distribution of velocity measured on the Athabasca Glacier (Raymond, 1971).

Résumé. Ecoulement d'un glacier de vallée avec une loi de frottement solide. Il est supposé que le frottement à la surface du lit obéit à la loi de frottement solide de Coulomb en présence d'une pression interstitielle (Lliboutry, 1968). De ce fait, le frottement est maximal à une certaine distance de part et d'autre du fond de la vallée. On a calculé, en admettant la loi de fluage non linéaire de Glen, l'ecoulement permanent parallèle de la glace le long d'un canal régulier cylindrique de section droite parabolique. On retrouve avec une excellente précision les valeurs et la répartition des vitesses mesurées sur le glacier de l'Athabasca (Raymond, 1971).

Zusammenfassung. Bewegung eines Talgletschers unter der Annahme eines Reibungsgesetzes für feste Körper. Von der Reibung am Gletscherbett wird angenommen, dass sie beim Vorhandensein von Druck in den Hohlräumen dem Reibungsgesetz von Coulomb für feste Körper folgt (Lliboutry, 1968). Demzufolge nimmt die Reibung an bestimmten Stellen am Grunde des Troges einen Höchstwert an. Unter der Voraussetzung von Glen's nicht-linearem Fliessgesetz wurde die stetige Fliessbewegung des Eises entlang eines regelmässigen, zylindrischen Kanals mit parabolischem Querschnitt berechnet. Die Ergebnisse geben mit hoher Genauigkeit die Geschwindigkeitsverteilung wieder, die am Athabasca-Glacier gemessen wurden (Raymond, 1971).

I. Introduction

Nye (1965) has calculated a solution for the steady-state flow along a channel of uniform section and slope of a glacier obeying the non-linear flow law of Glen. He takes as boundary condition on the rock bed a zero slip velocity. It could also be non-zero, uniform, and independent of the friction, but such a hypothesis seems completely unrealistic.

Recent measurements of ice deformation on the surface and at depth made by Raymond (1971) on the Athabasca Glacier show a very different distribution of velocities from those suggested by Nye. Instead of a constant slipping velocity, Raymond has found a velocity which varies along the section. This velocity, which is a few metres per year at the edges, reaches 42 m a⁻¹ at the centre or about 80% of the surface velocity. This characteristic leads us to adopt a theoretical model which allows large variations of slip velocity. It seems more realistic to adopt as boundary condition between ice and rock a friction f proportional to the normal pressure of the ice, reduced by the mean pressure of liquid water at the interface (Lliboutry, 1968, 1969). Measurement of the level of water in hole 2A has in effect shown that there exists a very large water pressure in cavities at the bed of the glacier. For an extremely wide glacier (plane problem) the difference between the pressure of the ice and the pressure of the water in cavities has the mean value

$$\mathcal{N} = \kappa(\rho_{i}h - \rho_{w}h_{w}) \tag{I}$$

where ρ_i and ρ_w are the densities of ice and water respectively, h is the thickness of ice, h_w the piezometric height corresponding to subglacial water channels, and κ is a factor depending on the way the hydraulic network branches, and varies from $\frac{1}{2}$ to $\frac{2}{3}$.

But, as Professor Lliboutry has commented, for a valley glacier we must take into account the variation in pressure due to the difference in height H between the point considered and the place where the subglacial water cavities come together with the main subglacial stream. The expression for $\mathcal N$ becomes

$$\mathcal{N} = \kappa [(\rho_{\mathbf{i}} h - \rho_{\mathbf{w}} h_{\mathbf{w}}) + (\rho_{\mathbf{w}} - \rho_{\mathbf{i}}) H]. \tag{2}$$

2. Co-ordinates and notation

We adopt a co-ordinate system as shown in Figure 1. The free surface of the ice is the plane y = 0 which makes an angle α with the horizontal, t is the angle formed by the normal to the bed with the Oy axis, w is the ratio of the half-width to the depth a of the perpendicular section, and y_w is the distance from the water table to the surface.

