

PAPER

Equilibrium and non-equilibrium diffusion approximation for the radiative transfer equation

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Abstract

In this paper, we study the distribution of the temperature within a body where the heat is transported only by radiation. Specifically, we consider the situation where both emission-absorption and scattering processes take place. We study the initial-boundary value problem given by the coupling of the radiative transfer equation with the energy balance equation on a convex domain $\Omega \subset \mathbb{R}^3$ in the diffusion approximation regime, that is, when the mean free path of the photons tends to zero. Using the method of matched asymptotic expansions, we will derive the limit initial-boundary value problems for all different possible scaling limit regimes, and we will classify them as equilibrium or non-equilibrium diffusion approximation. Moreover, we will observe the formation of boundary and initial layers for which suitable equations are obtained. We will consider both stationary and time-dependent problems as well as different situations in which the light is assumed to propagate either instantaneously or with finite speed.

1. Introduction

The kinetic equation, which describes the interaction of matter with photons, is the radiative transfer equation. The radiative transfer equation can be written including absorption-emission processes and scattering processes in a rather general setting as

$$\frac{1}{c} \partial_t I_\nu(t, x, n) + n \cdot \nabla_x I_\nu(t, x, n) = \alpha_\nu^e - \alpha_\nu^a I_\nu(t, x, n) + \alpha_\nu^s \left(\int_{\mathbb{S}^2} K(n, n') I_\nu(t, x, n') dn' - I_\nu(t, x, n) \right). \quad (1.1)$$

We denote by $I_\nu(t, x, n)$ the radiation intensity, that is, the distribution of energy of photons moving at time $t > 0$, at position $x \in \Omega \subset \mathbb{R}^3$ and in direction $n \in \mathbb{S}^2$ with frequency $\nu > 0$. Moreover, c is the speed of light in the medium that will be assumed to be constant. The parameters α^e , α^a and α^s are, respectively, the emission, absorption and scattering coefficients. These are functions that can depend on the frequency ν , on the position x or, in the case of local thermal equilibrium, on the local temperature $T(x)$. The function K is the scattering kernel. It can be considered as the probability rate of a photon to be deflected from an incident direction $n' \in \mathbb{S}^2$ to a new direction $n \in \mathbb{S}^2$. The scattering kernel K can also be assumed to depend on the frequency $\nu \in \mathbb{R}_+$. However, in this paper, we omit the dependence on ν in order to simplify the notation. Notice that all the results that we will present in this paper also hold in the case where K is a function of ν .

In this paper, we will study the heat transfer by means of radiation under some assumptions. First of all, we consider only the case of local thermal equilibrium in which the temperature $T(t, x)$ is well-defined at any point $x \in \Omega$ and for any time $t > 0$. This is not necessarily the case in situations where

the microscopic processes driving the system towards equilibrium are slow. Such problems arise in applications to astrophysics (cf. [45]). Under this assumption, the emission coefficient takes a particular form. Indeed, it is given by $\alpha_v^e = \alpha_v^a B_v(T(t, x))$, where $B_v(T) = \frac{2hv^3}{c^2} \frac{1}{e^{\frac{hv}{kT}} - 1}$ is the Planck distribution of a black body. We assume also that the considered material is isotropic without a preferred direction of scattering. Hence, the scattering kernel K is invariant under rotations.

We couple the radiative transfer equation with the energy balance equation

$$C \partial_t T(t, x) + \frac{1}{c} \partial_t \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn I_v(t, x, n) \right) + \operatorname{div} \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn n I_v(t, x, n) \right) = 0, \quad (1.2)$$

where $C > 0$ is the volumetric heat capacity of the material. The combined system (1.1) and (1.2) allows to determine the temperature of the system at any point when the heat is transferred only by means of radiation. Notice that in (1.2), we are not considering other heat transport processes such as conduction or convection. After a suitable time rescaling, we can assume $C = 1$. As a boundary condition, we consider a source of radiation placed at infinity. Mathematically, we impose

$$I_v(t, x, n) = g_v(t, n) \quad \text{if } x \in \partial\Omega \text{ and } n \cdot n_x < 0, \quad (1.3)$$

where $n_x \in \mathbb{S}^2$ is the outer normal to the boundary at point x . However, we could consider a more general setting with the incoming boundary profile $g_v(t, x, n)$ depending also on $x \in \partial\Omega$.

In this paper we, will consider both the time-dependent and the stationary cases. Assuming $\Omega \subset \mathbb{R}^3$ bounded and convex and as initial values the bounded functions $I_0(x, n, \nu)$ and $T_0(x)$, we consider the following initial-boundary value problem

$$\begin{cases} \frac{1}{c} \partial_t I_v(t, x, n) + n \cdot \nabla_x I_v(t, x, n) = \alpha_v^a(x) (B_v(T(t, x)) - I_v(t, x, n)) \\ \quad + \alpha_v^s(x) \left(\int_{\mathbb{S}^2} K(n, n') I_v(t, x, n') dn' - I_v(t, x, n) \right) & x \in \Omega, n \in \mathbb{S}^2, t > 0 \\ \partial_t T + \frac{1}{c} \partial_t \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn I_v(t, x, n) \right) + \operatorname{div} \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn n I_v(t, x, n) \right) = 0 & x \in \Omega, n \in \mathbb{S}^2, t > 0 \\ I_v(0, x, n) = I_0(x, n, \nu) & x \in \Omega, n \in \mathbb{S}^2 \\ T(0, x) = T_0(x) & x \in \Omega \\ I_v(t, x, n) = g_v(t, n) & x \in \partial\Omega, n \cdot n_x < 0, t > 0 \end{cases} \quad (1.4)$$

and the following stationary boundary value problem

$$\begin{cases} n \cdot \nabla_x I_v(x, n) = \alpha_v^a(x) (B_v(T(x)) - I_v(x, n)) \\ \quad + \alpha_v^s(x) \left(\int_{\mathbb{S}^2} K(n, n') I_v(x, n') dn' - I_v(x, n) \right) & x \in \Omega, n \in \mathbb{S}^2 \\ \operatorname{div} \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn n I_v(n, x) \right) = 0 & x \in \Omega, n \in \mathbb{S}^2 \\ I_v(n, x) = g_v(n) & x \in \partial\Omega, n \cdot n_x < 0. \end{cases} \quad (1.5)$$

Problems like (1.4) and (1.5) or similar equations related to radiative transfer are often studied in the framework of the so-called diffusion approximation (see [42, 58]). This approximation is valid when the mean free path of the photons is much smaller than the macroscopic size of the system. However, the mean free path of the photons can be small because either the scattering mean free path or the absorption mean free path is smaller than the size of the system. The main consequence of that is that, depending on the ratio between the different mean free paths, the radiation intensity can be approximated by the Planck distribution, that is, $B_v(T)$, or it cannot be. The first case is denoted as equilibrium diffusion approximation, while the second one is referred to as non-equilibrium diffusion approximation. These concepts have been extensively discussed in the physical literature on radiation (cf. [42, 58]). The goal of this paper is to obtain a precise mathematical characterization of these concepts, specifically to derive

an accurate mathematical condition for the validity of the equilibrium diffusion approximation and to determine the regions where the equilibrium or non-equilibrium diffusion approximation holds for the specific problems (1.4) and (1.5). To this end, we will use perturbative methods and matched asymptotic expansions in order to study different scaling limits for the scattering and absorption mean free paths.

1.1. Scaling lengths and results

We study the solutions of the time-dependent and stationary radiative transfer equations (1.4) and (1.5) under different scaling limits, and we obtain suitable problems satisfied by the limit of the solutions of the original problems. For these problems, we will obtain either the equilibrium or the non-equilibrium diffusion approximation. To this end, we start defining some characteristic lengths.

We consider a convex domain $\Omega \subset \mathbb{R}^3$ with diameter of order 1 and such that the size of the domain is comparable in all directions of the space. Moreover, the characteristic macroscopic length L is assumed to be $L = 1$. We remark that many of the results obtained in this paper are also valid in a non-convex domain. However, in non-convex domains, we should also take into account the consequences of incoming radiation into cavities, an issue that we will not consider in this paper (see [30] for more details).

We will replace the absorption coefficient $\alpha_v^a(x)$ by

$$\frac{\alpha_v^a(x)}{\ell_A} \quad (1.6)$$

and the scattering coefficient $\alpha_v^s(x)$ by

$$\frac{\alpha_v^s(x)}{\ell_S}, \quad (1.7)$$

where now $\alpha_v^a(x) = \mathcal{O}(1)$ and $\alpha_v^s(x) = \mathcal{O}(1)$ are bounded by a constant of order one in both variables. We denote by ℓ_A the absorption length and by ℓ_S the scattering length. These are also the mean free paths of the absorption/emission processes and the scattering processes, respectively. In some physical applications, it is convenient to assume $\alpha_v^a(x)$ or $\alpha_v^s(x)$ to tend to zero for large or small frequencies ν . The exact dependence of these functions on ν will be made after. Roughly speaking, we have to assume that they have to decay not too fast in order to obtain that some integrals arising in the analysis are convergent.

In many technological applications, it can be assumed that $\alpha_v^s \ll \alpha_v^a$ (cf. [58]). However, there are also applications where the scattering plays a more important role than the absorption/emission process. This is the case, for example, in the analysis of planetary atmospheres (see [20, 45]).

Another important scaling length that we should consider is the Milne length, which is given by the minimum between absorption and scattering length,

$$\ell_M = \min\{\ell_A, \ell_S\}. \quad (1.8)$$

The Milne length can be considered to be the effective mean free path of the whole radiative process. The key feature of the Milne length is that at distances of order ℓ_M to the boundary, the radiation intensity becomes isotropic, that is, independent of the direction $n \in \mathbb{S}^2$. Since we are interested in the diffusion approximation, we assume in the rest of this paper $\ell_M \ll L = 1$.

Another length that plays a crucial role in the analysis of this paper is the quantity that we will denote as thermalization length, which is the geometrical mean of the absorption and the Milne length

$$\ell_T = \sqrt{\ell_A \ell_M}. \quad (1.9)$$

The thermalization length is the characteristic distance from the boundary at which the radiation intensity I_ν approaches the Planck equilibrium distribution of the temperature.

We now replace in (1.4) and (1.5) the absorption and scattering coefficients with the expressions in (1.6) and (1.7). The changes in the temperature take place in times of order

$$\tau_h = \frac{\ell_A}{\min\{\ell_T^2, 1\}} \gg 1,$$

which will be denoted as the heat parameter. Therefore, in order to obtain an equation that changes in times t of order 1, we will replace t by $\tau_h t$. Notice that, after this change of variable, the changes of times t of order 1 are associated with relevant changes of the temperature of order 1. We will use this notation throughout the paper; that is, we will denote by t the time after the change of variable. Hence, (1.4) writes using $L = 1$

$$\begin{cases} \frac{1}{c} \partial_t I_v(t, x, n) + \tau_h n \cdot \nabla_x I_v(t, x, n) = \frac{\alpha_v^a(x) \tau_h}{\ell_A} (B_v(T(t, x)) - I_v(t, x, n)) \\ \quad + \frac{\alpha_v^s(x) \tau_h}{\ell_S} \left(\int_{\mathbb{S}^2} K(n, n') I_v(t, x, n') dn' - I_v(t, x, n) \right) & x \in \Omega, n \in \mathbb{S}^2, t > 0 \\ \partial_t T + \frac{1}{c} \partial_t \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn I_v(t, n, x) \right) \\ \quad + \tau_h \operatorname{div} \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn n I_v(t, n, x) \right) = 0 & x \in \Omega, n \in \mathbb{S}^2, t > 0 \\ I_v(0, x, n) = I_0(x, n, v) & x \in \Omega, n \in \mathbb{S}^2 \\ T(0, x) = T_0(x) & x \in \Omega \\ I_v(t, n, x) = g_v(t, n) & x \in \partial\Omega, n \cdot n_x < 0, t > 0. \end{cases} \quad (1.10)$$

We will also consider the case where the speed of light is infinite, that is, $c = \infty$. This approximation is justified if the characteristic time for the temperature to change is much smaller than the time required for the light to cross the domain. In this case, the equation will be

$$\begin{cases} n \cdot \nabla_x I_v(t, x, n) = \frac{\alpha_v^a(x)}{\ell_A} (B_v(T(t, x)) - I_v(t, x, n)) \\ \quad + \frac{\alpha_v^s(x)}{\ell_S} \left(\int_{\mathbb{S}^2} K(n, n') I_v(t, x, n') dn' - I_v(t, x, n) \right) & x \in \Omega, n \in \mathbb{S}^2, t > 0 \\ \partial_t T + \tau_h \operatorname{div} \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn n I_v(t, n, x) \right) = 0 & x \in \Omega, n \in \mathbb{S}^2, t > 0 \\ T(0, x) = T_0(x) & x \in \Omega \\ I_v(t, n, x) = g_v(t, n) & x \in \partial\Omega, n \cdot n_x < 0, t > 0. \end{cases} \quad (1.11)$$

Similarly, the stationary problem (1.5) can be written as

$$\begin{cases} n \cdot \nabla_x I_v(x, n) = \frac{\alpha_v^a(x)}{\ell_A} (B_v(T(x)) - I_v(x, n)) \\ \quad + \frac{\alpha_v^s(x)}{\ell_S} \left(\int_{\mathbb{S}^2} K(n, n') I_v(x, n') dn' - I_v(x, n) \right) & x \in \Omega, n \in \mathbb{S}^2 \\ \operatorname{div} \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn n I_v(n, x) \right) = 0 & x \in \Omega, n \in \mathbb{S}^2 \\ I_v(n, x) = g_v(n) & x \in \partial\Omega, n \cdot n_x < 0. \end{cases} \quad (1.12)$$

It is important to remark that we assume $g_v(t, n)$ in (1.10) and (1.11) to change in times of order 1 after rescaling the time; that is, we assume the incoming radiation g_v to change in the same time scale as the one for meaningful changes of the temperature.

Notice that at first glance, the time τ_h does not seem to have units of time. However, we must take into account that since $L = 1$, omitted in all the equations, all quantities ℓ_A , ℓ_S , ℓ_M and ℓ_T are non-dimensional parameters that have to be understood as $\frac{\ell_A}{L}$, $\frac{\ell_S}{L}$, $\frac{\ell_M}{L}$ and $\frac{\ell_T}{L}$. In addition, we recall that we have chosen

Table 1. Main results

	$\ell_M = \ell_T \ll L$	$\ell_M \ll \ell_T \ll L$	$\ell_M \ll \ell_T = L$	$\ell_M \ll L \ll \ell_T$
Milne layer	Milne = Thermalization	Yes	Yes	Yes
Thermalization layer	Thermalization = Milne	Yes	\approx Bulk	No
Bulk	Equilibrium diffusion approximation	Equilibrium diffusion approximation	Transition from equilibrium to non-equilibrium approximation	Non-equilibrium diffusion approximation

a particular unit of time for which the heat capacity is $C = 1$. Hence, all the space and time variables appearing in (1.10)–(1.12) are non-dimensional. In Sections 4–6, we will see that the definition of the heat parameter, namely, τ_h , is motivated by the behaviour of the radiation intensity in the bulk, and it is the order of time in which the temperature changes.

There are three characteristic lengths in (1.10)–(1.12), namely, ℓ_A , ℓ_S and $L = 1$, and we can consider several relative scalings between them. Since $\ell_M \ll 1$ in the case of the diffusion approximation, the solutions can be described by means of different boundary layers. It turns out that the relative size and the structure of these boundary layers can be characterized using the relative scalings of ℓ_M (cf. (1.8)), ℓ_S (cf. (1.9)) and $L = 1$. In order to consider these different scalings, in the following sections, we will set for the equations (1.10), (1.11) and (1.12) $\ell_M = \varepsilon \ll 1$, and we will choose ℓ_A , ℓ_S and c as powers of ε .

Notice that the incoming radiation g_v to the boundary of Ω is not necessarily isotropic, and in general, it is different from the Planck distribution; that is, it is not in thermal equilibrium. This implies the onset (in principle) of two nested boundary layers near the boundary where the intensity I_v changes its behaviour. The thickness of these layers is ℓ_M and ℓ_T , respectively. In the first layer, which we call the Milne layer, the radiative intensity I_v becomes isotropic. In the latter, which we denote as the thermalization layer, I_v approaches the Planck distribution for a suitable temperature that has to be determined, and it is one of the unknowns of the problem. Notice moreover that, since by definition $\ell_M \leq \ell_T$, the Milne layer always appears before the thermalization layer. On the other hand, if ℓ_M is comparable to ℓ_T , both layers can coincide. It is worth noting that beyond the thermalization layer, the radiative intensity I_v is given by a Planck distribution. In the time-dependent problem, besides the formation of boundary layers, we observe the formation of initial layers in which the radiation intensity becomes isotropic or the equilibrium distribution, respectively.

