


RESEARCH ARTICLE

# Integrable fractional Burgers hierarchy

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## Abstract

Linear and integrable non-linear fractional evolution equations are discussed. Earlier results for the integrable fractional Korteweg–deVries (KdV) equation and the KdV hierarchy are reviewed. Using these as a guide, the fractional integrable Burgers equation and hierarchy and its solutions are analysed. Some explicit solutions are provided.

## 1. Introduction and background

The question of whether fractional derivatives can occur goes back to the origin of calculus and letters between l'Hôpital and Leibniz. While fractional calculus and associated equations have a long history only relatively recently have fractional partial differential equations been used effectively to describe physical systems. For example, it has been found to be important in anomalous diffusion [20, 28, 30, 33], amorphous materials [10, 22, 26], porous media [8, 9, 19], climate science [12], fractional quantum mechanics and optics [14, 16, 17, 23], amongst others. Fractional equations using the Riesz fractional derivatives, Riesz transforms [24] or fractional Laplacian [15] are effective tools when describing behaviour in complex systems because the Riesz fractional derivative is closely related to non-Gaussian statistics [18]. In porous media, the fractional Laplacian plays a central role and in fractional quantum mechanics the fractional Schrödinger equation is the key equation. Fractional media is 'rough' or multi-scale media that is neither regular nor random. Equations in multi-scale or fractional media can have fractional derivatives in any governing term [32].

With integer derivatives, one-dimensional (1D) non-linear Schrödinger (NLS) equation [1, 3] and the Korteweg–de Vries (KdV) equation [11] are well-known integrable equations possessing soliton solutions and an infinite set of conservation laws (cf. [2, 3]). Integrable equations arise in non-linear dynamics and waves; they provide exactly solvable equations and are also an important element of Kolmogorov–Arnold–Moser theory which underlies our understanding of chaos. While in the space of possible non-linear evolution equations, integrable cases are extremely rare, nevertheless they occur frequently in application.

Recently, Ablowitz et al. found a new class of integrable fractional integrable systems; these include the integrable fractional KdV and NLS equations [5]; integrable fractional modified KdV and sine-Gordon equations [6] and also certain integrable fractional discrete/difference equations, i.e., integrable fractional discrete NLS equation [4]. These methods can be used to construct  $N$ -soliton solutions in other integrable systems [31, 34]. The key aspects in the methodology are having a general evolution equation such as a hierarchy of equations that can be expanded to fractional powers and completeness; these aspects are found on the direct scattering side and the solution obtained from inverse scattering.

In this paper, we will be concerned with a integrable or solvable fractional Burgers equation and its associated hierarchy. The classical Burgers equation is often considered to be the most elementary integrable/solvable non-trivial non-linear evolution equation. The Cole–Hopf transformation (cf. [1]) leads directly to a linear evolution equation; unlike KdV, NLS or modified KdV, there is no need for inverse scattering. Here we investigate integrable fractional extensions of this Burgers equation and associated hierarchy. The results are explicit and the method is considerably simpler than the integrable fractional systems analysed using inverse scattering transform (IST). These equations are the simplest integrable/solvable fractional systems we are aware of.

Below we will first discuss linear fractional equations solvable by Fourier methods, then we will outline the main ideas associated with the integrable fractional KdV equation. We include this so that we can compare with the results we obtain for the integrable fractional Burgers equation and hierarchy. In the [appendix](#), we provide more information about the integrable fractional KdV equation.

### 1.1. Linear evolution equations

Linear evolution equations have been studied extensively. For example, consider an equation of the form

$$q_t + \gamma(\partial_x)q_x = 0, \quad q(x, 0) = q_0(x), \quad |x| < \infty \quad (1.1)$$

where  $\gamma(x)$  is a polynomial and  $q_0(x)$  vanishes rapidly as  $|x| \rightarrow \infty$ . These equations can be solved by Fourier transforms with the solution given by

$$q(x, t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} dk \hat{q}(k, 0) e^{ik(x - \gamma(ik)t)}, \quad (1.2)$$

where the Fourier transform of  $q(x, t)$  is given by

$$\hat{q}(k, t) = \int_{-\infty}^{\infty} q(x, t) e^{-ikx} dx. \quad (1.3)$$

For example, with  $\gamma(x) = x^2$ , we have the linearized KdV equation

$$q_t + \partial_x^3 q = 0, \quad q(x, 0) = q_0(x), \quad |x| < \infty. \quad (1.4)$$

Importantly, this methodology can be extended to fractional equations. For example, when  $\gamma(k) = k^2|k^2|^\alpha$ ;  $-1 < \alpha < 1$  (here and below we take  $\alpha \in \mathbb{R}$ ), we have

$$q_t + \partial_x^3 |\partial_x^2|^\alpha q = 0, \quad q(x, 0) = q_0(x), \quad |x| < \infty. \quad (1.5)$$

This is a linearized fractional KdV equation. Such fractional equations can be solved by Fourier transforms in a similar way to that of equations with polynomial  $\gamma(k)$ . This is based upon using the identification  $k \rightarrow -i\partial_x$  in the equation and inserting the function  $\gamma(ik)$  in the solution.

### 1.2. Fractional KdV hierarchy

Since the IST is the non-linear analog of Fourier transforms, we are motivated to extend IST to integrable fractional non-linear equations. We studied this issue in recent papers [4–6]. The main underlying issues are discussed below.

It was shown in [7] that, associated with the time-independent Schrödinger equation,

$$v_{xx} + \left(k^2 + q(x, t)\right) v = 0, \quad |x| < \infty \quad (1.6)$$

was a class of solvable non-linear equations given by

$$q_t + \gamma(L^A)q_x = 0, \quad |x| < \infty \quad (1.7)$$

where  $L^A$  is the operator

$$L^A = -\frac{1}{4}\partial_x^2 - q + \frac{1}{2}q_x \int_x^\infty dy$$

and  $\gamma(k)$  is related to the dispersion relation of the linear part of the equation. Note the linear limit is  $L^A \sim -\frac{1}{4}\partial_x^2$ . The operator  $L^A$  is the adjoint to an operator that involves certain squared eigenfunctions associated with (1.6) [7]; see also the [appendix](#).

The standard KdV hierarchy is given by

$$q_t + (L^A)^n q_x = 0, \quad n = 0, 1, 2, 3, \dots \quad (1.8)$$

When  $n = 1$ , this operator formulation yields the KdV equation

$$q_t + 6qq_x + q_{xxx} = 0. \quad (1.9)$$

When  $n = 2$ , we find Lax 5th order equation

$$q_t + q_{xxxxx} + 10qq_{xxx} + 20q_x q_{xx} + 30q^2 q_x = 0 \quad (1.10)$$

and so on. In Ablowitz et al. [7], the most general case considered was when  $\gamma(L^A)$  was taken to be a meromorphic function.