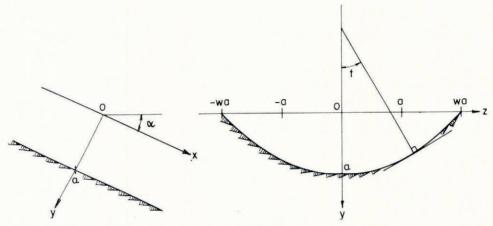


Fig. 1. Schematic diagram of valley glacier. Left: longitudinal profile along centre line. Right: transverse parabolic crosssection of width ratio w= 2.

We suppose that the movement is in a steady state and is parallel to the Ox axis with velocity u. We suppose that the stresses follow the equations:

$$\sigma_x = \sigma_y = \sigma_z = -\rho_i g \cos \alpha y,
\tau_{yz} = 0,$$
(3)

with, in the plane y = 0,

$$\sigma_y = \tau_{xy} = 0.$$

In this case the equilibrium equations reduce to

$$\frac{\partial \tau_{xy}}{\partial y} + \frac{\partial \tau_{xz}}{\partial z} = -\rho_{ig} \sin \alpha, \tag{4}$$

and Glen's flow law gives

$$\frac{\partial u}{\partial y} = A \tau^{n-1} \tau_{xy}, \qquad \frac{\partial u}{\partial z} = A \tau^{n-1} \tau_{xz},$$
 (5)

where $\tau = (\tau_{xy^2} + \tau_{xz^2})^{\frac{1}{2}}$, A = 0.17 and n = 3.

We adopt the reduced variables

$$Y = y/a, \qquad \mathcal{Z} = z/a, \qquad Y_{\rm w} = y_{\rm w}/a,$$

$$T_Y = \tau_{xy}/\rho g \sin \alpha, \qquad T_Z = \tau_{xz}/\rho g \sin \alpha,$$

$$T = \tau/\rho g \sin \alpha, \qquad U = u/a A (\rho g a \sin \alpha)^n,$$
(6)

and the stress function ψ already introduced by Nye so that

$$T_{Y} = \frac{\partial \psi}{\partial Z} - \frac{\Upsilon}{2}, \qquad T_{Z} = -\frac{\partial \psi}{\partial \Upsilon} - \frac{Z}{2}.$$
 (7)

3. Boundary conditions at the bottom of the glacier

The friction condition at the bed is written

$$T_Y \cos t + T_Z \sin t = C_0 N / \rho g a \sin \alpha$$
 (8)

where C_0 is a constant if w and Υ_w are given. For $0 \leqslant \Upsilon \leqslant \Upsilon_w$ the second term in Equation (8) becomes CY with $C = C_0 \kappa \cot \alpha$, and for $Y_{\mathbf{w}} \leqslant Y \leqslant 1$

$$C\left[\frac{\rho_{\mathbf{w}}\Upsilon_{\mathbf{w}}}{\rho_{\mathbf{i}}} - \frac{\rho_{\mathbf{w}} - \rho_{\mathbf{i}}}{\rho_{\mathbf{i}}}\Upsilon\right]. \tag{9}$$

Along the edge of the perpendicular section where Υ and Z are related by the equation $Y = I - (Z^2/w^2)$, Equation (8) is a first-order differential equation for a function of a single variable. Let us put $\xi = \tan t$, and Equation (8) is written for $0 \leqslant \Upsilon \leqslant \Upsilon_w$

$$\psi_{\xi'} = -\frac{Cw^2}{4} (1 + \xi^2)^{\frac{1}{8}} \left(1 - \frac{w^2 \xi^2}{4} \right) + \frac{w^2}{8} \left(1 + \frac{w^2 \xi^2}{4} \right),$$
and for $Y_{\mathbf{w}} \leqslant Y \leqslant \mathbf{I}$

$$\psi_{\xi'} = \frac{Cw^2}{4} \left[\delta(1 + \xi^2)^{\frac{1}{8}} \left(1 - \frac{w^2 \xi^2}{4} \right) - (1 + \delta)(1 + \xi^2)^{\frac{1}{8}} \left(1 - \frac{w^2 \xi_{\mathbf{w}}^2}{4} \right) + \frac{w^2}{8} \left(1 + \frac{w^2 \xi^2}{4} \right) \right],$$
where $\delta = (a_{\mathbf{w}} - a_{\mathbf{v}})/a_{\mathbf{v}} = 0.12$ and $\xi_{\mathbf{w}}$ is the value of ξ for $Y_{\mathbf{w}}$.