Table 1 summarizes the behaviour of the solution (T, I_v) to the equations (1.10)–(1.12) for different scaling limits yielding equilibrium or non-equilibrium diffusion approximation. Moreover, for any considered regime, we observe the onset or not of Milne layers or thermalization layers. Finally, when ℓ_T is of the same order as the characteristic length L , the thermalization, that is, the transition of I_v to the equilibrium distribution $B_v(T)$, takes place in the bulk of the domain Ω .

The theory of the non-equilibrium diffusion approximation of the radiative transfer equation is particularly relevant in astrophysical situations. The most extreme scenario takes place when the thermalization processes are so slow that it is not possible to define a macroscopic temperature at each point. This situation, which will not be considered in this paper, is known as non-local thermal equilibrium (cf. [29, 45]), and it takes place for very rarefied gases.

Nevertheless, the non-equilibrium diffusion approximation can also occur in cases in which the local thermal equilibrium holds. This is the situation considered in this article. As given in Section 6.5 (83) in [42] and in Sections 4.2.3 and 4.3 in [50], when the scattering process is much more important than the emission-absorption process, the radiation intensity converges, as the mean free paths of the photons tends to zero, to the Planck distribution at distances from the boundary of the order of the thermalization

length ℓ_T . In particular, if ℓ_T is much larger than the characteristic size of the domain, the radiation intensity does not approach $B_\nu(T)$ at any point. Specific astrophysical situations where this happens are hot stellar atmospheres where scattering is the leading radiation process (cf. [42]).

Moreover, the parameter regimes considered in this paper have significant applications in the description of the behaviour of the temperature in the upper part of the atmosphere. We emphasize that the main aim of this article is the classification of the situations in which equilibrium or non-equilibrium diffusion approximation holds and the formal derivation of the limit equations describing these approximations.

1.2. Revision of the literature

The problem concerning the distribution of temperature of a material interacting with electromagnetic waves is not only a relevant question in many physical applications, but it is also the source of several interesting mathematical problems. The radiative transfer equation is the kinetic equation describing the interaction of photons with matter. Its derivation and its main properties are explained in [10, 42, 45, 50, 58]. In particular, the validity of the diffusion approximation and a discussion of the situations where the radiation intensity is expected to be or not to be given approximately by the Planck distribution are considered in [42, 58].

Starting from the seminal work of Compton [11], the interaction of matter and radiation has been widely studied both in the physical and mathematical literature. Some of the early results can be found in the paper of Milne [43], who considered a simplified model of monochromatic radiation depending only on one space variable.

When considering the diffusion approximation of the radiative transfer equation, a boundary layer near the boundary appears in which the distribution of radiation becomes isotropic. The specific equation describing this layer involves a radiative transfer equation depending on one space variable, whose details depend on the problem under consideration. This class of problems is known in the mathematical literature as Milne problems, and they have been extensively studied at least for some particular choices of α_ν^a and α_ν^s .

While it is difficult to find explicit solutions of the radiative transfer equation, in the case of a small photon's mean free path (i.e. in the diffusion approximation), this problem reduces to an elliptic (in the stationary case) or a parabolic (in the time-dependent case) problem. The mathematical properties of these problems are much better understood than the properties of the non-local radiative transfer equation (1.1). Due to this, the diffusion approximation of the radiative transfer equation has been studied in great detail.

Before discussing the currently available mathematical results about the diffusion approximation and the Milne problems, it is worth introducing an equation that is closely related to the radiative transfer equation (1.1). In the absence of emission-absorption processes, that is, when $\alpha_\nu^a = 0$, and when α_ν^s is independent of the frequency ν the radiative transfer equation (1.1) reduces to

$$\partial_t u(t, x, n) + n \cdot \nabla_x u(t, x, n) = \alpha(x) \left(\int_{\mathbb{S}^2} K(n, n') u(t, x, n') dn' - u(t, x, n) \right), \quad (1.13)$$

where $u = \int_0^\infty I_\nu(t, x, n) d\nu$. This equation is mathematically identical to the one-speed neutron transport equation. Moreover, in the stationary case, the radiative transfer equation reduces to (1.13) also in the presence of absorption-emission processes if both α^a and α^s are independent of the frequency. The case where both absorption and scattering coefficients are independent of the frequency is usually denoted in the literature as the grey approximation. Therefore, the one-speed neutron transport equation and the radiative transfer equation for the grey approximation are mathematically equivalent. See [12] for more details. As a matter of fact, the neutron transport equation, especially its diffusion approximation, was largely studied in the late 1970s. The reason is that this problem is important in order to determine the critical size for neutron transport, that is, the smallest size of the system for which the scattering eigenvalue problem has a stable solution. This is relevant in nuclear reactor engineering. For more details about this issue, we refer to [12].

In several articles [23, 35–40], Larsen and several coauthors studied many properties of the neutron transport equation and its diffusion approximation. Moreover, in [41], the authors studied via asymptotic analysis the diffusion approximation of the radiative transfer equation for both absorption and scattering taking as initial and boundary value the Planck distribution. This choice of boundary data simplifies the treatment of the problem because no boundary layers or initial transport problems arise at least to the leading order.

To the best of our knowledge, the first mathematically rigorous article about the diffusion approximation for the neutron transport equation is [9]. In that article, the authors studied equation (1.13) under different boundary conditions including also the absorbing boundary condition that we are considering in (1.3). In particular, using probabilistic methods, they studied the Milne problem arising for the boundary layers and proved the convergence of the solution of the original neutron transport equation to the solution of a diffusive problem. Moreover, the scattering kernel considered is assumed to be strictly positive, bounded and rotationally symmetric.

More recently, Guo and Wu studied in a series of papers [28, 54–57] both the stationary and time-dependent diffusion approximation for the neutron transport equation with a constant scattering kernel and a constant scattering coefficient. They proved rigorously the convergence to such a diffusion problem computing also a geometric correction for the boundary layer. Their method is based on the derivation of suitable $L^2 - L^p - L^\infty$ estimates, a method that has been extensively used in the study of kinetic equations (cf. [27, 31]).

The mathematical theory of the radiative transfer equation has also been extensively studied. The well-posedness and the diffusion approximation for the time-dependent problem without scattering have been studied using the theory of m -accretive operators in [4–6].

In a recent paper [16], we developed an alternative method to derive the equilibrium diffusion approximation starting with the stationary radiative transfer equation. Specifically, in [16], the grey approximation and the case of absence of scattering are considered. The procedure developed in [16] consists of reformulating the problem (1.12) as a non-local elliptic equation for the temperature for which maximum principle techniques are applicable.

As indicated before, an important class of problems, which need to be studied in order to derive the boundary condition for the diffusion approximation, are the Milne problems.

In the case of pure absorption, namely, when $\alpha_v^* = 0$, the well-posedness for the Milne problem can be found, for instance, in [25] and also in [16] using different methods. In particular, in [25], well-posedness is shown for a very large class of absorption coefficients.

In the case of pure scattering, radiative transfer equation for the grey approximation (equivalently the neutron transport equation), the well-posedness of the Milne problem has been studied in [7, 9]. More recently, geometric corrections to the solution of the Milne problem have been obtained in [28, 54–57].

To our knowledge, the only example of the Milne problem involving both emission/absorption and scattering has been studied in [51]. The case considered in this paper is that of a constant scattering kernel and constant scattering coefficient and a more general absorption coefficient. The proof relies on the accretiveness of the operators used, similar to the Perron method applied to solve boundary value problems for elliptic equations.

It is finally worth mentioning that also for other kinetic equations, such as the Boltzmann equation, the diffusion limit and hence the boundary layer equations have been studied. The equations describing the boundary layers are also often denoted in the literature by Milne problems (see, for instance, [8, 17–19]).

Besides the studies about the diffusion approximation, the radiative transfer equation has been analysed in numerous works. In recent times, there has been a growing interest in the study of problems involving the radiative transfer equation in different contexts. The well-posedness of the stationary equation (1.5) has been considered in [14, 30]. The authors proved the existence of solutions to the stationary radiative transfer equation with or without scattering in the cases of constant coefficients, coefficients depending on the frequency but not on the temperature of the system and finally, coefficients depending on both the frequency and the temperature of the particular form $\alpha_v(T) = Q(v)\alpha(T)$.

Finally, the radiative transfer equation has also been considered for more complicated interactions between matter and photons. We refer to [24, 26, 42, 58] for problems concerning the interaction of matter with radiation in a moving fluid. For the study of the interaction of electromagnetic waves with a Boltzmann gas whose molecules have different energy levels, we refer to [13, 29, 45, 49]. Several authors considered problems where the heat is transported in a body by means of both radiation and conduction; we refer to [21, 22, 33, 34, 46, 52, 53]. Finally, homogenization problems in porous and perforated domains where the heat is transported by conduction, radiation and possibly also convection are studied in [1–3, 32, 48]. Specifically, in [48], the authors applied the method of multiple scales to a homogenization problem describing the heat transport in a porous medium. The heat transport is assumed to be due to the conduction in the solid part of the material and due to the radiation in the gas-filled cavities.

Derivations of the scattering kernel for the radiative transfer equation, taking as starting point the Maxwell equations, has also been extensively studied in [44].

1.3. Structure of the paper

The paper is organized as follows. In Section 2, we will study some of the mathematical properties of the scattering operator and of the absorption-emission process appearing in the radiative transfer equation. We will then proceed to the derivation of the limit problems in the diffusion approximation under different scaling limits. In Section 3, we consider the stationary diffusion approximation for the radiative transfer equation, and we derive, using the method of matched asymptotic expansions, the new limit boundary value problem as well as the boundary layer equations. Moreover, we will see for which choice of characteristic lengths the equilibrium diffusion approximation holds and for which ones it fails. We will then proceed with the study of the time-dependent diffusion approximation, for which we will use again the method of matched asymptotic expansions. In Section 4, the focus is on the case of infinite speed of light (i.e. instantaneously transport of the radiation in the domain), namely, on the problem (1.11). Besides the construction of the limit problems and their classification as equilibrium and non-equilibrium diffusion approximations, we will also derive the initial layer and initial-boundary layer equations. In Section 5 and in Section 6, we proceed similarly to Section 4 studying first the time-dependent diffusion approximation in the case of finite speed of light, that is, speed of light of order one (cf. Section 5), and later in the case where the speed of light is assumed to scale like a power law $c = \varepsilon^{-\kappa}$ for $\kappa > 0$ and $\varepsilon = \ell_M$ (cf. Section 6).

2. Preliminary results

In this section, we collect some properties of the scattering operator and absorption operator that will be used later in the analysis of the diffusion approximation.

2.1. Properties of the scattering operator

Before deriving suitable diffusion approximations according to the different values of ℓ_M and ℓ_T , we describe some properties of the scattering kernel and of the scattering operator.

We consider throughout the paper the kernel $K \in C(\mathbb{S}^2 \times \mathbb{S}^2)$ to be non-negative and satisfying $\int_{\mathbb{S}^2} K(n, n') dn = 1$. We also assume in the whole article that the kernel K is invariant under rotations, that is,

$$K(n, n') = K(\mathcal{R}n, \mathcal{R}n') \quad \text{for all } n, n' \in \mathbb{S}^2 \text{ and for any } \mathcal{R} \in SO(3).$$

Moreover, for any $n, \omega \in \mathbb{S}^2$, we define by $\mathcal{R}_{n,\omega} \in SO(3)$ the rotation of π around the bisectrix of the angle between n and ω lying in the plane containing both vectors. This rotation satisfies $\mathcal{R}_{n,\omega}(n) = \omega$

and $\mathcal{R}_{n,\omega}(\omega) = n$. As shown in [14], this implies that the scattering kernel K is symmetric. Notice that this is not true in two dimensions unless we assume K to be invariant also under reflections.

We define the scattering operator as the bounded linear operator given by

$$H: L^\infty(\mathbb{S}^2) \rightarrow L^\infty(\mathbb{S}^2)$$

$$\varphi \mapsto H[\varphi] = \int_{\mathbb{S}^2} K(\cdot, n') \varphi(n') \, dn'. \quad (2.1)$$

With this notation, we can formulate the following proposition, which contains the most important properties of the scattering operator.

Proposition 2.1. *Let $K \in C(\mathbb{S}^2 \times \mathbb{S}^2)$, invariant under rotations, non-negative and satisfying*

$$\int_{\mathbb{S}^2} K(n, n') \, dn = 1.$$

Assume $\varphi \in L^\infty(\mathbb{S}^2)$ satisfies $H[\varphi] = \varphi$. Then

- (i) φ is continuous,
- (ii) φ is constant,
- (iii) $\text{Ran}(Id - H) = \{\varphi \in L^\infty(\mathbb{S}^2): \int_{\mathbb{S}^2} \varphi = 0\}$.

The proof of Proposition 2.1 can be found in Appendix A. A direct consequence of Proposition 2.1 is the following proposition for a continuous scattering kernel $K \in C(\mathbb{S}^2 \times \mathbb{S}^2 \times \Omega \times \mathbb{R}_+)$ invariant under rotations for each pair (x, v) .

Proposition 2.2. *Let $K \in C(\mathbb{S}^2 \times \mathbb{S}^2 \times \Omega \times \mathbb{R}_+)$. For any $x, v \in \Omega \times \mathbb{R}_+$, we define $K_{x,v}(n, n') = K(n, n', x, v)$. Assume that for any $x, v \in \Omega \times \mathbb{R}_+$, the kernel $K_{x,v}$ is invariant under rotations, is non-negative and satisfies $\int_{\mathbb{S}^2} K_{x,v}(n, n') \, dn = 1$. Then the following holds.*

- (i) *For any $x, v \in \Omega \times \mathbb{R}_+$ and $n, \omega \in \mathbb{S}^2$, there exist finitely many $n_1, \dots, n_N \in \mathbb{S}^2$ such that (A.1) holds for $K_{x,v}$;*
- (ii) *if $\varphi \in L^\infty(\mathbb{S}^2 \times \Omega \times \mathbb{R}_+)$ satisfies $H[\varphi] = \varphi$, then φ is continuous, and it is constant for every $x, v \in \Omega \times \mathbb{R}_+$,*
- (iii) *$\text{Ran}(Id - H) = \{\varphi(\cdot, x, v) \in L^\infty(\mathbb{S}^2): \int_{\mathbb{S}^2} \varphi(n, x, v) \, dn = 0\}$ for every $x, v \in \Omega \times \mathbb{R}_+$.*

Proof. Apply Proposition 2.1 to the continuous kernel $K_{x,v}$. □

Remark. In the following sections, we will consider the diffusion approximation for scattering kernels K independent of $x \in \Omega$ and $v \geq 0$. However, under the assumptions of Proposition 2.2, the same results would apply for more general kernels depending continuously on x and v .

Remark. The assumption of K being invariant under rotations is crucial for the validity of Proposition 2.1 and Proposition 2.2. Consider, for example, the following continuous function

$$k(n) = \frac{2}{3\pi} \left(\chi_{\{|n \cdot e_3| \leq \frac{1}{4}\}}(n) + (2 - 4|n \cdot e_3|) \chi_{\{\frac{1}{4} < |n \cdot e_3| < \frac{1}{2}\}}(n) \right).$$

Then the kernel $K(n, n') = k(n) \chi_{\mathbb{S}^2}(n')$ is continuous in both variables, is non-negative and satisfies

$$\int_{\mathbb{S}^2} K(n, n') \, dn = \int_{\mathbb{S}^2} k(n) \, dn = 1.$$

However, K is not invariant under rotations. This kernel describes the scattering properties of a non-isotropic medium. It is easy to see that in this case $H[c](n) = ck(n)$, for $c \in \mathbb{R}$. Hence, the constant functions are not a solution to $H[\varphi] = \varphi$. Actually, all solutions of $H[\varphi] = \varphi$ satisfy $\varphi(n) = k(n) \int_{\mathbb{S}^2} \varphi(n') \, dn'$ and have hence the form $\varphi = \lambda k$, where $\lambda \in \mathbb{R}$ is an arbitrary constant. Therefore, the subspace of eigenvectors of H with eigenvalue 1 is one-dimensional.