Suppose we wish to analyse fractional non-linear equations such as a fractional KdV equation where

$$\gamma(L^A) = -4L^A | -4L^A |^\alpha \quad \text{with } -1 < \alpha < 1.$$

However, we are confronted with the question: what is the meaning of a fractional power of the operator  $L^A$ ; i.e., how to express  $|L^A|^\alpha$  in physical space? In Ablowitz et al. [5], it was shown that the integrable fractional KdV equation

$$q_t - 4L^A |4L^A|^\alpha q_x = 0 \quad (1.11)$$

and integrable fractional KdV equation hierarchy

$$q_t + (-4L^A)^n |4L^A|^\alpha q_x = 0, \quad n = 1, 2, \dots \quad (1.12)$$

( $n = 1$  is the integrable fractional KdV equation) can be written in terms of concrete functions associated with the time-independent Schrödinger equation (1.6). For  $\alpha = 0$ , equation (1.12) provides an evolution

equation with integer derivatives. For fractional  $\alpha$ , an explicit non-local evolution equation can be written in term of the eigenfunctions of Schrödinger equation (1.6). The result is (see the [appendix](#) for more information)

$$q_t + \int_{\Gamma_\infty} dk (-4k^2)^n |4k^2|^\alpha \frac{\tau^2(k)}{4\pi i k} \int_{-\infty}^{\infty} dy G(x, y, k) q_y = 0, \quad n = 1, 2, \dots \quad (1.13)$$

where

$$G(x, y, k) = \partial_x(\psi^2(x, k))\varphi^2(y, k) - \partial_x(\varphi^2(x, k))\psi^2(y, k),$$

and  $\psi(x, k)$ ,  $\varphi(x, k)$  satisfy (1.6) with  $\varphi(x, k) \sim e^{-ikx}$ ,  $x \rightarrow -\infty$ ,  $\psi(x, k) \sim e^{ikx}$ ,  $x \rightarrow \infty$  and where

$$\varphi(x, k)\tau(k) = \psi(x, -k) + \rho(k)\psi(x, k)$$

with  $\tau(k)$ ,  $\rho(k)$  being the ‘transmission, reflection’ coefficients, respectively; it can be shown that  $\psi(x, k)e^{-ikx}$ ,  $\varphi(x, k)e^{ikx}$  are analytic in the upper half plane (UHP),  $\tau(k)$  is meromorphic in the UHP;  $\Gamma_\infty = \lim_{R \rightarrow \infty} \Gamma_R$  is the semicircular contour in the UHP from  $k = -R$  to  $k = R$ , above all poles of  $\tau(k)$  which are simple and finite in number and  $k = 0$  is a removable singular point. Equation (1.13) provides explicit meaning of the integrable fractional KdV hierarchy (1.12). Finding the functions in equation (1.12) requires finding the solution to the direct side of the time-independent Schrödinger equation (1.6).

At first glance, equation (1.13) may appear unusual, but in fact linear equations solvable by Fourier transforms can be put in a similar form. In this regard, consider the linear dispersive equation

$$q_t + \gamma(\partial_x^2)q_x = 0. \quad (1.14)$$

Using the Fourier representation of  $q_x$ , we can rewrite equation (1.14) as

$$q_t + \gamma(\partial_x^2) \frac{1}{2\pi} \int_{-\infty}^{\infty} dk e^{ikx} \int_{-\infty}^{\infty} dy e^{-iky} q_y = 0 \quad (1.15)$$

or

$$q_t + \frac{1}{2\pi} \int_{-\infty}^{\infty} dk \gamma(-k^2) \int_{-\infty}^{\infty} dy e^{ik(x-y)} q_y = 0. \quad (1.16)$$

A typical example is the fractional linear KdV hierarchy where

$$\gamma(\partial_x^2) = (\partial_x^2)^n |\partial_x|^\alpha \Rightarrow \gamma(-k^2) = (-k^2)^n |k^2|^\alpha, \quad n = 1, 2, \dots, -1 < \alpha < 1.$$

In the linear limit equation (1.13) reduces to equation (1.16) with these choices of  $\gamma(k)$ . We remark that linear fractional equations are intrinsically non-local.

### 1.3. IST solution of the fractional KdV hierarchy

In order to linearize/solve the integrable fractional KdV hierarchy, we employ inverse scattering. Briefly, this can be stated as follows. Solve the Gel’fand, Levitan, Marchenko (GLM) equation:

$$K(x, y; t) + F(x + y; t) + \int_x^\infty ds K(x, s; t) F(s + y; t) = 0 \quad (1.17a)$$

$$F(x; t) = F_c + F_d = \frac{1}{2\pi} \int_{-\infty}^{\infty} dk \rho(k, t) e^{ikx} + \sum_{j=1}^J c_j(t) e^{-k_j x} \quad (1.17b)$$

for  $K(x, y, t)$ ,  $y \geq x$ ; the solution of the fKdV equation is obtained from:

$$q(x, t) = 2 \frac{d}{dx} K(x, x; t).$$

In the GLM equation (1.17a–1.17b), the function  $F(x; t)$  depends on the so-called ‘scattering’ data (including their time dependence) which includes both continuous and discrete data; continuous data:  $\rho(k, t) = \frac{b(k, t)}{a(k, t)}$ ,  $a(k, t) = a(k, 0)$ ,  $b(k, t) = b(k, 0) e^{-2ik\gamma(k^2)t}$  where  $a(k, 0), b(k, 0)$  are known in terms of Wronskians of  $\phi, \varphi$  and

$$\gamma(k^2) = (-4k^2)^n |4k^2|^\alpha; -1 < \alpha < 1, n = 1, 2, \dots$$

Discrete data:  $k_j = ik_j$ , discrete eigenvalues;  $a(k_j) = 1/\tau(k_j) = 0$ ,  $j = 1, 2, \dots, J$ : constant in time, and  $c_j(t) = ib_j/a'(k_j)$ , where at an eigenvalue  $k_j$ ,  $\phi(x, k_j) = b_j \psi(x, k_j)$ ;  $c_j(t)$  are often referred to as norming constants.

We see that the only difference in the solution between KdV and fractional KdV is in the time dependence:  $\gamma(k^2)$ . This is similar to the linear case. ‘Pure’ soliton solutions are obtained when  $\rho(k, 0) = 0$  in which case  $F = F_d$ . Further, as  $t \rightarrow \infty$ ,  $F_c \rightarrow 0 \Rightarrow F \rightarrow F_d$  which in the long time limit leads to soliton solutions. A one soliton solution to fKdV is obtained when  $\rho(k, 0) = 0$ ,  $k_1 = ik_1$ ,  $\kappa_1 > 0$ ,  $c_1 = 2\kappa_1 e^{2\kappa_1 x_1}$ ; the one soliton solution is given by

$$q_{sol}(x, t) = 2\kappa_1^2 \text{sech}^2 \{ \kappa_1 ((x - x_1) - (4\kappa_1^2)^{1+\alpha} t) \}.$$

## 2. Integrable fractional Burgers equation

The Burgers hierarchy is given by

$$u_t + \sigma \partial_x L^n u = 0 \text{ where } L = (\partial_x + u(x, t)), \sigma \text{ const.} \quad (2.1)$$

The Burgers hierarchy and certain associated solutions were discussed in Kudryashov and Sinelshchikov [13].