where $\delta = (\rho_{\rm w} - \rho_{\rm i})/\rho_{\rm i} = 0.12$ and $\xi_{\rm w}$ is the value of ξ for $\Upsilon_{\rm w}$.

Along the Oz axis $T_Y = 0$ therefore $d\psi/d\mathcal{Z} = 0$ and ψ is constant. Similarly on Oy where $T_z = 0$, $d\psi/dy = 0$ and ψ is constant. One chooses this constant to be zero, and therefore ψ is known at two points of the bed: $\Upsilon = 0$, $Z = \pm w$ and $\Upsilon = 1$, Z = 0. These two expressions for ψ must become the same at $\Upsilon = \Upsilon_w$ which determines the value of C.

It follows that for $\Upsilon \leqslant \Upsilon_{\mathbf{w}}$:

$$\begin{split} \psi &= \frac{Cw^2}{64} \left[\frac{{\rm i} 6 - w^2}{2} \left(\frac{2\lambda_0}{w} - \lambda \xi \right) - w^2 \left(\frac{8\lambda_0}{w^3} - \lambda \xi^3 \right) + \frac{{\rm i} 6 + w^2}{2} \left(\lambda_0{}' - \lambda{}' \right) \right] + \\ &\qquad \qquad + \frac{w^2}{8} \left(\xi + \frac{w^2 \xi^3}{{\rm i} 2} \right) - \frac{w}{3} \,, \end{split} \tag{11}$$

and for $\Upsilon_{\mathbf{w}} \leqslant \Upsilon \leqslant \mathbf{1}$:

$$\begin{split} \psi &= \frac{Cw^2}{8} \left[\delta \left\{ \left(\frac{16 - w^2}{16} \, \xi^2 - \frac{w^2}{8} \, \xi^3 \right) \lambda + \frac{16 + w^2}{16} \, \lambda' \right\} - \mathcal{Y}_{\mathbf{w}} (\mathbf{1} + \delta) (\lambda \xi + \lambda') \right] + \\ &\qquad \qquad + \frac{w^2}{8} \left(\xi + \frac{w^2 \xi^3}{12} \right), \end{split} \tag{12}$$

with

$$C = \frac{8}{3w} / \left[(1+\delta) \left\{ \left(\frac{w^2 \xi_w^3}{8} - \frac{16 - w^2}{16} \xi_w \right) \lambda_w - \frac{16 + w^2}{16} \lambda_w' + \mathcal{Y}_w (\lambda_w \xi_w + \lambda_w') \right\} + \frac{8 - w^2}{8w} \lambda_0 + \frac{16 + w^2}{16} \lambda_0' \right]$$
(13)

where

$$\lambda = (\mathbf{1} + \xi^2)^{\frac{1}{2}}, \qquad \lambda' = \ln (\lambda + \xi),$$

 $\xi_{\rm w}, \, \lambda_{\rm w}, \, \lambda_{\rm w}'$ are the values of $\xi, \, \lambda, \, \lambda'$ for $\Upsilon = \Upsilon_{\rm w}, \, {\rm and} \, \lambda_0, \, \lambda_0'$ the values of $\lambda, \, \lambda'$ for $\Upsilon = 0$.