Remark. As we noticed above, in two dimensions, the invariance under rotations of K does not imply directly its symmetry under reflections. However, it is still possible to show that the only eigenfunctions of H with eigenvalue 1 are the constants. To check this, we recall the well-known fact that the one-dimensional sphere \mathbb{S}^1 can be parameterized by $\theta \in [0, 2\pi)$. Moreover, we can assume without loss of generality that any scattering kernel K invariant under rotations has the form $K(n, n') = K(\theta(n) - \theta(n'))$. Let $f \in L^\infty(\mathbb{S}^1)$ be an eigenfunction with eigenvalue 1 for H . We then see

$$\int_0^{2\pi} K(\theta - \varphi) f(\varphi) d\varphi = f(\theta).$$

This equation can be solved using the Fourier series. We hence obtain the following identity for the Fourier coefficients

$$\hat{f}(n) \left(1 - 2\pi \hat{K}(n)\right) = 0. \quad (2.2)$$

For $n = 0$ we have $\hat{K}(0) = \frac{1}{2\pi} \int_0^{2\pi} K(\theta) d\theta = \frac{1}{2\pi}$. On the other hand, we obtain for $n \neq 0$

$$|\hat{K}(n)| < \frac{1}{2\pi} \int_0^{2\pi} K(\theta) d\theta = \frac{1}{2\pi}.$$

Therefore, the identity (2.2) is satisfied if and only if $\hat{f}(n) = 0$ for all $n \neq 0$. This implies that f is constant.

2.2. Relation between the temperature and the radiation intensity

We derive here an identity that relates temperature and radiation intensity and that will be repeatedly used in the stationary problem, for instance, in the stationary boundary layer equations.

Using the identity $\operatorname{div} \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn n I_v(x, n) \right) = \int_0^\infty dv \int_{\mathbb{S}^2} dn n \cdot \nabla_x I_v(x, n)$ and plugging the first equation of (1.5) into the second one, we see that we have

$$\int_0^\infty dv \int_{\mathbb{S}^2} dn \alpha_v^a(x) (B_v(T(x)) - I_v(x, n)) = 0, \quad (2.3)$$

where we also used the fact that the integral over the sphere \mathbb{S}^2 of the scattering term is 0 due to the symmetry of the kernel K . With this identity, we can recover the value of the temperature given the radiation intensity. Let us define by $F: \mathbb{R}_+ \times \Omega \rightarrow \mathbb{R}_+$ the following function

$$F(T, x) = \int_0^\infty \alpha_v^a(x) B_v(T) dv. \quad (2.4)$$

Since B_v is monotone in T , the function $F(\cdot, x)$ is invertible. Hence, (2.3) implies that

$$T(x) = F^{-1} \left(\left(\int_0^\infty dv \int_{\mathbb{S}^2} dn \alpha_v^a(x) I_v(x, n) \right), x \right), \quad (2.5)$$

where F^{-1} is the inverse with respect to the first variable; that is, $F(T, x) = \xi$ implies $T = F^{-1}(\xi, x)$. Equations (2.3) and (2.5) will appear often in the following sections, in particular in the study of the boundary layers.

3. The stationary diffusion approximation: different scales

We first study the stationary diffusion regime for different scalings. We consider (1.12) for α_v^a and α_v^s strictly positive and bounded. Moreover, in the diffusion regime, we have $\ell_M \ll 1$. Hence, in (1.12), we assume $\ell_M = \min\{\ell_A, \ell_S\} = \varepsilon$. Moreover, we impose $\ell_A = \varepsilon^{-\beta}$ and $\ell_S = \varepsilon^{-\gamma}$, for suitable choices of $\gamma, \beta \geq -1$ with $\min\{\gamma, \beta\} = -1$. Notice that at least one of β and γ is negative. This choice of ℓ_A and ℓ_S as an inverse power law of $\varepsilon > 0$ for $\beta, \gamma \geq -1$ will be convenient in order to make the computations

simpler in the following subsections. Under these assumptions, we rewrite equation (1.12) as

$$\begin{cases} n \cdot \nabla_x I_v(x, n) = \varepsilon^\beta \alpha_v^a(x) (B_v(T(x)) - I_v(x, n)) \\ \quad + \varepsilon^\gamma \alpha_v^s(x) \left(\int_{\mathbb{S}^2} K(n, n') I_v(x, n') dn' - I_v(x, n) \right) & x \in \Omega, n \in \mathbb{S}^2 \\ \operatorname{div} \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn n I_v(n, x) \right) = 0 & x \in \Omega, n \in \mathbb{S}^2 \\ I_v(n, x) = g_v(n) & x \in \partial\Omega, n \cdot n_x < 0. \end{cases} \quad (3.1)$$

Moreover, we assume the scattering kernel $K \in C(\mathbb{S}^2 \times \mathbb{S}^2)$ to be invariant under rotations, non-negative and with $\int_{\mathbb{S}^2} K(n, n') dn = 1$. We consider also $\Omega \subset \mathbb{R}^3$ to be a bounded convex domain with C^1 -boundary. For $x \in \partial\Omega$, we denote by $n_x \in \mathbb{S}^2$ the outer normal to the boundary at x .

Before describing in detail the limit diffusion problems for the different choices of scaling parameters, we shortly explain how we will use the method of matched asymptotic expansions to derive the limit problems for each case. In order to find the limit problem valid in the bulk, the so-called outer problem, we expand the radiation intensity as

$$I_v(x, n) = \phi_0(x, n, v) + \sum_{k \geq 0} \varepsilon^{\delta+k} \psi_{k+1}(x, n, v) + \sum_{l \geq 0} \varepsilon^l \phi_l(x, n, v) \quad (3.2)$$

for a suitable $\delta > 0$ depending on the choice of the scaling parameters. To be more precise,

$$\delta = \begin{cases} \gamma + 1 & \text{if } \beta = -1 \text{ (i.e. } \ell_A = \ell_M), \\ \beta - \lfloor \beta \rfloor & \text{if } \gamma = -1 \text{ (i.e. } \ell_S = \ell_M). \end{cases} \quad (3.3)$$

We remark that if $-1 < \beta < 0$, by our definition, $\delta = \beta + 1 > 0$. The choice of δ in (3.2) is due to the following observations. If $\ell_A = \ell_M$, the leading term of the radiative transfer equation is the emission-absorption term, so that

$$\alpha_v^a(x)(I_v(x, n) - B_v(T(x))) = \varepsilon n \cdot \nabla_x I_v(x, n) - \alpha_v^s(x) \varepsilon^{\gamma+1} (H - Id)[I_v(x, \cdot)](n),$$

where we used the notation of (2.1). Therefore, it is natural to look for a solution of this equation in form of a series of powers of ε with exponents 1 and $\gamma + 1$. On the other hand, if $\ell_S = \ell_M$, the leading term is the scattering term yielding

$$\alpha_v^s(x)(H - Id)[I_v(x, \cdot)](n) = \varepsilon n \cdot \nabla_x I_v(x, n) - \varepsilon^{\beta+1} \alpha_v^a(x)(I_v(x, n) - B_v(T(x))).$$

As we have seen in Proposition 2.1, the solvability of this equation requires to impose a compatibility condition on the right-hand side. More precisely, $(Id - H)$ is invertible in the space of functions with $\int_{\mathbb{S}^2} f(n) dn = 0$. This compatibility condition is provided by the transport term $\varepsilon n \cdot \nabla_x I_v(x, n)$. In particular, the relevant feature is that the problem

$$\alpha_v^s(x)(H - Id)[I_v(x, \cdot)](n) - \varepsilon n \cdot \nabla_x I_v(x, n) = f(x, n, v) \quad (3.4)$$

is not solvable if $\varepsilon = 0$, unless $\int_{\mathbb{S}^2} f(x, n, v) dn = 0$. On the contrary, in the case of $\varepsilon > 0$ and small, it turns out that problem (3.4) can be solved for general f . However, the solution becomes of the order $\varepsilon^{-2} \|f\|_\infty$. This explains why we have to add terms much larger than $\varepsilon^{\beta+1}$ in the expansion (3.2) for $\beta > 0$. We remark that the expansion (3.2) is also used in the time-dependent case. There, the value of δ when $\ell_S = \ell_M$ is justified by the behaviour of the radiation intensity for smaller time scales and by the need to impose this orthogonality condition.

Having expansion (3.2), we proceed by plugging it into the boundary value problem (1.12), and we compare all terms of the same order of magnitude. In this way, we will obtain different diffusive equations solved by ϕ_0 in the interior of Ω that will yield the leading order of the radiation intensity I_v .

However, to solve the resulting equation for ϕ_0 , we need some boundary condition whose derivation requires to analyse boundary layer equations for (3.1). The resulting boundary layer problems are related to the description of the radiation intensity in the regions close to the boundary. The thickness of these

layers is given by the Milne length and the thermalization length. Therefore, we will rescale the space variable according to ℓ_M and to ℓ_T , and we will analyse the resulting one-dimensional problems.

The matching between the outer and the inner solutions will provide the boundary condition for the equation satisfied in the bulk.

3.1. Case 1.1: $\ell_M = \ell_T \ll \ell_S$ and $L = 1$. *Equilibrium approximation*

Since we set $\ell_M = \varepsilon \ll 1$, the case $\ell_M = \ell_T \ll \ell_S$ arises when $\ell_A = \varepsilon$ (i.e. $\beta = -1$) and $\ell_S = \varepsilon^{-\gamma}$ for $\gamma > -1$. Notice that in this case ℓ_S could be small, namely, $\ell_S \ll L = 1$, but also large, for example, if $\gamma > 0$.

In order to find the outer problem, we choose $\delta = \gamma + 1$, and we substitute (3.2) into the first equation in (3.1), and we identify all terms with the same power of ε , that is, ε^{-1} , ε^γ (if $-1 < \gamma < 0$) and ε^0 . If $-1 < \gamma < 0$, the terms of order ε^{-1} give

$$0 = \alpha_v^a(x)(B_v(T(x)) - \phi_0(x, n, v)).$$

Hence, the leading order satisfies $\phi_0(x, n, v) = B_v(T(x))$, where B_v is the Planck distribution, which is independent of $n \in \mathbb{S}^2$. This corresponds to the diffusion equilibrium approximation, since in the interior, the radiation intensity is at the leading order the equilibrium Planck distribution.

The terms of order ε^γ imply $\psi_1 = 0$. Indeed, since $\phi_0(x, n, v) = B_v(T(x))$ is independent of $n \in \mathbb{S}^2$, we have $\int_{\mathbb{S}^2} K(n, n') \phi_0(x, v) dn' - \phi_0(x, v) = 0$, so that

$$\alpha_v^a \psi_1(x, n, v) = \int_{\mathbb{S}^2} K(n, n') \phi_0(x, v) dn' - \phi_0(x, v) = 0.$$

Finally, we compare all terms of order ε^0 . In this case, we have

$$n \cdot \nabla_x B_v(T(x)) = -\alpha_v^a(x) \phi_1(x, n, v),$$

where in the case $\gamma = 0$, we used again that $(H - Id) B_v(T) = 0$.

Therefore, we obtain the following expansion for I_v

$$I_v(x, n) = B_v(T(x)) - \varepsilon \frac{1}{\alpha_v^a(x)} n \cdot \nabla_x B_v(T(x)) + \dots, \quad (3.5)$$

where $T(x)$ is a function, which is at this stage still unknown.

We now plug (3.5) into the second equation of (3.1). The term of order ε^0 cancels out because $B_v(T)$ is isotropic, hence

$$\operatorname{div} \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn n B_v(T(x)) \right) = 0.$$

We find that the leading term is the one of order ε^1 , and we obtain

$$\operatorname{div} \left(\int_0^\infty dv \frac{1}{\alpha_v(x)} \left(\int_{\mathbb{S}^2} dn n \otimes n \right) \nabla_x B_v(T(x)) \right) = 0.$$

Finally, using that $\int_{\mathbb{S}^2} n \otimes n dn = \frac{4\pi}{3} Id$, we conclude that the limit problem solved at the interior by T is

$$\operatorname{div} \left(\int_0^\infty \frac{\nabla_x B_v(T(x))}{\alpha_v(x)} dv \right) = 0. \quad (3.6)$$

In order to obtain the behaviour of I_v close to the boundary $\partial\Omega$, we now derive a boundary value problem that can be written in a single variable. This boundary layer equation is known in the literature as the Milne problem. The matching of the solution of the Milne problem with the outer solution will provide the boundary value for the equation (3.6) solved by the temperature T .

We take $p \in \partial\Omega$. Assuming that near the boundary the radiation intensity and the temperature only depend on the distance to the boundary, we can further assume that they depend only on the distance

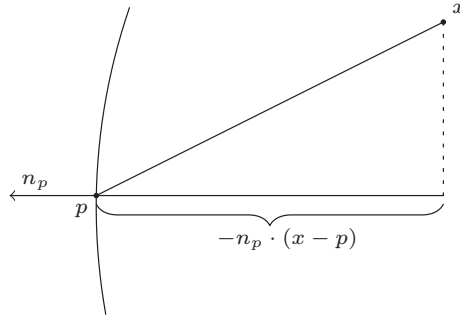


Figure 1. Representation of the change of variables.

to the boundary in direction n_p . This is possible due to the smallness of the thickness of the boundary layer and the continuity of α . We hence define for $x \in \Omega$ in a neighbourhood of p the new scalar rescaled variable

$$y = -\frac{x-p}{\varepsilon} \cdot n_p. \quad (3.7)$$

We recall that $-(x-p) \cdot n_p$ is non-negative, since $x-p$ points in the interior of the domain, and it is exactly the length of the cathetus with endpoint p of the triangle having as hypotenuse $x-p$ (cf. Figure 1).

Defining $\mathcal{R}_p(x) = \text{Rot}_p(x-p)$ as a rigid motion mapping p to zero with $\text{Rot}_p(n_p) = -e_1$, we see that we can also write y as the first component of $y_1 = \mathcal{R}_p\left(\frac{x-p}{\varepsilon}\right)_1$. Hence, as $\varepsilon \rightarrow 0$, we obtain that both the absorption and the scattering coefficients satisfy $\alpha_v^j(x) = \alpha_v^j\left(\varepsilon \text{Rot}_p(x) + p\right) \rightarrow \alpha_v^j(p), j \in \{a, s\}$.

We can now write the one-dimensional problem obtained by this new scaling and by the limit $\varepsilon \rightarrow 0$. Since $\varepsilon^{\nu+1} \rightarrow 0$ as $\varepsilon \rightarrow 0$, the scattering term is negligible, and we obtain for any $p \in \partial\Omega$

$$\begin{cases} -(n \cdot n_p) \partial_y I_v(y, n; p) = \alpha_v^a(p)(B_v(T(y, p)) - I_v(y, n; p)) & y > 0, n \in \mathbb{S}^2 \\ \text{div} \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn (n \cdot n_p) I_v(y, n; p) \right) = 0 & y > 0, n \in \mathbb{S}^2 \\ I_v(0, n; p) = g_v(n) & n \cdot n_p < 0. \end{cases} \quad (3.8)$$

The Milne equation (3.8) is the equation describing the boundary layer for the diffusion approximation. In the pure absorption case, the Milne problem was rigorously studied in [25]. The well-posedness of (3.8) is shown there for constant absorption coefficients and also for coefficients depending only on the frequency ν , as well as for coefficients depending on both frequency and temperature of the form $\alpha_v^a(p) = Q(\nu)\alpha(T(p))$. Moreover, the asymptotic behaviour of I_v at infinity has also been computed in this paper. It is indeed shown in [25] that as $y \rightarrow \infty$, the solution of the Milne problem converges to the Planck distribution, that is,

$$\lim_{y \rightarrow \infty} I_v(y, n; p) = I_v^\infty(p) = B_v(T_\infty(p)),$$

for some $T_\infty(p)$ depending only on g_v and p . Notice that $I_v^\infty(p)$ is independent of $n \in \mathbb{S}^2$.