For  $n = 0$ , (2.1) reduces to the transport equation,

$$u_t + \sigma u_x = 0. \quad (2.2)$$

For  $n = 1$ , we find the celebrated Burgers equation,

$$u_t + \sigma(u_{xx} + 2uu_x) = 0. \quad (2.3)$$

And for  $n = 2$ , we have

$$u_t + \sigma(u_{xxx} + 3u_x^2 + 3uu_{xx} + 3u^2 u_x) = 0, \quad (2.4)$$

which was found by Tasso [29] (see also Sharma and Tasso [27]) and Olver [21], who used the property that the equation has an infinite number of symmetries. Equation (2.4) is sometimes referred to as the Sharma-Tasso-Olver (STO) equation.

In Kudryashov and Sinelshchikov [13], the solution of the Burgers hierarchy is obtained by using the Cole–Hopf transformation

$$u = \frac{\psi_x}{\psi} \quad (2.5)$$

and it is shown that

$$u_t + \sigma \partial_x L^n u = \partial_x \left( \frac{\psi_t + \sigma \psi_{n+1,x}}{\psi} \right) = 0, \quad n = 0, 1, 2, \dots \quad (2.6)$$

where  $\psi_{n+1,x}$  represents  $n+1$  derivatives in  $x$ .

In order to obtain equation (2.6), we use the following lemma [13].

**Lemma 2.1.** *Under the transformation (2.5), the operator  $L^n$  from (2.1) becomes*

$$\begin{aligned} L^n \frac{\psi_x}{\psi} &= \left( \partial_x + \frac{\psi_x}{\psi} \right)^n \frac{\psi_x}{\psi} \\ &= \frac{\psi_{n+1,x}}{\psi}. \end{aligned}$$

Proof: The equation in Lemma (2.1) is obtained by induction. When  $n=0$ , we have

$$L^0 \frac{\psi_x}{\psi} = \frac{\psi_x}{\psi}.$$

If we assume the lemma holds for  $n=k$ , i.e.,

$$\left( \partial_x + \frac{\psi_x}{\psi} \right)^k \frac{\psi_x}{\psi} = \frac{\psi_{k+1,x}}{\psi},$$

then

$$\begin{aligned} \left( \partial_x + \frac{\psi_x}{\psi} \right)^{k+1} \frac{\psi_x}{\psi} &= \left( \partial_x + \frac{\psi_x}{\psi} \right) \left( \partial_x + \frac{\psi_x}{\psi} \right)^k \frac{\psi_x}{\psi} \\ &= \left( \partial_x + \frac{\psi_x}{\psi} \right) \frac{\psi_{k+1,x}}{\psi} \\ &= \frac{\psi_{k+2,x}}{\psi} - \frac{\psi_{k+1,x}}{\psi^2} \psi_x + \frac{\psi_{k+1,x}}{\psi^2} \psi_x \\ &= \frac{\psi_{k+2,x}}{\psi}. \end{aligned}$$

Thus, by induction, the lemma holds for all  $n$ .

We can now derive equation (2.6) using the Cole–Hopf transformation (2.5) and Lemma (2.1). This follows from

$$\begin{aligned} u_t + \sigma \partial_x L^n u &= \frac{\psi_{xt}}{\psi} - \frac{\psi_x \psi_t}{\psi^2} + \sigma \partial_x \left( \frac{\psi_{n+1,x}}{\psi} \right) \\ &= \partial_x \left( \frac{\psi_t}{\psi} \right) + \sigma \partial_x \left( \frac{\psi_{n+1,x}}{\psi} \right) \\ &= \partial_x \left( \frac{\psi_t + \sigma \psi_{n+1,x}}{\psi} \right) \\ &= 0. \end{aligned}$$

The issue we address here is to understand the fractional Burgers equation and fractional Burgers hierarchy

$$u_t + \sigma \partial_x L^n |L|^\alpha u = 0 \quad \text{with } -1 < \alpha < 1. \quad (2.7)$$

Importantly, when we operate on a pure exponential or evaluate a Fourier transform we use the following formula for fractional derivatives

$$\partial_x^n |\partial_x|^\alpha e^{\mu x} = \mu^n |\mu|^\alpha e^{\mu x}. \quad (2.8)$$

## 2.1. Inverse approach

In analogy with the fractional KdV equation/hierarchy, we will consider both the ‘direct and inverse’ side of Burgers equation/hierarchy. Analogous to the fact that the time-independent Schrödinger equation is key to both the direct and inverse side of the KdV hierarchy, the Cole–Hopf equation is central to both the direct and inverse side of the Burgers hierarchy. First, we consider the inverse, which has a natural extension in terms of the linearized equation. If we formally replace  $n$  by  $n + |\alpha|$ ,  $-1 < \alpha < 1$ , then equation (2.6) takes the form

$$\partial_x \left( \frac{\psi_t + \sigma \psi_{n+|\alpha|+1,x}}{\psi} \right) = 0. \quad (2.9)$$

We note that equation (2.9) can be evaluated in a Fourier context and can be considered as the fractional continuation of equation (2.6).

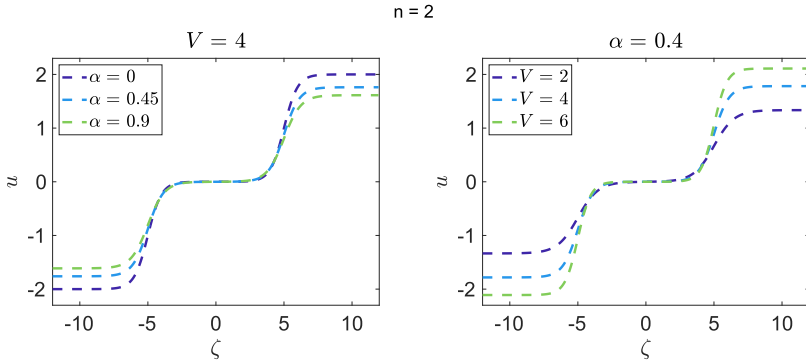
After integrating once, equation (2.9) becomes

$$\psi_t + \sigma \psi_{n+|\alpha|+1,x} = C(t)\psi, \quad (2.10)$$

where  $C(t)$  is an arbitrary function of time. We note that  $C(t)$  can be absorbed into  $\psi$  by rescaling. We can rewrite equation (2.10) in the form

$$\psi_t + \sigma \partial_x^{n+1} |\partial_x|^\alpha \psi = C(t)\psi. \quad (2.11)$$

The term  $|\partial_x|^\alpha$  yields well-posed solutions. This is the 1D analog of the fractional Laplacian. Under the Cole–Hopf transformation (2.5), equation (2.11) can be viewed as the solution of the *inverse* problem associated with the fractional Burgers hierarchy. Similarly, the analog of the *direct* problem for the



**Figure 1.** Evolution of the fractional Burgers extension of the transport equation ( $n=0$ ) with  $\sigma=1$  and various values of  $\alpha$ . The initial condition is  $u(x,0) = (x-x_0)e^{-(x-x_0)^2}$  with  $x_0=5$ . (a) Contour plots. (b) Profiles taken at  $t=5$ .