4. Numerical solutions

Function ψ , known at the edges of the section, must satisfy within the section the equation in partial derivatives:

$$\left[\left(\frac{\partial \psi}{\partial \mathcal{Z}} - \frac{\Upsilon}{2} \right)^{2} + 3 \left(\frac{\partial \psi}{\partial \Upsilon} + \frac{\mathcal{Z}}{2} \right)^{2} \right] \frac{\partial^{2} \psi}{\partial \Upsilon^{2}} + \left[3 \left(\frac{\partial \psi}{\partial \mathcal{Z}} - \frac{\Upsilon}{2} \right)^{2} + \left(\frac{\partial \psi}{\partial \Upsilon} + \frac{\mathcal{Z}}{2} \right)^{2} \right] \frac{\partial^{2} \psi}{\partial \mathcal{Z}^{2}} + 4 \left(\frac{\partial \psi}{\partial \mathcal{Z}} - \frac{\Upsilon}{2} \right) \left(\frac{\partial \psi}{\partial \Upsilon} + \frac{\mathcal{Z}}{2} \right) \frac{\partial^{2} \psi}{\partial \Upsilon \partial \mathcal{Z}} = 0 \tag{14}$$

Equation (14) is of the elliptic type throughout the domain. To resolve this Dirichlet problem, one uses an iterative relaxation method described in detail by Nye (1965). To do this, Equation (14) is written in finite difference form for the network shown in Figure 2. In this case the value of ψ at point 2 is a linear function of the values of ψ at the eight neighbouring points.

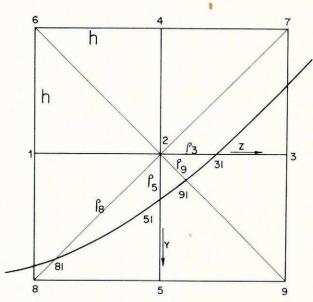


Fig. 2. Square mesh used to write Equation (14) as a finite-difference approximation at the point 2. Near the bed (heavy line), the points 3, 5, 9 and 8 can be exterior to the cross-section. Instead of these points we take the points 31, 51, 91 and 81. The distance of these points from point 2 are the ρ₁.

A difference in treatment affects the way of expressing Equation (14) for points neighbouring the boundary when some of the eight neighbouring points are outside the domain. These external points (points 8, 5, 9 and 3 in Figure 2) are replaced in the example shown by the points 81, 51, 91 and 31 respectively. The distances between the point 2 and the points i_1 are called ρ_1 . The first derivatives at the point 2 are therefore given to the second order approximately by:

$$\psi_{y'} = \frac{I}{2} \left(\frac{\psi_{51} - \psi_2}{\rho_5} + \frac{\psi_2 - \psi_4}{h} \right),$$

$$\psi_{z'} = \frac{I}{2} \left(\frac{\psi_{31} - \psi_2}{\rho_3} + \frac{\psi_2 - \psi_1}{h} \right).$$
(15)

These expressions involving ψ_2 we have replaced by

$$\psi_{y'} = \frac{\psi_{51} - \psi_4}{\rho_5 + h},
\psi_{z'} = \frac{\psi_{31} - \psi_1}{\rho_3 + h}.$$
(16)

The method has been programmed for an IBM 360-70 computer. To cover the domain, a technique of alternate iterations has been used taking the points line by line and beginning from an axis on the perpendicular section, then column by column beginning this time by the points at the margin. This treatment related to a relaxation technique gives a rapid convergence. The meshes of the grid are squares of variable side, the first solution obtained for squares of side 0.2, serves as an initial solution for the grid of side 0.1, etc. The calculation has been terminated for squares of side 0.05, the solution obtained being very close to its predecessor. The calculating programme was tested for two obvious solutions of Equation (14) which are

The tests showed that for these solutions the finite-difference form of the differential equation and the manner of treating points near to the boundary of the perpendicular section are correct.

5. Solutions

The calculation has been made with values obtained on the Athabasca Glacier: W = 2, a = 310 m, $\alpha = 3^{\circ} 30'$.