Moreover, since in this case the thermalization length and the Milne length are the same, this is the only boundary layer appearing. The radiation intensity I_v becomes simultaneously isotropic and at equilibrium $B_v(T)$ in the same length scale. This gives a matching condition for the temperature that has to be used as a boundary condition for the new limit problem. In particular, the temperature and the radiation intensity solving the Milne problem (3.8) are related by equation (2.3). In particular,

$$T_\infty(p) = \lim_{y \rightarrow \infty} F^{-1} \left(\left(\int_0^\infty dv \alpha_v^a(p) I_v^\infty(p) \right), p \right), \quad (3.9)$$

where F is defined in (2.4) and $g \mapsto I_v^\infty(p)$ is a functional that determines the limit intensity for each boundary point $p \in \partial\Omega$.

Summarizing, the limit problem for the stationary radiative transfer equation (1.12) in the case $\ell_M = \ell_T \ll \ell_S$ is given by the following boundary value problem

$$\begin{cases} \operatorname{div} \left(\int_0^\infty \frac{\nabla_x B_v(T(x))}{\alpha_v(x)} dv \right) = 0 & x \in \Omega \\ T(p) = T_\infty(p) & p \in \partial\Omega, \end{cases}$$

where $T_\infty(p)$ is given by (3.9).

3.2. Case 1.2: $\ell_M = \ell_T = \ell_S \ll L$. *Equilibrium approximation*

Due to the definitions $\ell_M = \varepsilon \ll 1$ and $\ell_T = \sqrt{\ell_A \ell_M}$, we have $\ell_M = \ell_S = \ell_T = \ell_A = \varepsilon$ in (1.12), that is, $\beta = \gamma = -1$ in (3.1).

We consider the expansion (3.2) for $\delta = 0$, or equivalently without the expansion $\sum_{k \geq 0} \varepsilon^{\delta+k} \psi_{k+1}$. We plug (3.2) into (3.1), and we compare all terms of the same power of ε , namely, ε^{-1} and ε^0 . The term of order ε^{-1} yields

$$0 = \alpha_v^a(x)(B_v(T(x)) - \phi_0(x, n, \nu)) + \alpha_v^s(x) \left(\int_{\mathbb{S}^2} K(n, n') \phi_0(x, n', \nu) dn' - \phi_0(x, n, \nu) \right). \quad (3.10)$$

Notice that $\phi_0(x, n, \nu) = B_v(T(x))$ is a solution to (3.10). This follows from Proposition 2.1 and the isotropy of $B_v(T)$. We show now that the solution to (3.10) is unique.

To this end, for every $x \in \mathbb{R}^3$ and $\nu > 0$, we define $0 < \theta_{\nu,x} = \frac{\alpha_v^s(x)}{\alpha_v^a(x) + \alpha_v^s(x)} < 1$. Moreover, we also define the following operator, which maps for every fixed x, ν non-negative continuous functions to non-negative continuous functions and which is given by

$$A_{\nu,x}[\varphi](n) = \theta_{\nu,x} \int_{\mathbb{S}^2} K(n, n') \varphi(n') dn'. \quad (3.11)$$

Then equation (3.10) can be rewritten as

$$\phi_0(x, n, \nu) = A_{\nu,x}[\phi_0](x, n, \nu) + \frac{\alpha_v^a(x)}{\alpha_v^a(x) + \alpha_v^s(x)} B_v(T(x)). \quad (3.12)$$

Since the maps $\phi_0 \mapsto A_{\nu,x}(\phi_0)$ is a linear contraction, the Banach fixed-point theorem implies that (3.12) has a unique solution for every $T(x) \in \mathbb{R}_+$. Hence, $\phi_0 = B_v(T)$. Therefore, in this case, we also recover the equilibrium diffusion approximation.

We turn now to the terms of order ε^0 . In this case, we have

$$n \cdot \nabla_x B_v(T(x)) = -\alpha_v^a(x) \phi_1(x, n, \nu) - \alpha_v^s(x) \left(\int_{\mathbb{S}^2} K(n, n') \phi_1(x, n', \nu) dn' - \phi_1(x, n, \nu) \right).$$

Then, using the operator $A_{\nu,x}$ defined as in (3.11), we can rewrite this equation as

$$-\frac{1}{\alpha_v^a(x) + \alpha_v^s(x)} n \cdot \nabla_x B_v(T(x)) = (Id - A_{\nu,x}) \phi_1(x, n, \nu). \quad (3.13)$$

The same argument as for the term of order ε^{-1} holds also in this case, and the Banach fixed-point theorem ensures the existence of a unique solution to (3.13) given by

$$\phi_1(x, n, \nu) = -\frac{1}{\alpha_v^a(x) + \alpha_v^s(x)} (Id - A_{\nu,x})^{-1} (n \cdot \nabla_x B_v(T(x))),$$

where for any x, v , we used the notation

$$(Id - A_{v,x})^{-1}(n) = \begin{pmatrix} (Id - A_{v,x})^{-1}(n_1) \\ (Id - A_{v,x})^{-1}(n_2) \\ (Id - A_{v,x})^{-1}(n_3) \end{pmatrix},$$

which is well-defined due to the action of the linear operator $A_{v,x}$ only on the variable $n \in \mathbb{S}^2$.

Hence, we obtain the following expansion

$$I_v(x, n) = B_v(T(x)) - \varepsilon \frac{1}{\alpha_v^a(x) + \alpha_v^s(x)} (Id - A_{v,x})^{-1}(n) \cdot \nabla_x B_v(T(x)) + \varepsilon^2 \phi_2 + \dots \quad (3.14)$$

Plugging (3.14) into the second equation of (1.12) and using that the Planck distribution is isotropic, we obtain the following limit problem solved in the domain Ω that yields the temperature $T(x)$ to the leading order

$$\begin{aligned} 0 &= \operatorname{div} \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn n \frac{1}{\alpha_v^a(x) + \alpha_v^s(x)} (Id - A_{v,x})^{-1}(n) \cdot \nabla_x B_v(T(x)) \right) \\ &= \operatorname{div} \left(\int_0^\infty dv \frac{1}{\alpha_v^a(x) + \alpha_v^s(x)} \left(\int_{\mathbb{S}^2} dn n \otimes (Id - A_{v,x})^{-1}(n) \right) \nabla_x B_v(T(x)) \right). \end{aligned} \quad (3.15)$$

The behaviour of I_v close to the boundary $\partial\Omega$ is given again by a boundary layer equation, which can be written in one variable. The derivation of the Milne problem for this case follows exactly the same steps as Subsection 3.1 under the scaling (3.7). In this case, both emission and scattering terms appear, since they are of the same order. Hence, for every $p \in \partial\Omega$, the Milne problem is given by

$$\begin{cases} -(n \cdot n_p) \partial_y I_v(y, n, p) = \alpha_v^a(p) (B_v(T(y, p)) - I_v(y, n, p)) \\ \quad + \alpha_v^s(p) \left(\int_{\mathbb{S}^2} K(n, n') I_v(y, n', p) dn' - I_v(y, n, p) \right) & y > 0, n \in \mathbb{S}^2 \\ \operatorname{div} \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn (n \cdot n_p) I_v(y, n, p) \right) = 0 & y > 0, n \in \mathbb{S}^2 \\ I_v(0, n, p) = g_v(n) & n \cdot n_p < 0. \end{cases} \quad (3.16)$$

The mathematical properties of the Milne problem for both absorption and scattering processes have been considered in [51]. Although the results provided in [51] have been obtained only for the case of a constant scattering kernel and constant scattering coefficient, the arguments there suggest that for more general choices of K and α_v^s , the solution I_v of (3.16) converges to the Planck equilibrium distribution as $y \rightarrow \infty$.

Notice that in this case, the thermalization length and the Milne length are the same; hence, the boundary layers coincide. Matching inner and outer solutions, we obtain the following boundary condition for equation (3.15)

$$T_\infty(p) = \lim_{y \rightarrow \infty} F^{-1} \left(\left(\int_0^\infty dv \int_{\mathbb{S}^2} dn \alpha_v^a(p) I_v(y, n, p) \right), p \right), \quad (3.17)$$

with F as in (2.4). Indeed, as we have seen in Subsection 2.2, the temperature T and the radiation energy I_v satisfying the Milne problem (3.16) are related by the identity (2.3).

Summarizing, the limit problem for the stationary radiative transfer equation (1.12) in the case $\ell_M = \ell_T = \ell_S$ is given by the following boundary value problem

$$\begin{cases} \operatorname{div} \left(\int_0^\infty \frac{dv}{\alpha_v^a(x) + \alpha_v^s(x)} \left(\int_{\mathbb{S}^2} dn n \otimes (Id - A_{v,x})^{-1}(n) \right) \nabla_x B_v(T(x)) \right) = 0 & x \in \Omega \\ T(p) = T_\infty(p) & p \in \partial\Omega, \end{cases}$$

where T_∞ is defined as in (3.17) for the solution $I_v(y, n, p)$ to the Milne problem (3.16).

3.3. Case 2: $\ell_M \ll \ell_T \ll L$. *Equilibrium approximation*

The assumption $\ell_T = \sqrt{\ell_M \ell_A} \gg \ell_M$ implies $\ell_A > \ell_M$ and hence $\varepsilon = \ell_M = \ell_S$. We thus consider $\ell_A = \varepsilon^{-\beta}$ for $\beta > -1$. Moreover, since $\ell_T = \varepsilon^{\frac{1-\beta}{2}} \ll L = 1$, we restrict to the case $\ell_A = \varepsilon^{-\beta}$ for $\beta \in (-1, 1)$.

Since $\ell_M = \ell_S \ll \ell_A$, the scattering process has a greater effect than the absorption-emission process. We expect hence the Milne problem to depend exclusively on the scattering process. In the bulk, we also expect the scattering process to be present in the diffusive equation derived for the limit problem, but we will also show that at the interior, the leading order of the radiation intensity is still the Planck distribution. Thus, we are again in the case of the equilibrium diffusion approximation. In this case, the thermalization length is much larger than the Milne length, but it is also still much smaller than the characteristic length of the domain. A second boundary layer, the so-called thermalization layer, will therefore appear. The equation describing this new layer will depend on both absorption-emission and scattering processes. Moreover, while the radiative energy becomes isotropic in the Milne layer, in the thermalization layer, I_ν will approach the Planck distribution.

We use again the expansion (3.2) for the radiation intensity with $\delta = \beta - \lfloor \beta \rfloor$, that is, $\delta = \beta + 1$ if $\beta < 0$ and $\delta = \beta$ if $\beta \geq 0$, and we plug it into the first equation in (1.12). We proceed as usual with the identification of the terms with the same power of ε .

Using the notation of (2.1), the terms of order ε^{-1} give

$$H[\phi_0(x, \cdot, \nu)](n) = \phi_0(x, n, \nu).$$

Proposition 2.1 implies hence that ϕ_0 is independent of $n \in \mathbb{S}^2$ and hence $\phi_0 = \phi_0(x, \nu)$.

Next, we consider $\beta < 0$. The terms of power ε^β give

$$\alpha_\nu^a(x)(B_\nu(T(x)) - \phi_0(x, n)) = \alpha_\nu^s(H - id)\psi_1(x, n, \nu).$$

An integration over \mathbb{S}^2 implies $B_\nu(T(x)) = \phi_0(x, \nu)$. Hence, as for ϕ_0 , we conclude that $\psi_1 = \psi_1(x, \nu)$ is independent of $n \in \mathbb{S}^2$. The terms of power ε^0 give

$$n \cdot \nabla_x \phi_0(x, \nu) = \alpha_\nu^s(x)(H[\phi_1](x, n, \nu) - \phi_1(x, n, \nu)). \quad (3.18)$$

Now we consider $\beta > 0$. In this case, $\delta = \beta$. The terms of power $\varepsilon^{\beta-1}$ give

$$H[\psi_1(x, \cdot, \nu)](n) = \psi_1(x, n, \nu),$$

which implies that $\psi_1(x, \nu)$ is independent of $n \in \mathbb{S}^2$. The terms of power ε^0 yield again equation (3.18), while the terms of power ε^β imply

$$n \cdot \nabla_x \psi_1(x, \nu) = \alpha_\nu^a(x)(B_\nu(T(x)) - \phi_0(x, n)) + \alpha_\nu^s(x)(H - id)[\psi_2(x, \cdot, \nu)](n), \quad (3.19)$$

for which an integration over \mathbb{S}^2 and the isotropy of both ϕ_0 and ψ_1 give $B_\nu(T(x)) = \phi_0(x, \nu)$.

Finally, it remains to study the case $\beta = 0$. In this case, there is no expansion $\sum_{k \geq 0} \varepsilon^k \psi_{k+1}$. Therefore, the terms of order ε^0 give the equation

$$n \cdot \nabla_x \phi_0(x, \nu) = \alpha_\nu^a(x)(B_\nu(T(x)) - \phi_0(x, \nu)) + \alpha_\nu^s(x)(H[\phi_1](x, n, \nu) - \phi_1(x, n, \nu))$$

which integrated over \mathbb{S}^2 implies

$$\phi_0 = B_\nu(T),$$

due to the isotropy of ϕ_0 , as for (3.19).

Hence, for all $\beta \in (-1, 1)$, the identification of all terms of power ε^{-1} , ε^β , $\varepsilon^{\beta-1}$ (if $\beta > 0$) and ε^0 gives $\phi_0 = B_\nu(T)$, $\psi_1 = \psi_1(x, \nu)$ and

$$-\frac{1}{\alpha_\nu^s(x)} n \cdot \nabla_x B_\nu(T(x)) = (Id - H)[\phi_1(x, \cdot, \nu)](n). \quad (3.20)$$

We now study equation (3.20). As we know from Proposition 2.1, the kernel of the operator $(Id - H)$ is given by the constant functions, and its range consists of all functions with zero mean integral, that is, $\text{Ran}(Id - H) = \{\varphi \in L^\infty(\mathbb{S}^2): \int_{\mathbb{S}^2} \varphi = 0\}$. Hence, the following linear operator is bijective

$$(Id - H): L^\infty(\mathbb{S}^2) / \mathcal{N}(Id - H) \rightarrow \text{Ran}(Id - H),$$

where $L^\infty(\mathbb{S}^2) / \mathcal{N}(Id - H)$ denotes the quotient space. Let $e_i \in \mathbb{R}^3$ be the unit vector; we consider the equation

$$n \cdot e_i = (Id - H)\varphi(n). \quad (3.21)$$

Since $n \cdot e_i \in \text{Ran}(Id - H)$, for any $c \in \mathbb{R}$, the function $\varphi(n) = (Id - H)^{-1}(n \cdot e_i) + c$ is a solution to (3.21). Therefore, using the notation

$$(Id - H)^{-1}(n) = \begin{pmatrix} (Id - H)^{-1}(n \cdot e_1) \\ (Id - H)^{-1}(n \cdot e_2) \\ (Id - H)^{-1}(n \cdot e_3) \end{pmatrix}$$

and using the linearity of $(Id - H)$, we see that ϕ_2 is given by

$$\phi_2(x, n, v) = -\frac{1}{\alpha_v^s(x)}(Id - H)^{-1}(n) \cdot \nabla_x B_v(T(x)) + c(x, v) \quad (3.22)$$

where $c(x, v)$ is independent of $n \in \mathbb{S}^2$. The isotropic function $c(x, v)$ does not contribute to the divergence-free condition of (1.12). Therefore, we will not compute the exact value of $c(x, v)$. Equation (3.22) implies that the first three terms in the expansion of I_v are given for all $\beta \in (-1, 1)$ by

$$I_v(x, n) = B_v(T(x)) + \varepsilon^{\beta - |\beta|} \psi_1(x, v) - \frac{\varepsilon}{\alpha_v^s(x)}(Id - H)^{-1}(n) \cdot \nabla_x B_v(T(x)) + \varepsilon c(x, v) + \dots$$

The divergence-free condition in (1.12) implies in the same manner as in the derivation of (3.15) the following equation, which yields the limit problem in the interior of the domain Ω

$$\text{div} \left(\int_0^\infty dv \frac{1}{\alpha_v^s(x)} \left(\int_{\mathbb{S}^2} dn n \otimes (Id - H)^{-1}(n) \right) \nabla_x B_v(T(x)) \right) = 0. \quad (3.23)$$

The behaviour of I_v close to the boundary $\partial\Omega$ is described by two nested boundary layer equations. As anticipated at the beginning of Subsection 3.3, since $\ell_M \ll \ell_T \ll L$, we observe the formation of two distinct boundary layers. The first one, the Milne layer, has a thickness of size ℓ_M , and it is described by the Milne problem, whose derivation is similar to the derivation of the Milne problems (3.8) and (3.16). The next boundary layer, which we will denote by thermalization layer, has a thickness of size ℓ_T , and it is described by a new boundary layer equation, which we will denote as thermalization equation and which we will construct immediately after deriving the Milne problem.