Burgers hierarchy takes the form

$$u_t + \sigma \partial_x L^n |L|^\alpha u = 0. \quad (2.12)$$

We will refer to the case  $n=1$  as the fractional Burgers equation.

Taking  $C(t) = 0$ , we can use the definition (2.8) to write solutions to equation (2.10) in terms of Fourier transforms or series. For  $n=0$  and  $\sigma$  real, equation (2.10) has oscillating exponential solutions of the form

$$e^{i(kx - \sigma k |k|^\alpha t)}$$

and a Fourier transform solution of the form

$$\psi(x,t) - 1 = \frac{1}{2\pi} \int_{-\infty}^{\infty} \widehat{\psi}(k,0) e^{i(kx - \sigma k |k|^\alpha t)} dk \quad (2.13)$$

where

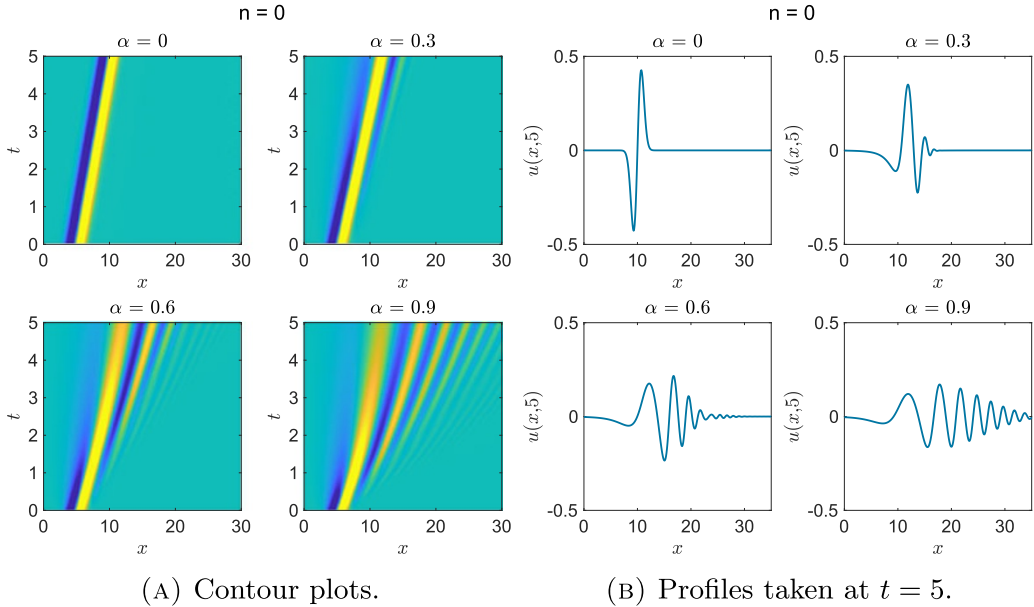
$$\widehat{\psi}(k,0) = \int_{-\infty}^{\infty} (\psi(x,0) - 1) e^{-ikx} dx$$

is the Fourier transform of the initial value. The initial value  $\psi(x,t=0)$  is obtained from the Cole–Hopf transformation (2.5) as

$$\psi(x,0) = e^{\int_{-\infty}^x u_0(x') dx'} \quad (2.14)$$

where we normalize  $\psi$  to be unity as  $x \rightarrow -\infty$ . So, assuming  $u(x,t)$  is decaying and initially  $\int_{-\infty}^{\infty} u_0(x) dx = 0$ , there exists a Fourier transform for  $\psi - 1$ .

In Figure 1, we see example evolutions for the fractional extension of the transport equation that have been calculated using the solution found from the *inverse* method (2.13) and computationally obtained using discrete Fourier transforms. Here, we see that the fractional term is associated with a dispersive front that resembles a dispersive shock wave.



**Figure 2.** Evolution of the fractional Burgers equation ( $n=1$ ) with  $\sigma = -1$  and various values of  $\alpha$ . The initial condition is  $u(x, 0) = e^{-(x+x_0)^2/\omega} - e^{-(x-x_0)^2/\omega}$  with  $x_0 = 10$  and  $\omega = 4$ . (a) Contour plots. (b) Profiles taken at  $t = 5$ .

For  $n = 1$  and  $\sigma = -1$ , we have the fractional Burgers equation with associated plane wave solutions of the form

$$\psi_k(x, t) = e^{ikx - k^2|k|^\alpha t}$$

which decay rapidly in time and general solution

$$\psi(x, t) = 1 + \frac{1}{2\pi} \int_{-\infty}^{\infty} \hat{\psi}(k, 0) e^{ikx - k^2|k|^\alpha t} dk. \quad (2.15)$$

We can also analyse periodic solutions via

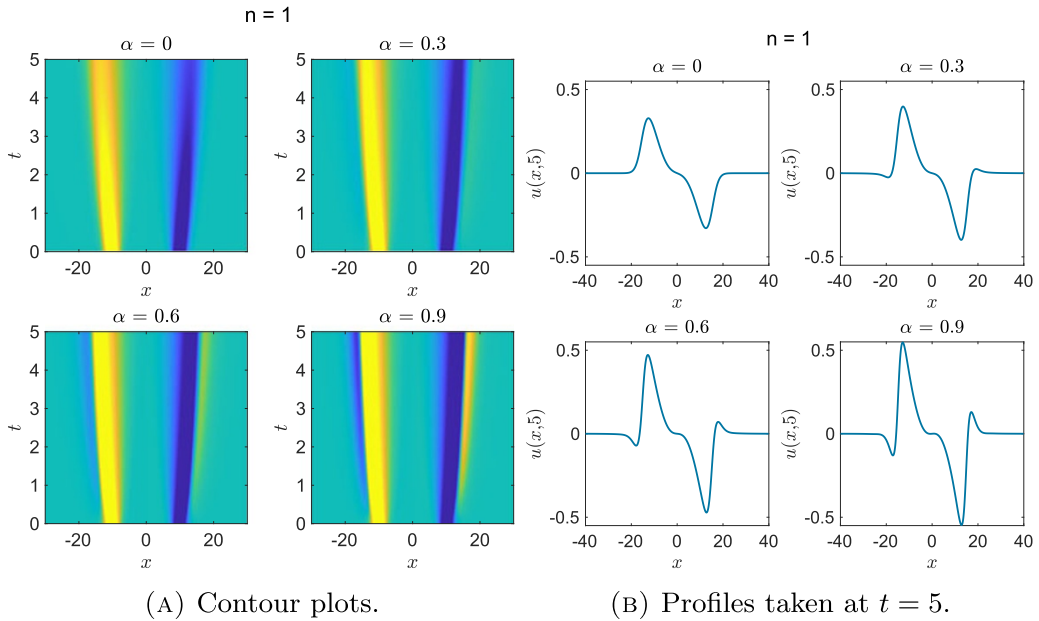
$$\psi(x, t) = 1 + \sum_{n=-\infty}^{\infty} \hat{\psi}_n(t) e^{inx - n^2|n|^\alpha t},$$

which is being used for the numerical examples.

