

High Accuracy Numerical Methods for Ordinary Differential Equations with Discontinuous Right-hand Side

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Ordinary Differential Equations (ODEs) with discontinuous right-hand side, where the discontinuities occur in the *state* variables arise in a number of applications.

The appropriate formulation of such a problem (Filippov [4]) is to replace the ODE " $x' = f(x)$ " by a *differential inclusion* $x' \in F(x)$ where F is a set-valued function with nonempty compact convex values and is upper semi-continuous. Solutions exist, although they are not necessarily unique.

Numerical methods to compute solutions of differential inclusions have already been developed and convergence results proven by Taubert [6, 7], Elliott [3] and Niepage and Wendt [5]. However, these methods are no better than 1st order accurate, and 1st order accuracy holds only with additional assumptions. Further, unless solutions are unique, these methods only guarantee that a *sub-sequence* of the numerical solutions converge.

It is assumed that the structure of the discontinuous ODE is as follows: there is a collection of disjoint open sets R_i with dense union in \mathbb{R}^n , such that $x \in R_i$ implies that $f(x) = f_i(x)$ with f_i smooth, and the R_i can be described by functions: $R_i = \{x \mid h_i(x) < h_j(x), j \neq i\}$. The *active set* at x is $I(x) = \{i \mid x \in \overline{R_i}\}$. The Filippov formulation becomes $x' \in \text{co}\{f_i(x) \mid i \in I(x)\}$. We suppose that $I(x(t))$ is a piecewise constant function. Where $I(x(t))$ is constant, we can select elements of the above differential inclusion that keep the active set constant. At a *switching point* the set of possible new values for $I(x(t))$ are determined by means of a Linear Complementarity Problem. Given a new active set from this set, we can continue by solving a new smooth ODE to maintain the new active set, until another switching point occurs.

A complete algorithm using this approach has been developed and convergence results proven. In particular, if a particular solution has only finitely many switching points and some non-degeneracy conditions are satisfied, then by suitable choices of new active sets, a sequence of numerical solutions can be generated that converge to the given solution with the same order of accuracy the smooth ODE solver used.

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This algorithm has been implemented and numerical results obtained.

A “decomposition” extension to the main algorithm is described and convergence results are given for this extension. This extension has been implemented and numerical results obtained for a friction problem with multiple friction surfaces.

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