Following the same procedure as in Subsection 3.1, we can derive the Milne problem for this scaling limit under the rescaling (3.7). In this case, we obtain a closed equation for I_v , which depends only on the scattering process, since this is the largest term. Indeed, rescaling the space variable, we obtain

$$\begin{cases} -(n \cdot n_p) \partial_y I_v(y, n, p) = \alpha_v^s(p + \mathcal{O}(\varepsilon)) \left(\int_{\mathbb{S}^2} K(n, n') I_v(y, n', p) dn' - I_v(y, n, p) \right) \\ \quad + \varepsilon^{\beta+1} \alpha_v^a(p + \mathcal{O}(\varepsilon)) (B_v(T(y; p)) - I_v(y, n; p)) & y > 0, n \in \mathbb{S}^2 \\ \int_0^\infty dv \int_{\mathbb{S}^2} dn (n \cdot n_p) \partial_y I_v(y, n, p) = 0 & y > 0, n \in \mathbb{S}^2 \\ I_v(0, n, p) = g_v(n) & n \cdot n_p < 0. \end{cases} \quad (3.24)$$

Hence, for every $p \in \partial\Omega$, the Milne problem is given by

$$\begin{cases} -(n \cdot n_p) \partial_y I_v(y, n, p) = \alpha_v^s(p) \left(\int_{\mathbb{S}^2} K(n, n') I_v(y, n', p) dn' - I_v(y, n, p) \right) & y > 0, n \in \mathbb{S}^2 \\ I_v(0, n, p) = g_v(n) & n \cdot n_p < 0. \end{cases} \quad (3.25)$$

On the other hand, we also obtain an equation for the temperature. Indeed, plugging the first equation of (3.24) into the second one, we obtain to the leading order

$$\int_0^\infty dv \int_{\mathbb{S}^2} dn \alpha_v^a(p) (B_v(T(y; p)) - I_v(y, n; p)) = 0. \quad (3.26)$$

This equation has a steady distribution for the temperature T completely determined. At first glance, this appears strange since in the limit equation (3.25), the absorption coefficient $\alpha_v^a(p)$ does not appear, and the only processes able to modify the temperature are the absorption and emission of photons. However, the solution of this apparent paradox is that since (3.25) describes a stationary solution, it is implicitly understood that the system was running for an infinite amount of time before and the absorption/emission process had time to bring the system to a steady state, even when this process is very small.

The Milne problem for the pure scattering case has been studied in several papers such as [7, 9, 28, 51] in the context of neutron transport. Although all these results are actually obtained for functions α^s independent of the frequency, since the one-speed approximation for the neutron transport (cf. (1.13)) was considered, they are expected to hold pointwise for every frequency ν . For example, in [7], it is shown that there exists a unique solution to (3.25) for strictly positive bounded and rotationally symmetric scattering kernels. Moreover, as $y \rightarrow \infty$, the solution approaches a function $I(\nu; p)$ independent of $n \in \mathbb{S}^2$. Hence, in the Milne layer, the radiation intensity becomes isotropic.

We now turn to the thermalization layer. In this layer, we expect the radiation intensity to approach the Planck equilibrium distribution. Moreover, the boundary value for the problem (3.23) can also be found analysing the thermalization layer. In order to construct the new boundary layer equation, that is, the thermalization equation, we rescale the space variable according to the one-dimensional variable $\eta = -\frac{x-p}{\ell_T} \cdot n_p$ for $p \in \partial\Omega$, and we obtain the following equation

$$\begin{cases} -\varepsilon^{\frac{1+\beta}{2}} (n \cdot n_p) \partial_\eta I_v(\eta, n, p) = \alpha_v^a \left(p + \varepsilon^{\frac{1-\beta}{2}} \text{Rot}_p(\eta) \right) \varepsilon^{1+\beta} (B_v(T(\eta, p)) - I_v(\eta, n, p)) \\ \quad + \alpha_v^s \left(p + \varepsilon^{\frac{1-\beta}{2}} \text{Rot}_p(\eta) \right) \left(\left(\int_{\mathbb{S}^2} dn' K(n, n') I_v(\eta, n', p) \right) - I_v(\eta, n, p) \right) & \eta > 0, n \in \mathbb{S}^2 \\ \text{div} \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn (n \cdot n_p) I_v(\eta, n, p) \right) = 0 & \eta > 0, n \in \mathbb{S}^2 \\ I_v(0, n, p) = I(\nu; p) & p \in \partial\Omega, \end{cases} \quad (3.27)$$

where $I(\nu; p) = \lim_{y \rightarrow \infty} I^M(y, n, \nu; p)$ for I^M the solution to the Milne problem (3.25). In order to find the thermalization equation, we proceed in a way similar to the derivation of the outer problem. We hence expand the radiation intensity according to

$$I_v(\eta, n, p) = \varphi_0(\eta, n, \nu; p) + \varepsilon^{\frac{1+\beta}{2}} \varphi_1(\eta, n, \nu; p) + \varepsilon^{1+\beta} \varphi_2(\eta, n, \nu; p) + \dots$$

and we identify in (3.27) all terms of the same power of ε , namely, ε^0 , $\varepsilon^{\frac{1+\beta}{2}}$ and $\varepsilon^{1+\beta}$. We remark first that the functions φ_i for $i \in \mathbb{N}$ could depend on ε . Moreover, the choice of the powers of ε in the expansion of I_v is motivated by the order of magnitude of the sources in (3.27).

The terms of order ε^0 give

$$\int_{\mathbb{S}^2} K(n, n') \varphi_0 dn' = \varphi_0$$

and hence by Proposition 2.1, $\varphi_0(\eta, n, \nu; p) = \varphi_0(\eta, \nu; p)$ is independent of the direction $n \in \mathbb{S}^2$. The isotropy of φ_0 was expected as it is matched with the solution of the Milne problem, which becomes isotropic. Moreover, we also see that φ_0 does not depend on ε .

The terms of order $\varepsilon^{\frac{1+\beta}{2}}$ give

$$(n \cdot n_p) \partial_\eta \varphi_0 = \alpha_v^s(p_\varepsilon) (Id - H)(\varphi_1),$$

where we defined $p_\varepsilon = p + \varepsilon^{\frac{1-\beta}{2}} \text{Rot}_p(\eta)$. Thus, arguing as in the derivation of (3.22), Proposition 2.1 implies

$$\varphi_1(\eta, n, v; p) = \frac{1}{\alpha_v^s(p_\varepsilon)} (Id - H)^{-1}(n) \cdot n_p \partial_\eta \varphi_0 + c(\eta, v),$$

for some function $c(\eta, v)$. Finally, identifying the terms of order $\varepsilon^{1+\beta}$ implies after an integration over \mathbb{S}^2

$$\begin{aligned} & -\frac{1}{\alpha_v^s(p_\varepsilon)} \left(\int_{\mathbb{S}^2} (n \cdot n_p) (Id - H)^{-1}(n) \cdot n_p \, dn \right) \partial_\eta^2 \varphi_0(\eta, v; p) \\ & = \alpha_v^a(p_\varepsilon) (B_v(T(\eta; p)) - \varphi_0(\eta, v; p)). \end{aligned}$$

We now consider the limit as $\varepsilon \rightarrow 0$, and we obtain by the continuity of the absorption and scattering coefficient

$$-\frac{1}{\alpha_v^s(p)} \left(\int_{\mathbb{S}^2} (n \cdot n_p) (Id - H)^{-1}(n) \cdot n_p \, dn \right) \partial_\eta^2 \varphi_0(\eta, v; p) = \alpha_v^a(p) (B_v(T(\eta; p)) - \varphi_0(\eta, v; p)). \quad (3.28)$$

Moreover, the second equation in (3.27) yields

$$\int_0^\infty dv \frac{1}{\alpha_v^s(p)} \left(\int_{\mathbb{S}^2} (n \cdot n_p) (Id - H)^{-1}(n) \cdot n_p \, dn \right) \partial_\eta^2 \varphi_0(\eta, v; p) = 0, \quad (3.29)$$

where we again considered the limit $\varepsilon \rightarrow 0$. Thus, the thermalization layer equation is given for every $p \in \partial\Omega$ by

$$\begin{cases} \varphi_0(\eta, v; p) - \frac{1}{\alpha_v^a(p)\alpha_v^s(p)} \left(\int_{\mathbb{S}^2} (n \cdot n_p) (Id - H)^{-1}(n) \cdot n_p \, dn \right) \partial_\eta^2 \varphi_0(\eta, v; p) = B_v(T(\eta; p)) & \eta > 0 \\ \int_0^\infty dv \alpha_v^a(p) B_v(T(\eta; p)) = \int_0^\infty dv \alpha_v^a(p) \varphi_0(\eta, v; p) & \eta > 0 \\ \varphi_0(0, v; p) = I(v; p) & p \in \partial\Omega, \end{cases} \quad (3.30)$$

where the second equation is implied by (3.29) taking the integral over the frequency of (3.28). As far as we know, the thermalization problem has not been studied so far in the literature, and its well-posedness properties have not been described in detail. Nevertheless, we claim that the problem is well-posed under suitable assumptions and that the solution φ_0 to (3.30) converges to the Planck distribution, that is,

$$\lim_{\eta \rightarrow \infty} \varphi_0(\eta, v; p) = \varphi(v, p) = B_v(T_\infty(p)).$$

From the second equation in (3.30), we recover the relation (2.3) between the temperature and the radiation intensity φ_0 . Hence, $T(\eta; p) = F^{-1} \left(\left(\int_0^\infty dv \alpha_v^a(p) \varphi_0(\eta, v; p) \right), \eta; p \right)$ for F defined in (2.4). In particular,

$$T_\infty(p) = F^{-1} \left(\left(\int_0^\infty dv \alpha_v^a(p) \varphi(v, p) \right), p \right). \quad (3.31)$$

We remark that since $I(v; p)$, the limit as $y \rightarrow \infty$ of the solution $I^M(y, n, v; p)$ of the Milne problem (3.25), is a functional of the boundary condition g_v , so are $\varphi(v, p)$ and $T_\infty(p)$ functionals of the boundary condition g_v . Summarizing, in the case of $\ell_M \ll \ell_T \ll L$, the solution to (1.12) is expected to solve in the limit problem the following equilibrium diffusion approximation given by the stationary boundary value problem

$$\begin{cases} \text{div} \left(\int_0^\infty dv \frac{1}{\alpha_v^s(x)} \left(\int_{\mathbb{S}^2} dn \, n \otimes (Id - H)^{-1}(n) \right) \nabla_x B_v(T(x)) \right) = 0 & x \in \Omega \\ T(p) = T_\infty(p) & p \in \partial\Omega, \end{cases}$$

where T_∞ is defined in (3.31)

3.4. Case 3: $\ell_M \ll \ell_T = L$. *Transition from equilibrium to non-equilibrium*

Since $\ell_M = \varepsilon$ and $\ell_T = \sqrt{\varepsilon \ell_A} = L = 1$, we have to consider $\ell_S = \varepsilon$ and $\ell_A = \varepsilon^{-1}$.

This case is intriguing, because as we will see, it yields the transition between the equilibrium approximation and the non-equilibrium approximation, that is, the case where in the limit the radiation intensity is not given by the Planck distribution at the leading order in the bulk of the domain Ω .

As usual, we plug the expansion (3.2) for $\delta = 0$, thus without terms ψ_k , into the first equation of (3.1), and we identify all terms of the same power of ε , namely, ε^{-1} , ε^0 and ε^1 .

The terms of order ε^{-1} give

$$\phi_0(x, n, \nu) = H[\phi_0(x, \cdot, \nu)](n),$$

and hence by Proposition 2.1, the leading order is independent of $n \in \mathbb{S}^2$, that is, $\phi_0 = \phi_0(x, \nu)$.

The terms of order ε^0 give

$$n \cdot \nabla_x \phi_0(x, \nu) = \alpha_v^s(x) (H[\phi_1(x, \cdot, \nu)](n) - \phi_1(x, n, \nu)).$$

Due to the isotropy of ϕ_0 , Proposition 2.1 implies that ϕ_1 is given by

$$\phi_1(x, n, \nu) = -\frac{1}{\alpha_v^s(x)} (Id - H)^{-1}(n) \cdot \nabla_x \phi_0(x, \nu) + c(x, \nu),$$

where $c(x, \nu)$ is some function independent of $n \in \mathbb{S}^2$. As in Subsection 3.3, the isotropic function $c(x, \nu)$ will not contribute to the divergence-free condition; hence, it will not be explicitly computed.

Finally, the terms of order ε^1 yield, after an integration over \mathbb{S}^2 ,

$$4\pi \alpha_v^a(x) \phi_0(x, \nu) - \operatorname{div} \left(\frac{1}{\alpha_v^s(x)} \left(\int_{\mathbb{S}^2} n \otimes (Id - H)^{-1}(n) dn \right) \nabla_x \phi_0(x, \nu) \right) = 4\pi \alpha_v^a(x) B_\nu(T(x)), \quad (3.32)$$

where we used the invariance under rotations of the scattering kernel K and the identity $n \cdot \nabla_x f = \operatorname{div}(nf)$.

Moreover, plugging the expansion

$$I_\nu(x, n) = \phi_0(x, \nu) - \frac{\varepsilon}{\alpha_v^s(x)} (Id - H)^{-1}(n) \cdot \nabla_x \phi_0(x, \nu) + \varepsilon c(x, \nu) + \varepsilon^2 \dots$$

into the divergence-free equation in (3.1), we obtain at the leading order

$$\operatorname{div} \left(\int_0^\infty d\nu \frac{1}{\alpha_v^s(x)} \left(\int_{\mathbb{S}^2} n \otimes (Id - H)^{-1}(n) dn \right) \nabla_x \phi_0(x, \nu) \right) = 0,$$

which implies integrating (3.32) the following equation for the temperature

$$\int_0^\infty d\nu \alpha_v^a(x) \phi_0(x, \nu) = \int_0^\infty d\nu \alpha_v^a(x) B_\nu(T(x)).$$

Hence, using the definition of F in (2.4), we obtain the limit problem for ϕ_0 in the interior, namely,

$$\begin{aligned} \phi_0(x, \nu) - \frac{1}{4\pi \alpha_v^a(x)} \operatorname{div} \left(\frac{1}{\alpha_v^s(x)} \left(\int_{\mathbb{S}^2} n \otimes (Id - H)^{-1}(n) dn \right) \nabla_x \phi_0(x, \nu) \right) \\ = B_\nu \left(F^{-1} \left(\left(\int_0^\infty d\nu \alpha_v^a(x) \phi_0(x, \nu) \right), x \right) \right). \end{aligned}$$

Once more the boundary condition for the diffusion equation is given by the matching of the outer solution with the solution to a suitable boundary layer equation. Since $\ell_T = L = 1$, the thermalization layer corresponds to the outer problem. Indeed, the radiation intensity is out of equilibrium in the limit as $\varepsilon \rightarrow 0$. Hence, there is only one boundary layer, namely, the Milne layer. The Milne problem describing the boundary layer for (3.1) as $\ell_M \ll L = \ell_T$ is given once more by (3.25). Indeed, the scattering term is the term of larger order with $\ell_M = \ell_S$. Therefore, the computations in Subsection 3.3 also hold in this case. Summarizing, if $\ell_M \ll \ell_T = L$, the radiation intensity and the temperature satisfy the following equation

$$\begin{cases} \phi_0(x, \nu) - \frac{1}{4\pi\alpha_\nu^a(x)} \operatorname{div} \left(\frac{1}{\alpha_\nu^s(x)} \left(\int_{\mathbb{S}^2} n \otimes (Id - H)^{-1}(n) dn \right) \nabla_x \phi_0(x, \nu) \right) = B_\nu(T(x)) & x \in \Omega \\ \int_0^\infty d\nu \alpha_\nu^a(x) (B_\nu(T(x)) - \phi_0(x, \nu)) = 0 & x \in \Omega \\ \phi_0(p, \nu) = I_\nu^\infty(p) & p \in \partial\Omega, \end{cases}$$

where $I_\nu^\infty(p) = \lim_{y \rightarrow \infty} I_\nu(y, n; p)$ for $I_\nu(y, n; p)$ the solution to (3.25), which converges to the isotropic function I_ν^∞ . It is important to remark here that in this case, we are not obtaining an equilibrium diffusion regime. Indeed, the leading order ϕ_0 is not the Planck distribution, and therefore, this case is an example of the non-equilibrium diffusion approximation.