In Figure 2, we see example evolutions for the fractional Burgers equation where solutions have been calculated using the solution found from the *inverse* method (2.15) and computationally obtained using discrete Fourier transforms. Unlike the  $n=0$  case, we see less pronounced effects from increasing the fractional constant  $\alpha$  with a ‘lip’ developing on the shock-like side of the wave fronts. Note that there is not a smooth transition from the  $n=0$  case to the  $n=1$  case; we do not expect such a transition due to the absolute value in the Fourier solution of (2.11) which has waves of the form  $e^{ikx - (ik)^{(n+1)}|k|^\alpha t}$ , which maintains dispersion when  $n$  is even and diffusion when  $n$  is odd.

For  $n=2$  and  $\sigma = 1$ , similarly to the  $n=0$  case, our equation admits a family of periodic exponential solutions. The general solution takes the form

$$\psi(x, t) = 1 + \frac{1}{2\pi} \int_{-\infty}^{\infty} \hat{\psi}(k, 0) e^{i(kx - \sigma k^3|k|^\alpha t)} dk. \quad (2.16)$$



**Figure 3.** Evolution of the fractional Olver equation ( $n=2$ ) with  $\sigma=1$  and various values of  $\alpha$ . The initial conditions is  $u(x, 0) = (x - x_0)e^{-(x-x_0)^2}$  with  $x_0 = 80$ . (a) Contour plots. (b) Profiles taken at  $t=1$ .

In Figure 3, we see example evolutions for the  $n=2$  case found from the *inverse* method (2.16) and obtained computationally using discrete Fourier transforms. Note: the fractional equations also have solutions that exhibit blow up. This occurs when the non-linear effects are stronger and there are zeroes in the transformed equation, i.e.,  $\psi = 0$ .

Thus, using the concept of direct and inverse equations, we have seen that on the inverse side the fractional equation (2.11) can be evaluated via Fourier methods.

## 2.2. Direct approach

A key question remaining is to understand the meaning and method of calculation of the fractional equation (2.12) on the direct side. Here the part that needs to be understood is how to calculate  $|L|^\alpha$  where  $L = (u(x, t) + \partial_x)$ . For this, we once again employ the Cole–Hopf transformation (2.5). Here the Cole–Hopf transformation is the analog of the time-independent Schrödinger equation that is associated with the KdV/fractional KdV equation.

Consider the fractional continuation of the Lemma (2.1)

$$\begin{aligned} L^n |L|^\alpha \frac{\psi_x}{\psi} &= \left( \partial_x + \frac{\psi_x}{\psi} \right)^n |\partial_x + \psi_x|^\alpha \frac{\psi_x}{\psi} \\ &= \frac{\partial_x^{n+1} |\partial_x|^\alpha \psi}{\psi} \end{aligned} \quad (2.17)$$

which we calculate in Fourier space using the derivative formula (2.8). Then we have

$$0 = \partial_t u + \sigma \partial_x L^n |L|^\alpha u \quad (2.18a)$$

$$= \partial_t u + \sigma \partial_x \left( \frac{\partial_x^{n+1} |\partial_x|^\alpha \psi}{\psi} \right) \quad (2.18b)$$

$$= \partial_t u + \sigma \partial_x \frac{\partial_x^n |\partial_x|^\alpha \psi_x}{\psi}, \quad (2.18c)$$

where the initial condition  $u(x, t = 0) = u_0(x)$  is given on  $|x| < \infty$ . We calculate  $\psi, \psi_x$  from  $u$  using the Cole–Hopf transformation (2.5) via

$$\psi(x, t) = e^{\int_{-\infty}^x u(x', t) dx'} \quad (2.19a)$$

$$\psi_x(x, t) = u(x, t) e^{\int_{-\infty}^x u(x', t) dx'} \quad (2.19b)$$

where we normalize  $\psi$  to be unity as  $x \rightarrow -\infty$  and assume  $u(x, t)$  is decaying and initially  $\int_{-\infty}^{\infty} u_0(x) dx = 0$ . Now,  $\psi_x$  has a Fourier transform and we can evaluate the fractional Burgers hierarchy using equation (2.18c).

We calculate the *direct* method numerically using a standard 4th order Runge–Kutta solver in time and spectral methods to compute the spatial derivatives on the discretized system obtained by taking the Fourier transform of equation (2.18c). This leads us to

$$\mathbf{v}_t = -i\sigma \mathbf{k} \mathcal{F} \left( \frac{i\mathbf{k}^n |\mathbf{k}|^\alpha \psi_x}{\psi} \right) \quad (2.20a)$$

$$\mathbf{v}(0) = \mathcal{F}[u(\mathbf{x}, 0)] \quad (2.20b)$$

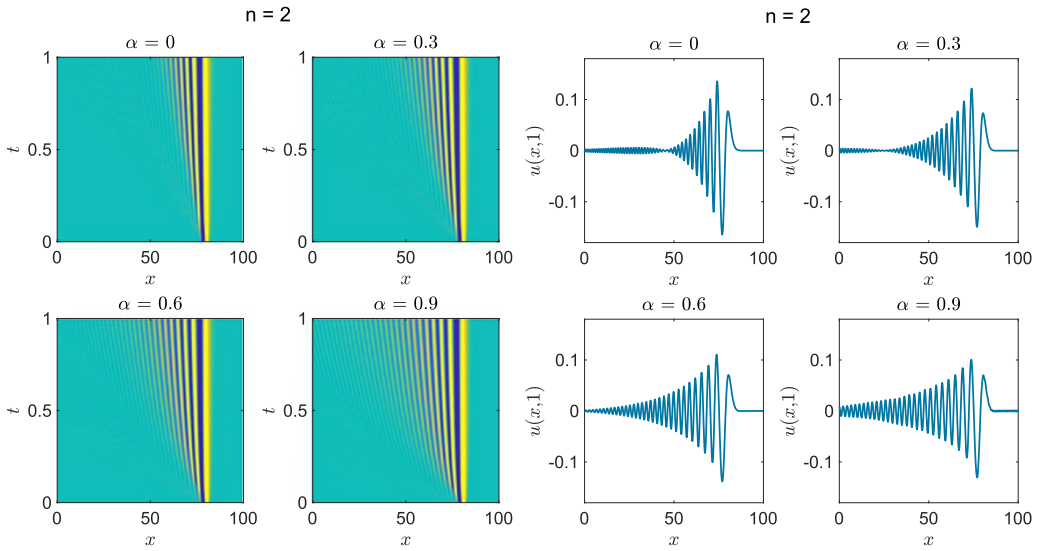
$$\text{with } \psi = \text{Exp} \left( \int \mathcal{F}^{-1}[\mathbf{v}] \right) \quad \text{and} \quad \psi_x = \mathcal{F}^{-1}[\mathbf{v}] \psi \quad (2.20c)$$