Using the $\Upsilon_{\rm w}$ the value of the water level for water in bore-hole 2A: $\Upsilon_{\rm w}=0.13$, we obtain a velocity at the centre of 104 m a⁻¹ at the surface and 96 m a⁻¹ at the bottom, although the shear stress τ_{xy} at the bottom is only $-0.37~\rho ga\sin\alpha$. The value 0.13 for the parameter $\Upsilon_{\rm w}$ therefore leads to results rather far from experimental results. However, taking $\Upsilon_{\rm w}=0.13$ one produces at the subglacial stream and at cavities which communicate easily with each other a very high pressure equal to 27 bars. But, according to Lliboutry's model, this pressure

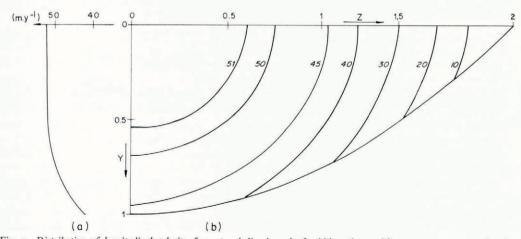


Fig. 3. Distribution of longitudinal velocity for a parabolic channel of width ratio 2 with $a=310\,\text{m}$. $\alpha=3^\circ$ 30' and $\Upsilon_{\rm W}=0.33,\,n=3,\,\tilde{A}=0.17,\,(a)$ down the Y-axis, (b) in cross section. Units are m a^{-1} .

varies from one point to another on the bed according to the nature of the interconnection of the cavities with the main subglacial stream. This has been verified in the course of borings made on the Glacier de Saint-Sorlin, France. For certain bore holes the level of water stabilized at different heights although others in the same neighbourhood emptied suddenly when the boring tool reached the rock bed (verbal communication from F. Gillet). It is for this reason that measurement of the piezometric height at a single point can only give a rough idea of the pressure which is occurring at the base of the glacier.

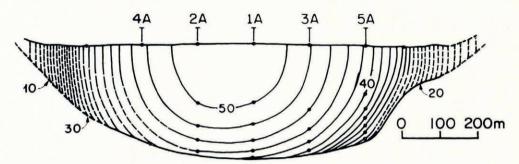


Fig. 4. Distribution of longitudinal velocity in Athabasca Glacier cross-section (section A, Raymond, 1970). Units are m a-1

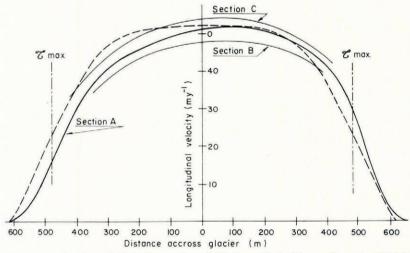


Fig. 5. Lateral variations of surface velocity in three sections of Athabasca Glacier (Raymond, 1970). Field data (solid lines), and computed values, with a=310 m, $Y_w=0.33$, n=3, A=0.17 (dashed line).

Several calculations, made with various values for the parameter $\Upsilon_{\rm w}$, show that the velocity decreases rapidly when $\Upsilon_{\rm w}$ increases (Fig. 7). For a mean-water height of $\frac{2}{3}a$ or a pressure of 20.8 bars at the base, the distribution of velocities (Fig. 3) is very close to that obtained by Raymond, for the majority of the section (Figs. 4, 5), the only difference coming from velocities close to the edge. But for this region a comparison is hardly possible because no measurements were made at depth. This value of $\Upsilon_{\rm w}$ has therefore been adopted.

The values of the velocities used at the centre of the surface, of the mean velocities over the surface $\langle u_s \rangle$ and the mean values over the section $\langle u \rangle$ as well as the total outflow are shown in Table I for the values measured on the Athabasca Glacier, those given by Nye's theory and by our theory.

Table I. Measured and calculated velocities and outflows

	u	$\langle u_{\rm s} \rangle$	$\langle u \rangle$	Outflow
	$m a^{-1}$	$m a^{-1}$	$m a^{-1}$	$hm^3 a^{-1}$
Athabasca Glacier	52	36	41	10.9
Nye's theory	17	11.6	11.4	2.9
Our theory $\Upsilon_{ m w}={ m o.33}$	52	37.5	41.5	II

6. Stress distribution

The distribution of stresses shown in Figure 6 gives a variation of τ_{xy} along the axis of the glacier practically linear with depth and at the bottom:

$$\tau_{xy} = -0.51 \rho ga \sin \alpha$$
.