3.5. Case 4: $\ell_M \ll L \ll \ell_T$. Non-equilibrium approximation

Since $\ell_M = \varepsilon$, the case where $\ell_T = \sqrt{\varepsilon \ell_A} \gg L = 1$ corresponds to $\ell_S = \varepsilon$ and $\ell_A = \varepsilon^{-\beta}$ for $\beta > 1$. Under this assumption, we obtain $\ell_T = \varepsilon^{\frac{1-\beta}{2}} \rightarrow \infty$ as $\varepsilon \rightarrow 0$. Therefore, in this last subsection, we study the case when the thermalization length ℓ_T is growing to infinity as $\varepsilon \rightarrow 0$. In this case, we do not expect the solution to (1.12) to approach at the interior the Planck distribution. We will indeed see that in this case, we obtain the so-called non-equilibrium diffusion approximation.

In order to derive the outer problem for (3.1), we plug expansion (3.2) with $\delta = \beta - \lfloor \beta \rfloor$ into the first equation of (3.1), and we identify all terms of the same power of ε , namely, ε^{-1} , $\varepsilon^{\beta - \lfloor \beta \rfloor - 1}$, ε^0 , $\varepsilon^{\beta - \lfloor \beta \rfloor}$ and ε^1 .

The terms of order ε^{-1} and $\varepsilon^{\beta - \lfloor \beta \rfloor - 1}$ yield $\int_{\mathbb{S}^2} K(n, n') f(n') dn' = f(n)$ for $f \in \{\phi_0, \psi_1\}$, respectively. Therefore, at the leading order, the radiation intensity is isotropic, that is, $\phi_0 = \phi_0(x, \nu)$. Moreover, also $\psi_1 = \psi_1(x, \nu)$.

The terms of power ε^0 give

$$-\frac{1}{\alpha_\nu^s(x)} n \cdot \nabla_x \phi_0 = (Id - H)[\phi_1(x, \cdot, \nu)](n).$$

Hence, Proposition 2.1 implies the existence of some function $c(x, \nu)$ independent of $n \in \mathbb{S}^2$ such that

$$\phi_1(x, n, \nu) = -\frac{1}{\alpha_\nu^s(x)} (Id - H)^{-1}(n) \cdot \nabla_x \phi_0 + c(x, \nu). \quad (3.33)$$

Similar to the terms of order ε^0 , the terms of power $\varepsilon^{\beta - \lfloor \beta \rfloor}$ give $\psi_2 = -\frac{1}{\alpha_\nu^s(x)} (Id - H)^{-1}(n) \cdot \nabla_x \psi_1 + c(x, \nu)$. As in Subsection 3.3, the isotropic function $c(x, \nu)$ does not contribute to the divergence-free condition, and it will not be explicitly computed.

Finally, the terms of order ε^1 imply

$$n \cdot \nabla_x \phi_1 = \alpha_\nu^s(x) (H - Id)[\phi_2(x, \cdot, \nu)](n).$$

Hence, using (3.33) and integrating over \mathbb{S}^2 , we obtain the desired interior limit problem for ϕ_0

$$\operatorname{div} \left(\frac{1}{\alpha_\nu^s(x)} \left(\int_{\mathbb{S}^2} n \otimes (Id - H)^{-1}(n) dn \right) \nabla_x \phi_0(x, \nu) \right) = 0.$$

Plugging now the first equation of (1.12) into the second one, we also obtain the following equation solved by the leading order of the temperature

$$\int_0^\infty d\nu \alpha_\nu^a(x) (B_\nu(T(x)) - \phi_0(x, \nu)) = 0.$$

We remark that ϕ_0 does not need to be the Planck distribution. This is also implied by the asymptotic expansion of the radiation intensity. Indeed, the comparison of the terms of order ε^β gives

$$n \cdot \nabla_x \psi_k(x, n, \nu) = \alpha_\nu^a(x) (B_\nu(T(x)) - \phi_0(x, \nu)) + \alpha_\nu^s(x) (H - Id)[\psi_{k+1}(x, \cdot, \nu)](n),$$

where $k = \lfloor \beta \rfloor + 1 \geq 2$. Since ψ_k does not need to be isotropic for $k \geq 2$, an integration over the sphere implies the orthogonality condition

$$\operatorname{div} \left(\int_{\mathbb{S}^2} n \psi_{\lfloor \beta \rfloor + 1}(x, n, \nu) \, dn \right) = \alpha_\nu^a(x) (B_\nu(T(x)) - \phi_0(x, \nu)).$$

As in Subsection 3.3, the Milne problem for the Milne layer is given by (3.25). As in Subsection 3.4, there is no thermalization layer since the radiation intensity does not approach the equilibrium distribution. Hence, denoting by $I_\nu(y, n, p)$ the solution to (3.25) and by $I_\nu^\infty(p) = \lim_{y \rightarrow \infty} I_\nu(y, n, p)$, we obtain for this case the following limit stationary boundary value problem

$$\begin{cases} \operatorname{div} \left(\frac{1}{\alpha_\nu^s(x)} \left(\int_{\mathbb{S}^2} n \otimes (Id - H)^{-1}(n) \, dn \right) \nabla_x \phi_0(x, \nu) \right) = 0 & x \in \Omega \\ \int_0^\infty d\nu \, \alpha_\nu^a(x) (B_\nu(T(x)) - \phi_0(x, \nu)) = 0 & x \in \Omega \\ \phi_0(p, \nu) = I_\nu^\infty(p) & p \in \partial\Omega. \end{cases}$$

4. Time-dependent diffusion approximation: the case of infinite speed of light ($c = \infty$)

We turn now to the time-dependent case. In physical applications, the order of magnitude of the speed of light c is so large compared with the speed of heat transfer that it is often considered infinite (cf. [58]). This approximation is valid if the distance travelled by the light in the time scale in which meaningful changes of the temperature take place is much larger than the characteristic length of the body L . We consider in this section the diffusion approximation for the time-dependent radiative transfer equation (1.10) when $c = \infty$, and in the next sections, we will consider other choices of c . Under this assumption, the initial-boundary value problem (1.10) reduces to (1.11). This is the case when the radiation is instantaneously transported in the domain Ω . Notice that, since under this assumption in equation (1.11), there is no term containing $\partial_t I_\nu$, we do not need to impose any initial value for I_ν .

We recall that the diffusion regime holds if $\ell_M = \varepsilon \ll 1$. We will consider different choices of ℓ_A and ℓ_S given as powers of ε . We will construct the resulting initial-boundary value limit problems as follows. We will first derive the outer problems valid in the interior of Ω . Afterwards, we will construct the initial layer problems describing the transient behaviour of the radiation intensity for very small times. We will also formulate boundary layer equations describing I_ν near the boundary of Ω . It turns out that the latter are the Milne problems and the thermalization problems derived in Section 3. Finally, the matching between the outer, the boundary layer and the initial layer solutions will provide the initial value and the boundary conditions for the limit problem in the diffusion approximation under consideration.

4.1. Outer problems

In this subsection, we derive the outer problems arising from equation (1.11) under the assumption $\ell_M = \varepsilon \ll 1$ and for different choices of $\ell_A = \varepsilon^{-\beta}$ and $\ell_S = \varepsilon^{-\gamma}$. As in the stationary case analysed in Section 3, there are five different cases to be considered which yield five different diffusive problems.

In order to determine the outer problems yielding the form of the solutions in the bulk of Ω , we use the expansion

$$I_\nu(t, x, n) = \phi_0(t, x, n, \nu) + \sum_{k \geq 0} \varepsilon^{\delta+k} \psi_{k+1}(t, x, n, \nu) + \sum_{l > 0} \varepsilon^l \phi_l(t, x, n, \nu) \quad (4.1)$$

for δ defined as in (3.3) depending on ℓ_A and ℓ_S , plugging (4.1) into (1.11) and identifying all terms of the same power of ε . It turns out that the diffusive problems are in this case the time-dependent version of the stationary outer problems of Section 3. Indeed, since $c = \infty$ the first equation in (1.11) is a stationary equation for the intensity I_ν . Therefore, the same computations of Section 3 show that for any choice of

ℓ_A and ℓ_S , the first order term ϕ_0 is isotropic, and the next non-isotropic term arising in the expansion of I_v is of order ε^1 .

Hence, in the case $\ell_T \leq 1$, that is, $\tau_h = \frac{1}{\varepsilon}$, since the time derivative of the temperature in the second equation of (1.11) is a term of order ε^0 , which is balanced by the divergence of the flux of energy, we obtain the following outer problems

(i) for $\ell_M = \ell_T \ll \ell_S$

$$\partial_t T(t, x) - \frac{4\pi}{3} \operatorname{div} \left(\int_0^\infty \frac{\nabla_x B_v(T(t, x))}{\alpha_v(x)} dv \right) = 0, \quad (4.2)$$

(ii) for $\ell_M = \ell_T = \ell_S$

$$\partial_t T(t, x) = \operatorname{div} \left(\int_0^\infty dv \frac{1}{\alpha_v^a(x) + \alpha_v^s(x)} \left(\int_{\mathbb{S}^2} dn n \otimes (Id - A_{v,x})^{-1}(n) \right) \nabla_x B_v(T(t, x)) \right), \quad (4.3)$$

(iii) for $\ell_M \ll \ell_T \ll L$

$$\partial_t T(t, x) = \operatorname{div} \left(\int_0^\infty dv \frac{1}{\alpha_v^s(x)} \left(\int_{\mathbb{S}^2} dn n \otimes (Id - H)^{-1}(n) \right) \nabla_x B_v(T(t, x)) \right), \quad (4.4)$$

(iv) for $\ell_M \ll L = \ell_T$

$$\begin{cases} -\frac{1}{\alpha_v^a(x)} \operatorname{div} \left(\frac{1}{\alpha_v^s(x)} \left(\int_{\mathbb{S}^2} n \otimes (Id - H)^{-1}(n) dn \right) \nabla_x \phi_0(t, x, v) \right) = B_v(T(t, x)) - \phi_0(t, x, v) \\ \partial_t T(t, x) - \operatorname{div} \left(\int_0^\infty dv \frac{1}{\alpha_v^s(x)} \left(\int_{\mathbb{S}^2} n \otimes (Id - H)^{-1}(n) dn \right) \nabla_x \phi_0(t, x, v) \right) = 0. \end{cases} \quad (4.5)$$

In the case $\ell_M \ll L \ll \ell_T$, namely, when $\tau_h = \frac{1}{\varepsilon^\beta}$ for $\beta > 1$ the outer problem is

$$\begin{cases} \operatorname{div} \left(\frac{1}{\alpha_v^s(x)} \left(\int_{\mathbb{S}^2} n \otimes (Id - H)^{-1}(n) dn \right) \nabla_x \phi_0(t, x, v) \right) = 0 \\ \partial_t T(t, x) - \int_0^\infty dv \alpha_v^a(x) (B_v(T(t, x)) - \phi_0(t, x, v)) = 0. \end{cases} \quad (4.6)$$

Indeed, plugging the expansion (4.1) with $\delta = \beta - \lfloor \beta \rfloor$ into the first equation in (1.11), we obtain, arguing as in Section 3.5, that the leading order ϕ_0 is isotropic and solves the stationary equation

$$\operatorname{div} \left(\frac{1}{\alpha_v^s(x)} \left(\int_{\mathbb{S}^2} n \otimes (Id - H)^{-1}(n) dn \right) \nabla_x \phi_0(t, x, v) \right) = 0.$$

Moreover, plugging the second equation of (1.11) into the second one yields

$$\partial_t T(t, x) - \int_0^\infty dv \alpha_v^a(x) (B_v(T(t, x)) - \phi_0(t, x, v)) = 0.$$

These are the equations describing the radiation intensity and the temperature in the bulk away from the boundary and for positive times.

We remark that as for the stationary problem, the regimes of equilibrium diffusion approximations are for $\ell_T \ll L$ and correspond to the problems (4.2), (4.3) and (4.4), while the regimes of non-equilibrium approximations are for $\ell_T \gtrsim L$ and are described by (4.5) and (4.6).

4.2. Initial layer equations and boundary layer equations

As in the case of the stationary diffusion approximation, the radiation intensity I_v and the temperature T can change abruptly near the boundaries; that is, boundary layers might arise. In addition, in the time-dependent case, the behaviour of (T, I_v) could also change quickly for small times. We will denote the latter as initial layers. In this subsection, we construct the initial layers for distances to the boundary

of order 1 and boundary layers for positive times of order 1. We denote by initial layer equations the problems derived for times $t \ll 1$ and solved at the interior of Ω . Similarly, the boundary layer equations are problems derived from rescaling the space variable only and solved for any $t > 0$.

In the considered case, that is, $c = \infty$, there are no initial layers for the temperature appearing in the bulk, that is, for distances to the boundary of order 1. To see this, we have to consider two different cases. We recall that the second equation in (1.11) is

$$\partial_t T(t, x) + \tau_h \operatorname{div} \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn n I_v(t, x, n) \right) = 0. \quad (4.7)$$

Hence, if $\ell_T \leq 1$, the heat parameter is $\tau_h = \frac{1}{\varepsilon}$. Therefore, in equation (4.7), the divergence of the flux of radiative energy is multiplied by ε^{-1} . As indicated before, ϕ_0 is isotropic. In addition to that, since the first non-isotropic term is of order ε , it follows that in (4.7), the term containing the divergence is of order 1 in the bulk. Therefore, $\partial_t T$ is of order 1 and as a consequence $T \simeq T_0$ for small times $t \ll 1$ and no initial layer appears. On the other hand, in the case $\ell_T \gg 1$, the heat parameter is $\tau_h = \ell_A = \frac{1}{\varepsilon^\beta}$ for $\beta > 1$. In this case, the leading term of the divergence of the total flux of energy is of order ε^β , and it is given by

$$\varepsilon^\beta \int_0^\infty dv \int_{\mathbb{S}^2} dn \alpha_v^a (B_v(T) - \phi_0).$$

This implies again that $\partial_t T$ is of order 1, and hence, there are also in this case no initial layers.

We now examine the boundary layers appearing for times of order 1. In this case, similarly as in the stationary case, Milne and thermalization layers arise. It turns out that the equations describing the radiation intensity near the boundary are given either by the stationary Milne problems (3.8), (3.16) and (3.25) or by the thermalization problem (3.30) or by a combination of both of them depending on the choice of ℓ_A and ℓ_S .

We begin by describing first the Milne layers. We rescale the space variable according to $y = -\frac{x-p}{\varepsilon} \cdot n_p$, where $\ell_M = \varepsilon$ and $p \in \partial\Omega$. We also express the absorption and scattering lengths according to $\ell_A = \varepsilon^{-\beta}$, $\ell_S = \varepsilon^{-\gamma}$ with $\min\{\beta, \gamma\} = -1$. With this notation, (1.11) becomes

$$\begin{cases} -(n \cdot n_p) \partial_y I_v(t, y, n; p) = \varepsilon^{\beta+1} \alpha_v^a (p + \mathcal{O}(\varepsilon)) (B_v(T) - I_v) \\ \quad + \varepsilon^{\gamma+1} \alpha_v^s (p + \mathcal{O}(\varepsilon)) \left(\int_{\mathbb{S}^2} K(n, n') I_v dn' - I_v \right) & y > 0 \\ \partial_t T(t, y; p) - \frac{\tau_h}{\varepsilon} \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn (n \cdot n_p) \partial_y I_v \right) = 0 & y > 0 \\ T(0, y; p) = T_0(y; p) & y > 0 \\ I_v(t, 0, n; p) = g_v(t, n) & n \cdot n_p < 0. \end{cases} \quad (4.8)$$

Letting $\varepsilon \rightarrow 0$, we obtain different Milne problems for different choices of β and γ . With similar arguments as in Section 3, we can see that the Milne problems are the same as the one derived for the stationary case, except for the fact that the unknowns also depend on the variable t . However, the variable t appears only as a parameter, and the Milne problems are stationary. These are given by (3.8) in the case $\gamma > -1$, by (3.16) if $\gamma = \beta = -1$ and finally by (3.25) if $\beta > -1$. Notice that we are assuming that, if the incoming radiation g_v depends on time, it does so only for times t of order one.