where  $\mathbf{x}$  and  $\mathbf{k}$  are compatible discretizations of the real and Fourier space respectively,  $\mathcal{F}$  and  $\mathcal{F}^{-1}$  are the discrete Fourier transform and inverse discrete Fourier transform and  $\int$  is an approximation of  $\int_{-\infty}^x u(x', t) dx'$  using a cumulative trapezoid rule. This scheme converges to solutions obtained from the *inverse* method as the number of Fourier modes taken increases; this is illustrated in Figure 4. Both the *inverse* and *direct* methods are in full agreement, though we note that the *direct* method requires small time stepping to converge.

Without using the Cole–Hopf formula (2.5) and Fourier fractional derivatives of exponentials given by equation (2.8), it is not clear how to evaluate the fractional extension of the  $L$  operator  $L^n |L|^\alpha$ . However, for special cases we can use the binomial expansion of  $L^n = (\partial_x + u)^n = u^n (1 + \frac{\partial_x}{u})^n$  when the operator  $\frac{\partial_x}{u}$  is smaller than unity. In certain cases, analytic continuation can lead to a result valid when  $\frac{\partial_x}{u}$  is not small. We also note that we can use other definitions of fractional derivatives on the forward and inverse side. However, the advantage of Fourier derivatives is that it leads to explicit results.

### 2.3. Shock solutions

Next we turn to studying special traveling wave (TW) solutions of these equations. We begin with Burgers equation (2.3) with  $\sigma = -1$ . A TW solution is obtained from equation (2.11) with



(A) Contour plots.

(B) Profiles taken at  $t = 1$ .

**Figure 4.** (Left) Comparison of the numerical solutions to the fractional Burgers equations found using the inverse method (solid blue) and the direct method (dashed red) with  $\alpha = 0.9$ ,  $N = 2^{10}$  (Fourier modes) and time step  $\Delta t = 6.25 \times 10^{-5}$ . (Right) Difference between the inverse method and the direct method with an increasing number of Fourier modes taken.

$n = 1, \alpha = 0, C(t) = C_0$  constant,

$$\psi_t - \partial_x^2 \psi = C_0 \psi. \quad (2.21)$$

A TW solution is obtained by looking for solutions of the form

$$\psi(x, t) = \psi(\zeta) \quad \text{where } \zeta = x - Vt, \quad V \text{ constant.} \quad (2.22)$$

This yields the ODE

$$\psi_{\zeta\zeta} + V\psi_{\zeta} + C_0\psi = 0. \quad (2.23)$$

Looking for solutions of the form  $e^{r\zeta}$ ,  $r$  constant, yields

$$r^2 + Vr + C_0 = 0 \Rightarrow r^2 + Vr + C_0 = 0,$$

which has two solutions

$$r_{\pm} = -\frac{V}{2} \pm \sqrt{\left(\frac{V}{2}\right)^2 - C_0}.$$

When  $\frac{V^2}{2} - C_0 > 0$ , there are two real solutions; we write the solution  $\psi$  as

$$\psi = c_1 e^{r_+ \zeta} + c_2 e^{r_- \zeta} \quad (2.24)$$

and the solution of Burgers equation as

$$u(\zeta) = \frac{\psi_\zeta}{\psi} \quad (2.25a)$$

$$= \frac{c_1 r_+ e^{r_+ \zeta} + c_2 r_- e^{r_- \zeta}}{c_1 e^{r_+ \zeta} + c_2 e^{r_- \zeta}} \quad (2.25b)$$

$$= \frac{r_+ + r_- e^{(r_- - r_+)(\zeta - \zeta_0)}}{1 + e^{(r_- - r_+)(\zeta - \zeta_0)}}, \quad (2.25c)$$

where  $\frac{c_2}{c_1} = e^{-(r_- - r_+)\zeta_0}$ . This shock solution increases from  $r_-$  as  $\zeta \rightarrow -\infty$  to  $r_+$  as  $\zeta \rightarrow \infty$ ; we also note that  $r_- + r_+ = -V$ . When  $(\frac{V}{2})^2 - C_0 = 0$  then  $r$  has a double root; we find

$$\psi = c_1 e^{-\frac{V}{2}\zeta} + c_2 \zeta e^{-\frac{V}{2}\zeta},$$

which corresponds to the following rational solution of Burgers equation

$$u(\zeta) = \frac{\psi_\zeta}{\psi} = -\frac{V}{2} + \frac{1}{\zeta - \zeta_0},$$

where  $\frac{c_1}{c_2} = -\zeta_0$ . This solution is singular when  $\zeta = \zeta_0$ . When  $\frac{V^2}{2} + C_0 < 0$ , there are singular oscillatory solutions; we will not go into further detail on these solutions here.

Now we will discuss the fractional Burgers equation (2.12) with  $n = 1$ ,  $-1 < \alpha < 1$ ,  $\sigma = -1$  whose solution is obtained from equation (2.11). As we did for Burgers equation, we look for TW solutions  $\psi(x, t) = \psi(\zeta)$  with  $C(t) = C_0$  constant. The fractional TW equation is given by

$$\partial_\zeta^2 |\partial_\zeta|^\alpha \psi + V \partial_\zeta \psi + C_0 \psi = 0. \quad (2.26)$$

Solutions of the form  $\psi = e^{r\zeta}$ ,  $r$  constant, lead to an equation for  $r$  of the form

$$r^2 |r|^\alpha + Vr + C_0 = 0. \quad (2.27)$$

Graphical analysis indicates that there can be two solutions  $r_\pm$  where  $r_+ > r_-$ . In this case, the equation for  $\psi$  has the same form as in equation (2.24)

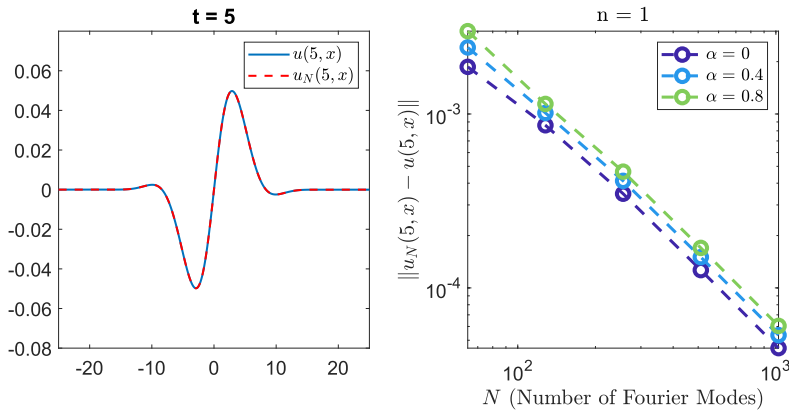
$$\psi = c_1 e^{r_+ \zeta} + c_2 e^{r_- \zeta}. \quad (2.28)$$