Along the edges at $\Upsilon = 0$, $Z = \pm w$, Equation (10) gives $\partial \psi / \partial \Upsilon = -\frac{1}{2}$; this value does not depend strongly on $\Upsilon_{\mathbf{w}}$ when w = 2.

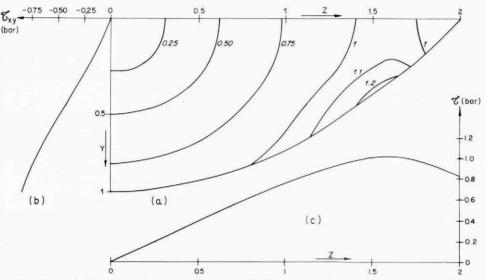


Fig. 6. Distribution of shear stress τ for a parabolic channel of width ratio 2 with a=310 m, $\alpha=3^{\circ}$ 30', $\Upsilon_{\rm w}=0.33$, n=3 and A=0.17, (a) in a cross section, (b) down the Y-axis, (c) on the Z-axis.

We therefore have:

$$T_{\mathbf{Z}} = -\frac{\partial \psi}{\partial \Upsilon} - \frac{\mathcal{Z}}{2} = -\frac{\mathbf{I}}{2}.$$

With the exception of the case where $\Upsilon_{\rm w}=1$, that is to say the case where the subglacial stream is at atmospheric pressure, $T_{\rm Z}$ has a maximum at the surface and not on the edge but at some distance from the margin of the glacier (Fig. 7). But it must be noted that if this corresponds with observations, this does not constitute a proof of the validity of our model, for Nye has obtained the same result with different boundary conditions.

With the law adopted, the maximum stress on the bed is no longer obtained along the axis of the channel as in Nye's model, but at the edges for $\Upsilon = \Upsilon_w$. This last characteristic can explain, as Professor Lliboutry has pointed out, the important lateral erosion and the U-shape encountered in the majority of valley glaciers.

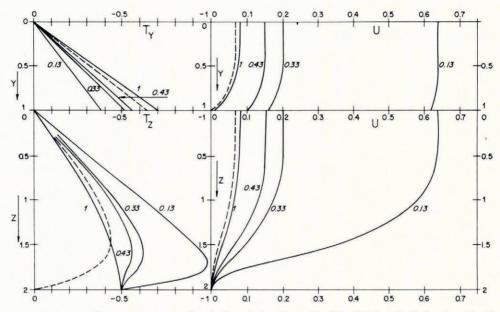


Fig. 7. Parabolic channel, w=2, n=3; values in dimensionless form. Top left: Velocity distribution down the Y-axis. Top right: Velocity in a transverse line (Z-axis) on the surface. Bottom left: shear stress Y_Y on the Y-axis. Bottom right: shear stress Y_Z on the Z-axis. Numbers on curves are values of Y_W . The dashed line represents the values computed by Nye for the same Y_X and Y_Y are the same Y_Y are the same Y_Y and Y_Y are the same Y_Y and Y_Y are the same Y_Y are the same Y_Y and Y_Y are the same Y_Y are the same Y_Y and Y_Y are the same Y_Y and Y_Y are the same Y_Y are the same Y_Y and Y_Y are the same Y_Y are the same Y_Y and Y_Y are the same Y_Y are the same Y_Y and Y_Y are the same Y_Y are the same Y_Y and Y_Y are the same Y_Y are the same Y_Y and Y_Y are the same Y_Y are the same Y_Y and Y_Y are the same Y_Y and Y_Y are the same Y_Y are the same Y_Y and Y_Y are the same Y_Y are the same Y_Y are the same Y_Y and Y_Y are the same Y_Y and Y_Y are the same Y_Y are the for the same channel.

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