We remark that when $\beta > -1$, the Milne problem (3.25) is a closed problem involving only the radiation intensity I_v . If $\ell_T \ll L$, in order to determine the temperature close to the boundary, we have to solve the stationary equation

$$\int_0^\infty dv \int_{\mathbb{S}^2} dn \alpha_v^a(p) (B_v(T(t, y; p)) - I_v(t, y, n; p)) = 0.$$

This is the same equation that we obtained in the stationary case in (3.26). On the other hand, if $\ell_T \gtrsim L$, the temperature is related to the radiation intensity by a time-dependent equation similar to the second

one in (4.5) and (4.6), namely, the equations describing the temperature in the bulk, that is,

$$\partial_t T(t, y; p) + \int_0^\infty dv \int_{\mathbb{S}^2} dn \alpha_v^a(p) (B_v(T(t, y; p)) - I_v(t, y, n; p)) = 0. \quad (4.9)$$

Besides the Milne layer in the case $\ell_M \ll \ell_T \ll L$, we also observe the formation of a thermalization layer at a distance ℓ_T to the boundary. The equation describing this layer is obtained with a change of variable $\eta = -\frac{x-p}{\ell_T} \cdot n_p$ for $p \in \partial\Omega$. Recall that in this case, we consider $\ell_S = \varepsilon$ and $\ell_A = \varepsilon^{-\beta}$ for $\beta \in (-1, 1)$ and hence $\ell_T = \varepsilon^{\frac{1-\beta}{2}}$ and $\tau_h = \frac{1}{\varepsilon}$. Thus, (1.11) becomes under this rescaling

$$\begin{cases} -\varepsilon^{\frac{1+\beta}{2}} (n \cdot n_p) \partial_\eta I_v(t, \eta, n; p) = \alpha_v^a \left(p + \mathcal{O} \left(\varepsilon^{\frac{1-\beta}{2}} \right) \right) \varepsilon^{\beta+1} (B_v(T) - I_v) \\ \quad + \alpha_v^s \left(p + \mathcal{O} \left(\varepsilon^{\frac{1-\beta}{2}} \right) \right) \left(\int_{\mathbb{S}^2} K(n, n') I_v dn' - I_v \right) & \eta > 0 \\ \partial_t T(t, \eta; p) - \varepsilon^{\frac{\beta-3}{2}} \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn (n \cdot n_p) \partial_\eta I_v \right) = 0 & \eta > 0. \end{cases} \quad (4.10)$$

We see once more that the thermalization layer equation is equation (3.30), the equation constructed for the stationary problem in Section (3.3).

Finally, matching the solution of the boundary layer equations with the outer problem, we can construct the boundary condition for the diffusive initial-boundary limit problem. We will summarize these problems in the following subsection.

4.3. Limit problems in the bulk

We summarize now the time-dependent partial differential equation problems that we obtain for the equation (1.11) as $\ell_M \rightarrow 0$ for all different choices of ℓ 's. They are given by the outer problems (4.2)–(4.6), valid in the bulk for positive times. Since there are no initial layers appearing for times $t \ll 1$, the initial condition is $T(t, x) = T_0(x)$ for any choice of ℓ_A and ℓ_S . Moreover, the boundary condition is given by the matching of the solution of the boundary layer problems with the outer solution.

(i) If $\ell_M = \ell_T \ll \ell_S$, then the problem is given by

$$\begin{cases} \partial_t T(t, x) - \frac{4\pi}{3} \operatorname{div} \left(\int_0^\infty \frac{\nabla_x B_v(T(t, x))}{\alpha_v(x)} dv \right) = 0 & x \in \Omega, t > 0 \\ T(0, x) = T_0(x) & x \in \Omega \\ T(t, p) = \lim_{y \rightarrow \infty} F^{-1} \left(\left(\int_0^\infty dv \alpha_v^a(p) I_v(t, y, n; p) \right), y, p \right) & p \in \partial\Omega, t > 0, \end{cases} \quad (4.11)$$

where $I_v(y, n; p)$ is the solution to the Milne problem (3.8).

(ii) If $\ell_M = \ell_T \ll L$, we obtain the following limit problem

$$\begin{cases} \partial_t T(t, x) = \operatorname{div} \left(\int_0^\infty dv \frac{1}{\alpha_v^a(x) + \alpha_v^s(x)} \left(\int_{\mathbb{S}^2} dn n \otimes (Id - A_{v,x})^{-1}(n) \right) \nabla_x B_v(T(x)) \right) & x \in \Omega, t > 0 \\ T(0, x) = T_0(x) & x \in \Omega \\ T(t, p) = \lim_{y \rightarrow \infty} F^{-1} \left(\left(\int_0^\infty dv \int_{\mathbb{S}^2} dn \alpha_v^a(p) I_v(t, y, n, p) \right), y, p \right) & p \in \partial\Omega, t > 0, \end{cases} \quad (4.12)$$

where $I_v(y, n, p)$ solves the Milne problem (3.16).

(iii) We turn now to the case $\ell_M \ll \ell_T \ll L$, which corresponds to the case $\ell_M = \varepsilon = \ell_S$ and $\ell_A = \varepsilon^{-\beta}$ for $\beta \in (-1, 1)$. We obtain the following limit problem

$$\begin{cases} \partial_t T - \operatorname{div} \left(\int_0^\infty dv \frac{1}{\alpha_v^s(x)} \left(\int_{\mathbb{S}^2} dn \, n \otimes (Id - H)^{-1}(n) \right) \nabla_x B_v(T(x)) \right) = 0 & x \in \Omega \\ T(0, x) = T_0(x) & x \in \Omega \\ T(t, p) = \lim_{\eta \rightarrow \infty} F^{-1} \left(\left(\int_0^\infty dv \int_{\mathbb{S}^2} dn \, \alpha_v^a(x) \varphi_0(t, \eta, v; p) \right), y, p \right) & p \in \partial\Omega, t > 0, \end{cases} \quad (4.13)$$

where $\varphi_0(t, \eta, v; p)$ solves the thermalization equations (3.30) with boundary value $\varphi_0(t, 0, v; p) = \lim_{y \rightarrow \infty} I_v(t, y, n, v; p)$ for I_v the solution to the Milne problem (3.25) with boundary value $g_v(t, n)$.

(iv) We consider now the last two cases where $\ell_M \ll L \lesssim \ell_T$. The limit problem in the case $\ell_T = L$ is

$$\begin{cases} -\frac{1}{\alpha_v^a(x)} \operatorname{div} \left(\frac{1}{\alpha_v^s(x)} \left(\int_{\mathbb{S}^2} n \otimes (Id - H)^{-1}(n) \, dn \right) \nabla_x \phi_0(t, x, v) \right) \\ \quad = B_v(T(t, x)) - \phi_0(t, x, v) & x \in \Omega, t > 0 \\ \partial_t T(t, x) + \int_0^\infty dv \int_{\mathbb{S}^2} dn \, \alpha_v^a(x) (B_v(T(t, x)) - \phi_0(t, x, v)) = 0 & x \in \Omega, t > 0 \\ T(0, x) = T_0(x) & x \in \Omega \\ \phi_0(t, p, v) = \lim_{y \rightarrow \infty} \int_{\mathbb{S}^2} I_v(t, y, n, p) & p \in \partial\Omega, t > 0, \end{cases} \quad (4.14)$$

where $I_v(t, y, n, p)$ solves the Milne problem (3.25) for the boundary value $g_v(t, n)$. Notice that in problem (3.25), the time t appears just as a parameter.

(v) Finally, if $L \ll \ell_T$ with the same notation as above, the limit problem in this case is

$$\begin{cases} \operatorname{div} \left(\frac{1}{\alpha_v^s(x)} \left(\int_{\mathbb{S}^2} n \otimes (Id - H)^{-1}(n) \, dn \right) \nabla_x \phi_0(t, x, v) \right) = 0 & x \in \Omega, t > 0 \\ \partial_t T(t, x) + \int_0^\infty dv \int_{\mathbb{S}^2} \alpha_v^a(x) (B_v(T(t, x)) - \phi_0(t, x, v)) = 0 & x \in \Omega, t > 0 \\ T(0, x) = T_0(x) & x \in \Omega \\ \phi_0(t, p, v) = \lim_{y \rightarrow \infty} \int_{\mathbb{S}^2} I_v(t, y, n, p) & p \in \partial\Omega, t > 0. \end{cases} \quad (4.15)$$

Also for this case, the boundary condition is obtained by the solution of the boundary layer described by the Milne problem (3.25).

4.4. Initial-boundary layers

It is important to note that in regions very close to the boundary and for a time $t \ll 1$, new layers could appear. These are the regions where the radiation intensity I_v and the temperature T change from the solution of the initial layer equation to the solution of the boundary layer equation. For this reason, we denote these layers as initial-boundary layers. In this section, we will derive the equations describing them for any choice of ℓ_A and ℓ_S . In the following, we will always denote by p a point belonging to the boundary, that is, $p \in \partial\Omega$.

(i) If $\ell_M = \ell_T \ll \ell_S$, we observe the formation of only one initial-boundary layer. It is described by an equation, which can be constructed rescaling the space variable as $y = -\frac{x-p}{\varepsilon} \cdot n_p$ and the time by $t = \varepsilon^2 \tau$. Indeed, since in this case $\beta = -1$ (because $\ell_A = \varepsilon$) and $\tau_h = \varepsilon^{-1}$, we see that the leading term of divergence of the flux of energy is of order ε^{-2} in the following equation

$$\partial_t T(t, y; p) + \tau_h \varepsilon^\beta \int_0^\infty dv \int_{\mathbb{S}^2} dn \, \alpha_v^a(p) (B_v(T(t, y; p)) - I_v(t, y, n; p)) = 0. \quad (4.16)$$

This equation is obtained by plugging the first equation in (4.8) into the second one. We recall that equation (4.8) is obtained after a rescaling of only the space variable. Hence, the time rescaling $t = \varepsilon^2 \tau$ gives a non-trivial equation for the temperature. Thus, the radiation intensity I_v and the temperature T solve the following initial-boundary layer equation

$$\begin{cases} -(n \cdot n_p) \partial_y I_v(\tau, y, n; p) = \alpha_v^a(p) (B_v(T(\tau, y)) - I_v(\tau, y, n; p)) & y > 0, \tau > 0 \\ \partial_\tau T(\tau, y) - \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn (n \cdot n_p) \partial_y I_v(\tau, y, n; p) \right) = 0 & y > 0, \tau > 0 \\ T(0, y; p) = T_0(p) & y > 0 \\ I_v(\tau, 0, n; p) = g_v(0, n) & n \cdot n_p < 0, \tau > 0. \end{cases}$$

- (ii) In the case $\ell_M = \ell_T = \ell_S$ under the scaling $y = -\frac{x-p}{\ell_M} \cdot n_p$ and $t = \varepsilon^2 \tau$, we obtain as above the following initial-boundary layer equation

$$\begin{cases} -(n \cdot n_p) \partial_y I_v(\tau, y, n; p) = \alpha_v^a(p) (B_v(T(\tau, y)) - I_v(\tau, y, n; p)) \\ \quad + \alpha_v^s \left(\int_{\mathbb{S}^2} K(n, n') I_v(\tau, y, n'; p) dn' - I_v(\tau, y, n; p) \right) & y > 0, \tau > 0 \\ \partial_\tau T(\tau, y) + \operatorname{div} \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn n I_v \right) = 0 & y > 0, \tau > 0 \\ T(0, y; p) = T_0(p) & y > 0 \\ I_v(\tau, 0, n; p) = g_v(0, n) & n \cdot n_p < 0, \tau > 0. \end{cases}$$

- (iii) If $\ell_A \ll \ell_T \ll L$, we obtain two different initial-boundary layers. This is consistent with the fact that there are two boundary layers appearing, namely, the Milne layer, in which I_v becomes isotropic, and the thermalization layer, in which I_v approaches to the Planck distribution. We now notice that rescaling the space variable by $y = -\frac{x-p}{\varepsilon} \cdot n_p$ and the time variable according to $t = \varepsilon^{1-\beta} \tau$ equation (4.16) gives the following initial-boundary Milne layer equation

$$\begin{cases} -(n \cdot n_p) \partial_y I_v(\tau, y, n; p) = \alpha_v^s(p) \left(\int_{\mathbb{S}^2} K(n, n') I_v(\tau, y, n'; p) dn' - I_v(\tau, y, n; p) \right) & y > 0, \tau > 0 \\ \partial_\tau T(\tau, y) + \int_0^\infty dv \int_{\mathbb{S}^2} dn \alpha_v^a(p) (B_v(T)(\tau, y; p) - I_v(\tau, y, n; p)) = 0 & y > 0, \tau > 0 \\ T(0, y; p) = T_0(p) & y > 0 \\ I_v(\tau, 0, n; p) = g_v(0, n) & n \cdot n_p < 0, \tau > 0. \end{cases} \quad (4.17)$$

Moreover, rescaling the space variable according to $\eta = -\frac{x-p}{\ell_T} \cdot n_p$ and the time by $t = \varepsilon^{1-\beta} \tau$ from equation (4.10), we obtain the following initial-boundary thermalization layer equation

$$\begin{cases} \varphi_0(\tau, \eta, v; p) - \frac{1}{\alpha_v^a(p) \alpha_v^s(p)} \left(\oint_{\mathbb{S}^2} (n \cdot n_p) (Id - H)^{-1}(n) \cdot n_p dn \right) \partial_\eta^2 \varphi_0(\tau, \eta, v; p) \\ \quad = B_v(T(\tau, \eta; p)) & \eta > 0, \tau > 0 \\ \partial_\tau T - \int_0^\infty dv \int_{\mathbb{S}^2} dn \alpha_v^a(p) (B_v(T)(\tau, \eta; p) - I_v(\tau, \eta, n; p)) = 0 & \eta > 0, \tau > 0 \\ T(0, \eta; p) = T_0(p) & y > 0 \\ \varphi_0(\tau, 0, v; p) = I(0, v; p) & p \in \partial\Omega, \tau > 0. \end{cases}$$

This is the initial-boundary layer equation describing the transition from the initial value to the boundary value in the limit problem (4.13).

(iv)+(v) Finally, in the last two considered cases, namely, when $\ell_T \gtrsim L$, we do not obtain an initial-boundary layer. However, under the space variable rescale $y = -\frac{x-p}{\varepsilon} \cdot n_p$ for the Milne problem (3.25), we also obtained an evolution equation for the temperature valid for all $t > 0$ given as we saw in (4.9) by

$$\begin{cases} -(n \cdot n_p) \partial_y I_v(t, y, n; p) = \alpha_v^s(p) \left(\int_{\mathbb{S}^2} K(n, n') I_v(t, y, n'; p) dn' - I_v(t, y, n, v; p) \right) & y > 0, t > 0 \\ \partial_t T(t, y) + \int_0^\infty dv \int_{\mathbb{S}^2} \alpha_v^a(p) (B_v(T)(t, y; p) - I_v(t, y, n; p)) = 0 & y > 0, t > 0 \\ T(0, y; p) = T_0(p) & y > 0 \\ I_v(t, 0, n; p) = g_v(t, n) & n \cdot n_p < 0, t > 0. \end{cases}$$

5. Time-dependent diffusion approximation: the case of speed of light of order 1

In this section, we construct the limit problem solved by the solution of the time-dependent equation (1.10) when $\ell_M \rightarrow 0$ and the speed of light is finite. Without loss of generality, we consider first the case $c = 1$. Physically, this means that the characteristic time for the propagation of light is similar to the time of the heat transfer process. This situation can be expected to be relevant only in astrophysical applications. The strategy is the same as in Section 4. We will first formulate the limit problem valid at the interior of the domain Ω for positive times. In Subsection 5.2, we will consider the formation of initial and boundary layers. In this case, we will obtain non-trivial initial layer equations. On the other hand, as in Section 4, the boundary layer equations are stationary and are the same equations we constructed in Section 3. Finally, in Subsections 5.3 and 5.4, we will summarize the initial-boundary value problem that we have obtained, and we will construct the initial-boundary layer equations that we have to consider in order to describe the behaviour of the solution in a small neighbourhood of the boundary for times $t \ll 1$.