Hence,

$$u(\zeta) = \frac{\psi_\zeta}{\psi} \quad (2.29a)$$

$$= \frac{c_1 r_+ e^{r_+ \zeta} + c_2 r_- e^{r_- \zeta}}{c_1 e^{r_+ \zeta} + c_2 e^{r_- \zeta}} \quad (2.29b)$$

$$= \frac{r_+ + r_- e^{(r_- - r_+)(\zeta - \zeta_0)}}{1 + e^{(r_- - r_+)(\zeta - \zeta_0)}} \quad (2.29c)$$



**Figure 5.** Traveling wave shock-like solutions of the fractional Burgers equation (2.26) with  $C_0 = 0$  and  $\zeta_0 = 0$ . Here we use the exact solution (2.29c) with (2.27), which yields  $r_+ = 0$  and  $r_- = -\text{sgn}(V)|V|^{1/(1+\alpha)}$ .

where  $\frac{c_2}{c_1} = e^{-(r_- - r_+)\zeta_0}$ . These TW shock waves are depicted in Figure 5. For  $C_0 = 0$ , we have  $r_+ = 0$  and  $r_- = -V^{1/(1+\alpha)}$ ,  $V > 0$ .

Finally, let's consider the next equation in the hierarchy (2.12) with  $\sigma = 1$ ,  $n = 2$ . The function  $\psi$  we will consider satisfies

$$\partial_t \psi + \partial_x^3 |\partial_x|^\alpha \psi = C(t) \psi. \quad (2.30)$$

TW solutions,  $\psi(x, t) = \psi(\zeta)$  with  $C(t) = C_0$  constant, satisfy

$$\partial_\zeta^3 |\partial_\zeta|^\alpha \psi - V \partial_\zeta \psi - C_0 \psi = 0. \quad (2.31)$$

Looking for solutions of the form  $\psi = e^{r\zeta}$ ,  $r$  constant, leads to the following equation for  $r$

$$r^3 |r|^\alpha - Vr - C_0 = 0. \quad (2.32)$$

For  $-1 < \alpha < 1$  depending on the sign and size of  $C_0$  and  $V$ , graphical analysis indicates there can be three real solutions  $r_3 > r_2 > r_1$ . Then we have

$$\psi = c_1 e^{r_1 \zeta} + c_2 e^{r_2 \zeta} + c_3 e^{r_3 \zeta} \quad (2.33)$$

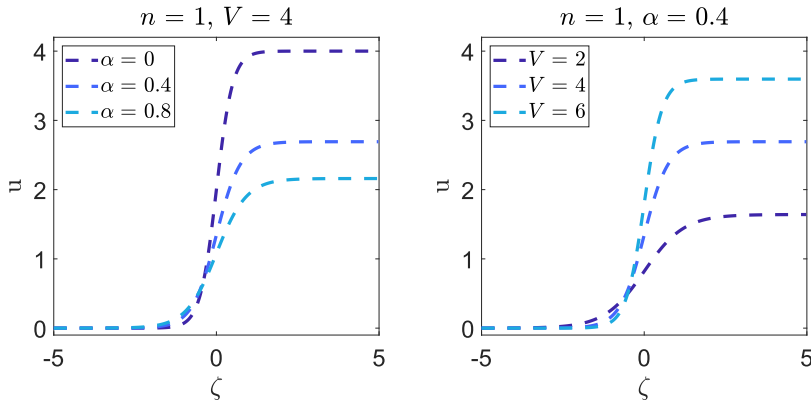
and

$$u(\zeta) = \frac{\psi_\zeta}{\psi} \quad (2.34a)$$

$$= \frac{c_1 r_1 e^{r_1 \zeta} + c_2 r_2 e^{r_2 \zeta} + c_3 r_3 e^{r_3 \zeta}}{c_1 e^{r_1 \zeta} + c_2 e^{r_2 \zeta} + c_3 e^{r_3 \zeta}} \quad (2.34b)$$

$$= \frac{r_1 e^{(r_1 - r_2)(\zeta - \zeta_-)} + r_2 + r_3 e^{(r_3 - r_2)(\zeta - \zeta_+)}}{e^{(r_1 - r_2)(\zeta - \zeta_-)} + 1 + e^{(r_3 - r_2)(\zeta - \zeta_+)}} \quad (2.34c)$$

where  $\frac{c_1}{c_2} = e^{-(r_1 - r_2)\zeta_-}$ ,  $\frac{c_3}{c_2} = e^{-(r_3 - r_2)\zeta_+}$ . So, as  $\zeta \rightarrow \infty$ ,  $u \sim r_3$  and as  $\zeta \rightarrow -\infty$ ,  $u \sim r_1$ ; hence we have a shock-like TW solution with some additional interior structure. Typical shock waves with



**Figure 6.** Traveling wave shock-like solutions of equation (2.31) ( $n=2$ ) with  $C_0 = 0$ ,  $\zeta_{\pm} = \pm 5$ . Here we use the exact solution (2.34c) with (2.32), which yields  $r_2 = 0$ ,  $r_1 = -V^{1/(2+\alpha)}$  and  $r_3 = V^{1/(2+\alpha)}$ ,  $V > 0$ .

a middle plateau are depicted in Figure 6. For  $C_0 = 0$ , we have  $r_2 = 0$ ,  $r_1 = -V^{1/(2+\alpha)}$  and  $r_3 = V^{1/(2+\alpha)}$ ,  $V > 0$ .

### 3. Conclusion

Fractional integrable Burgers equation and hierarchy are considered. Fractional derivatives are calculated via Fourier methods. Using the Cole–Hopf transformation, we formulate these Burgers equations on the direct side and discuss how to find these solutions. On the inverse side, we use the Cole–Hopf transformation to find a fractional partial differential equation. Results from fractional integrable KdV equation and hierarchy are used as a guide.

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## Appendix

To establish equation (1.13), we use a result involving completeness of suitable *squared* eigenfunctions of the time-independent Schrödinger equation. Concretely, in Sachs [34], it was shown that a rapidly decreasing function  $h(x)$  can be written in the form

$$h(x) = \int_{\Gamma_\infty} dk \frac{\tau^2(k)}{4\pi i k} \int_{-\infty}^{\infty} dy G(x, y, k) h(y) \quad (\text{A.1})$$

(note that the variable  $t$  is suppressed); in the above:

$$G(x, y, k) = \partial_x(\psi^2(x, k))\varphi^2(y, k) - \partial_x(\varphi^2(x, k))\psi^2(y, k),$$

where  $\psi(x, k), \varphi(x, k)$  satisfy (1.6) with

$$\varphi(x, k) \sim e^{-ikx}, x \rightarrow -\infty, \quad \psi(x, k) \sim e^{ikx}, x \rightarrow \infty$$

and

$$\varphi(x, k)\tau(k) = \psi(x, -k) + \rho(k)\psi(x, k)$$

with  $\tau(k), \rho(k)$  the ‘transmission, reflection’ coefficients, respectively; it can be shown that  $\psi(x, k)e^{-ikx}, \varphi(x, k)e^{ikx}$  are analytic in the UHP and  $\tau(k)$  is meromorphic in the UHP;  $\Gamma_\infty = \lim_{R \rightarrow \infty} \Gamma_R$  is the semicircular contour in the UHP from  $k = -R$  to  $k = R$ , above all poles of  $\tau(k)$  which are simple and finite ( $J$ ) in number;  $k = 0$  is a removable singular point. Due to analyticity we can deform the integral along  $\Gamma_\infty$ :

$$\int_{\Gamma_\infty} dk = \int_{-\infty}^{\infty} dk + \sum_{j=1}^{j=J} (2\pi i)(\text{residues}).$$

It is worth noting that in the linear limit:  $\int_{\Gamma_\infty} \sim \int_{-\infty}^{\infty}$ ;  $\varphi(x, k) \sim e^{-ikx}$ ,  $\psi(x, k) \sim e^{ikx}$ ,  $\tau \rightarrow 1$  and there are no poles in  $\tau(k)$ . Then the completeness relation reduces to

$$h(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} dk e^{ikx} \int_{-\infty}^{\infty} dy e^{-iky} h(y),$$

which is the completeness relation for Fourier transforms.

Recall the operator

$$L^A = -\frac{1}{4}\partial_x^2 - q + \frac{1}{2}q_x \int_x^\infty dy. \quad (\text{A.2})$$

Its adjoint is

$$L = -\frac{1}{4}\partial_x^2 - q + \frac{1}{2} \int_{-\infty}^x q_y dy. \quad (\text{A.3})$$

In Ablowitz et al. [29], the following spectral relations are derived for  $L^A$

$$L^A V^A = k^2 V^A, \quad \text{with } V^A = \partial_x(\psi^2(x, k)) \text{ or } \partial_x(\varphi^2(x, k)) \quad (\text{A.4})$$

and  $L$ :

$$LV = k^2 V, \quad \text{with } V = \psi^2(x, k) \text{ or } \varphi^2(x, k). \quad (\text{A.5})$$

Recall  $G(x, y, k) = \partial_x(\psi^2(x, k))\varphi^2(y, k) - \partial_x(\varphi^2(x, k))\psi^2(y, k)$ . Therefore, we have  $L^A G(x, y, k) = k^2 G(x, y, k)$  and similarly  $|L^A|^\alpha G(x, y, k) = |k^2|^\alpha G(x, y, k)$ . So with  $\gamma(L^A) = -4L^A |4L^A|^\alpha$ ,  $-1 < \alpha < 1$ , using completeness the fractional KdV equation given by

$$q_t - 4L^A |4L^A|^\alpha q_x = 0$$

is given by ( $t$  suppressed)

$$q_t - \int_{\Gamma_\infty} dk 4k^2 |4k^2|^\alpha \frac{\tau^2(k)}{4\pi i k} \int_{-\infty}^{\infty} dy G(x, y, k) q_y = 0. \quad (\text{A.6})$$

Using the properties of squared eigenfunctions, we can write the above equation as

$$q_t + \int_{\Gamma_\infty} dk |4k^2|^\alpha \frac{\tau^2(k)}{4\pi i k} \int_{-\infty}^{\infty} dy G(x, y, k) (6qq_y + q_{yyy}) = 0. \quad (\text{A.7})$$

Next it is shown how to go from equation (A.6) to (A.7). We use

$$-4k^2 G(x, y, k) = \partial_x(\psi^2(x, k))(-4k^2)\varphi^2(y, k) - \partial_x(\varphi^2(x, k))(-4k^2)\psi^2(y, k).$$

Then from

$$k^2(\varphi^2, \psi^2)^T(y, k) = L(\varphi^2, \psi^2)^T(y, k) \text{ where } L = -\frac{1}{4}\partial_y^2 - q(y) + \frac{1}{2} \int_{-\infty}^y q_{y'}(y') dy'$$

we have

$$-4k^2 G(x, y, k) = \partial_x(\psi^2(x, k))(-4L)\varphi^2(y, k) - \partial_x(\varphi^2(x, k))(-4L)\psi^2(y, k).$$

Using the operator  $L$  gives

$$-4k^2 G(x, y, k) q_y = \partial_x(\psi^2(x, k)) \left( (\partial_y^2 \varphi^2(y)) q_y + 4q\varphi^2(y) q_y - 2q_y \int_{-\infty}^y dy' q_{y'} \varphi^2(y') \right) \quad (\text{A.8})$$

$$- \partial_x(\varphi^2(x, k)) \left( (\partial_y^2 \psi^2(y)) q_y + 4q\psi^2(y) q_y - 2q_y \int_{-\infty}^y dy' q_{y'} \psi^2(y') \right). \quad (\text{A.9})$$

The  $\partial_y^2$  terms are integrated by parts twice to yield  $G(x, y, k) q_{yyy}$  and then we interchange integrals in the last terms to find

$$-2 \int_{-\infty}^{\infty} dy q_y \int_{-\infty}^y dy' q_{y'} \varphi^2(y') = -2 \int_{-\infty}^{\infty} dy' q_{y'} \varphi^2(y') \int_{y'}^{\infty} dy q_y = 2 \int_{-\infty}^{\infty} dy' q q_y \varphi^2(y). \quad (\text{A.10})$$

Combining terms yields

$$-4k^2 G(x, y, k) q_y = G(x, y, k) (q_{yyy} + 6qq_y),$$

which is the term on the right hand side of equation (A.7).

The above two equations (A.6) and (A.7) provide explicit meaning for the fractional KdV equation in terms of eigenfunctions and scattering data. We further note that when  $\alpha = 0$  we recover the KdV equation:  $q_t + 6qq_x + q_{xxx} = 0$ .

Moreover in the linear limit:  $\psi(x, k) \rightarrow e^{ikx}$ ,  $\phi(x, k) \rightarrow e^{-ikx}$ ,  $\tau \rightarrow 1$ , then from equation (A.6) we have

$$q_t + \int_{-\infty}^{\infty} dk (-i) k^3 |k^2|^\alpha e^{ikx} \underbrace{\int_{-\infty}^{\infty} e^{-iky} q(y) dy}_{=\hat{q}(k)} = 0.$$

Then using  $ik \rightarrow \partial_x$  we find the linear fractional KdV equation

$$q_t + \partial_x^3 |\partial_x^2|^\alpha q = 0.$$