5.1. Outer problems

We consider equation (1.10) in the case $c = 1$ and under the assumption $\ell_M = \varepsilon$ for the different choices of $\ell_A = \varepsilon^{-\beta}$ and $\ell_S = \varepsilon^{-\gamma}$. Expanding I_v according to (4.1) and identifying in (1.10) all terms of the same order, we conclude as we computed in Section 3 and Section 4 that the first order $\phi_0(t, x, n, v)$ of the intensity I_v is isotropic and the first non-isotropic term is of order ε^1 . Moreover, as long as $\ell_T \ll L$, we have $\phi_0(t, x, v) = B_v(T(t, x))$. The outer problems in the case $\ell_T \leq 1$, that is, $\tau_h = \frac{1}{\varepsilon}$, are given

(i) for $\ell_M = \ell_T \ll \ell_S$ by

$$\partial_t T(t, x) + 4\pi \sigma \partial_t T^4(t, x) - \frac{4\pi}{3} \operatorname{div} \left(\int_0^\infty \frac{\nabla_x B_v(T(t, x))}{\alpha_v(x)} dv \right) = 0,$$

(ii) for $\ell_M = \ell_T = \ell_S$ by

$$\begin{aligned} & \partial_t T(t, x) + 4\pi \sigma \partial_t T^4(t, x) \\ &= \operatorname{div} \left(\int_0^\infty dv \frac{1}{\alpha_v^a(x) + \alpha_v^s(x)} \left(\int_{\mathbb{S}^2} dn n \otimes (Id - A_{v,x})^{-1}(n) \right) \nabla_x B_v(T(t, x)) \right), \end{aligned}$$

(iii) for $\ell_M \ll \ell_T \ll L$ by

$$\partial_t T(t, x) + 4\pi \sigma \partial_t T^4(t, x) = \operatorname{div} \left(\int_0^\infty dv \frac{1}{\alpha_v^s(x)} \left(\int_{\mathbb{S}^2} dn n \otimes (Id - H)^{-1}(n) \right) \nabla_x B_v(T(t, x)) \right),$$

(iv) for $\ell_M \ll L = \ell_T$ by

$$\begin{cases} \partial_t \phi_0(t, x, v) - \operatorname{div} \left(\frac{1}{\alpha_v^s(x)} \left(\int_{\mathbb{S}^2} n \otimes (Id - H)^{-1}(n) dn \right) \nabla_x \phi_0(t, x, v) \right) \\ \quad = \alpha_v^a(x) (B_v(T(t, x)) - \phi_0(t, x, v)) \\ \partial_t T(t, x) + 4\pi \int_0^\infty dv \alpha_v^a(x) (B_v(T(t, x)) - \phi_0(t, x, v)) = 0. \end{cases} \quad (5.1)$$

In the case $\ell_T \gg 1$, that is, $\tau_h = \ell_A = \varepsilon^{-\beta}$ for $\beta > 1$, a similar computation to the one for the derivation of the problem (4.6) yields

$$\begin{cases} \operatorname{div} \left(\frac{1}{\alpha_v^s(x)} \left(\int_{\mathbb{S}^2} n \otimes (Id - H)^{-1}(n) dn \right) \nabla_x \phi_0(t, x, v) \right) = 0 \\ \partial_t T(t, x) + 4\pi \int_0^\infty dv \alpha_v^a(x) (B_v(T(t, x)) - \phi_0(t, x, v)) = 0. \end{cases} \quad (5.2)$$

Indeed, in the first equation of (1.10), the leading order of the term containing the time derivative of I_v is of power ε^0 as the emission-absorption term. On the other hand, the leading order ϕ_0 of the radiation intensity is isotropic, and the first non-isotropic term is of order ε^1 . Therefore, the identification in the first equation of (1.10) of the terms of order $\varepsilon^{1-\beta} \gg \varepsilon^0$ gives the stationary equation in (5.2) solved by ϕ_0 . Finally, plugging the first equation of (1.10) into the second one yields the equation for the temperature as in (5.2).

5.2. Initial layer equations and boundary layer equations

In this subsection, we will describe the initial layers and the boundary layers appearing for time scales smaller than the heat parameter τ_h and for regions close to the boundary, respectively. We start with the initial layers, and we will see that, similarly to the boundary layers considered in Sections 3 and 4, there are two nested initial layers appearing. Indeed, in a first layer, that is, for a very small time scale, the radiation intensity becomes isotropic, while in a second initial layer, it becomes eventually the Planck distribution for the temperature. We will denote the first layer as the initial Milne layer and the second one as the initial thermalization layer, due to their analogy with the boundary layers considered in Sections 3 and 4. We will also see that while the initial Milne layer appears for every choice of ℓ_A and ℓ_S , the initial thermalization layer coincides with the initial Milne layer (if $\ell_M = \ell_T$), appears after the initial Milne layer (if $\ell_M \ll \ell_T \ll L$) or is not present at all (if $\ell_T \gtrsim L$).

We recall that under the assumption $\ell_A = \varepsilon^{-\beta}$ and $\ell_S = \varepsilon^{-\gamma}$ for $\min\{\beta, \gamma\} = -1$ equation (1.10) writes

$$\begin{cases} \partial_t I_v(t, x, n) + \tau_h n \cdot \nabla_x I_v(t, x, n) = \alpha_v^a(x) \varepsilon^\beta \tau_h (B_v(T(t, x)) - I_v(t, x, n)) \\ \quad + \alpha_v^s(x) \varepsilon^\gamma \tau_h \left(\int_{\mathbb{S}^2} K(n, n') I_v(t, x, n') dn' - I_v(t, x, n) \right) & x \in \partial\Omega, n \in \mathbb{S}^2, t > 0 \\ \partial_t T + \partial_t \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn I_v(t, n, x) \right) + \tau_h \operatorname{div} \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn n I_v(t, n, x) \right) = 0 & x \in \partial\Omega, n \in \mathbb{S}^2, t > 0 \\ I_v(0, x, n) = I_0(x, n, v) & x \in \partial\Omega, n \in \mathbb{S}^2 \\ T(0, x) = T_0(x) & x \in \partial\Omega \\ I_v(t, n, x) = g_v(t, n) & x \in \partial\Omega, n \cdot n_x < 0, t > 0. \end{cases} \quad (5.3)$$

Notice that the leading term in the first equation is of order $\frac{\varepsilon}{\tau_h}$. Therefore, under a time rescaling $t = \frac{\varepsilon}{\tau_h} \tau$, the first equation writes

$$\partial_\tau I_v = \varepsilon^{\beta+1} \alpha_v^a(x) (B_v(T) - I_v) + \varepsilon^{\gamma+1} \alpha_v^s(x) \left(\int_{\mathbb{S}^2} K(n, n') I_v dn' - I_v \right) + \varepsilon n \cdot \nabla_x I_v$$

while the second one is

$$\partial_\tau T + \partial_\tau \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn I_v \right) + \varepsilon \operatorname{div} \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn n I_v \right) = 0.$$

It is hence easy to see that for any choice of ℓ_M and ℓ_S , there is an initial layer with thickness of order $\frac{\varepsilon}{\tau_h}$. Notice that as long as $\ell_T \lesssim 1$ (i.e. $\tau_h = \varepsilon^{-1}$), this initial layer has a thickness of order ε^2 , while in the case $\ell_T \gg 1$ (i.e. $\tau_h = \varepsilon^{-\beta}$ for $\beta > 1$), the order is $\varepsilon^{1+\beta}$. This layer plays the role of the Milne boundary layer in the time-dependent case, as in this layer, the radiation intensity becomes isotropic. For this reason, we will denote it as the initial Milne layer.

- (i) In the case $\ell_M = \ell_T \ll \ell_S$, the initial Milne layer is described by the following initial Milne equation for the leading order of the radiation intensity

$$\begin{cases} \partial_\tau \varphi_0(\tau, x, n, v) = \alpha_v^a(x) (B_v(T(\tau, x)) - \varphi_0(\tau, x, n, v)) & \tau > 0 \\ \partial_\tau T(\tau, x) + \int_0^\infty dv \int_{\mathbb{S}^2} dn \alpha_v^a(x) (B_v(T(\tau, x)) - \varphi_0(\tau, x, n, v)) = 0 & \tau > 0 \\ \varphi_0(0, x, n, v) = I_0(x, n, v) \\ T(0, x) = T_0(x). \end{cases} \quad (5.4)$$

This equation plays the same role as the Milne problem, and we expect $T \rightarrow T_\infty$ and $\varphi_0 \rightarrow B_v(T_\infty)$ as $\tau \rightarrow \infty$. Indeed, given a bounded solution to the equation (5.4), assuming $T_\infty(x) = \lim_{\tau \rightarrow \infty} T(\tau, x)$ and using simple ODE's arguments, we have

$$\varphi_0(\tau, x, n, v) = I_0 e^{-\alpha_v^a(x)\tau} + \int_0^\tau \alpha_v^a(x) e^{-\alpha_v^a(x)(\tau-s)} B_v(T(s, x)) ds \xrightarrow{\tau \rightarrow \infty} B_v(T_\infty(x)). \quad (5.5)$$

- (ii) We turn now to the case $\ell_M = \ell_T = \ell_S \ll L$. The initial Milne equation is

$$\begin{cases} \partial_\tau \varphi_0(\tau, x, n, v) = \alpha_v^a(x) (B_v(T(\tau, x)) - \varphi_0(\tau, x, n, v)) \\ \quad + \alpha_v^s(x) \left(\int_{\mathbb{S}^2} K(n, n') \varphi_0(\tau, x, n', v) dn' - \varphi_0(\tau, x, n, v) \right) & \tau > 0 \\ \partial_\tau T(\tau, x) + \int_0^\infty dv \int_{\mathbb{S}^2} dn \alpha_v^a(x) (B_v(T(\tau, x)) - \varphi_0(\tau, x, n, v)) = 0 & \tau > 0 \\ \varphi_0(0, x, n, v) = I_0(x, n, v) \\ T(0, x) = T_0(x). \end{cases} \quad (5.6)$$

Again, assuming $T_\infty(x) = \lim_{\tau \rightarrow \infty} T(\tau, x)$ for a bounded solution to (5.6), we can write an explicit formula for φ_0 , and we also obtain

$$\begin{aligned} \varphi_0(\tau, x, n, v) &= I_0 e^{-(\alpha_v^a(x) + \alpha_v^s(x))\tau} + \int_0^\tau \alpha_v^a(x) e^{-(\alpha_v^a(x) + \alpha_v^s(x))(\tau-s)} B_v(T(s, x)) ds \\ &\quad + \int_0^\tau \alpha_v^s(x) e^{-(\alpha_v^a(x) + \alpha_v^s(x))(\tau-s)} H[\varphi_0](\tau, x, n, v) \\ &= e^{-(\alpha_v^a(x) + \alpha_v^s(x))\tau} \sum_{n=0}^\infty \frac{(\alpha_v^s(x)\tau)^n}{n!} H^n[I_0](x, n, v) \\ &\quad + \int_0^\tau \alpha_v^a(x) e^{-\alpha_v^a(x)(\tau-s)} B_v(T(s, x)) ds \\ &\xrightarrow{\tau \rightarrow \infty} B_v(T_\infty(x)). \end{aligned}$$

- (iii) For the case $\ell_M \ll \ell_T \ll L$, similarly to the boundary layers, we expect the solution to the initial Milne layer equation to become isotropic but not necessarily to become the Planck distribution. In this case, the initial Milne equation is

$$\begin{cases} \partial_\tau \varphi_0(\tau, x, n, \nu) = \alpha_\nu^s(x) \left(\int_{\mathbb{S}^2} K(n, n') \varphi_0(\tau, x, n', \nu) dn' - \varphi_0(\tau, x, n, \nu) \right) & \tau > 0 \\ \partial_\tau T(\tau, x) = 0 & \tau > 0 \\ \varphi_0(0, x, n, \nu) = I_0(x, n, \nu) \\ T(0, x) = T_0(x). \end{cases} \quad (5.7)$$

On the one hand, we have $T(\tau, x) = T_0(x)$ for all $\tau > 0$, and on the other hand, we have

$$\varphi_0(\tau, x, n, \nu) = \exp(-\alpha_\nu^s(x)\tau(Id - H))I_0.$$

Using standard spectral theory for the compact self-adjoint operator $H \in \mathcal{L}(L^2(\mathbb{S}^2), L^2(\mathbb{S}^2))$, we see that the greatest eigenvalue of H is 1 with eigenfunctions being the constants. Hence, an application of the spectral gap theory and of the continuous functional calculus (cf. [47]) yields the limit

$$\lim_{\tau \rightarrow \infty} \varphi_0(\tau, x, n, \nu) = \varphi(x, \nu),$$

where φ is independent of $n \in \mathbb{S}^2$. Moreover, $\varphi(x, \nu) = \int_{\mathbb{S}^2} I_0(x, n, \nu) dn$. Indeed, integrating over \mathbb{S}^2 the first equation of (5.7), we obtain using that $\int_{\mathbb{S}^2} K(n, n') dn = 1$ the equation

$$\begin{cases} \partial_\tau \int_{\mathbb{S}^2} \varphi_0(\tau, x, n, \nu) dn = 0 & \tau > 0 \\ \int_{\mathbb{S}^2} \varphi_0(0, x, n, \nu) dn = \int_{\mathbb{S}^2} I_0(x, n, \nu) dn. \end{cases}$$

Hence, we conclude by the isotropy of φ

$$\int_{\mathbb{S}^2} I_0(x, n, \nu) dn = \int_{\mathbb{S}^2} \varphi_0(\tau, x, n, \nu) dn \xrightarrow{\tau \rightarrow \infty} \varphi(x, \nu).$$

The study of the Milne initial layer described by (5.7) has been rigorously studied in the context of the one-speed neutron transport equation in [9] and in [55], that is, when α_ν^s is independent of ν . While in [9] the behaviour of the neutron distribution for small times is analysed for general kernels using stochastic methods, in [55], equation (5.7) is solved for a very specific scattering kernel, namely, the constant kernel $K = \frac{1}{4\pi}$.

Moreover, there is also an initial thermalization layer. Indeed, under the rescaling $t = \varepsilon^{1-\beta} \tau$ for $\beta \in (-1, 1)$, $\gamma = -1$ and therefore $\tau_h = \frac{1}{\varepsilon}$, equation (5.3) becomes

$$\begin{cases} \partial_\tau I_\nu(\tau, x, n, \nu) + \varepsilon^{-\beta} n \cdot \nabla_x I_\nu(\tau, x, n) = \alpha_\nu^a(x) (B_\nu(T(\tau, x)) - I_\nu(\tau, x, n)) \\ \quad + \frac{\alpha_\nu^s(x)}{\varepsilon^{1+\beta}} \left(\int_{\mathbb{S}^2} K(n, n') I_\nu(\tau, x, n') dn' - I_\nu(\tau, x, n) \right) & \tau > 0 \\ \partial_\tau T(\tau, x) + \int_0^\infty dv \int_{\mathbb{S}^2} dn \partial_\tau I_\nu(\tau, x, n) + \varepsilon^{-\beta} \operatorname{div} \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn I_\nu(\tau, x, n) n \right) = 0 & \tau > 0 \end{cases} \quad (5.8)$$

As we have seen several times, the leading order φ_0 of I_ν in (5.8) is isotropic. Moreover, for $\beta \geq 0$ the term of order ε^β is also isotropic. Hence, the initial thermalization layer equation for

the leading order of the radiation intensity is given by

$$\begin{cases} \partial_\tau \varphi_0(\tau, x, \nu) = \alpha_\nu^a(x) (B_\nu(T(\tau, x)) - \varphi_0(\tau, x, \nu)) & \tau > 0 \\ \partial_\tau T(\tau, x) + \int_0^\infty d\nu \int_{\mathbb{S}^2} dn \partial_\tau \varphi_0(\tau, x, \nu) = 0 & \tau > 0 \\ \varphi_0(0, x, n, \nu) = \varphi(x, \nu) = \oint_{\mathbb{S}^2} I_0(x, n, \nu) dn \\ T(0, x) = T_0(x). \end{cases} \quad (5.9)$$

As for equation (5.4) arguing as in (5.5), we expect $\varphi_0(\tau, x, \nu) \rightarrow B_\nu(T_\infty(x))$ as $\tau \rightarrow \infty$ denoting by $T_\infty(x) = \lim_{\eta \rightarrow \infty} T(\tau, x)$.

(iv)+(v) Finally, in both cases $\ell_M \ll \ell_T = L$ and $\ell_M \ll L \ll \ell_T$, that is, in the non-equilibrium diffusion case, we observe the formation of only the initial Milne layer in which the radiation intensity becomes isotropic. In both cases, the initial Milne layer equation is once again (5.7).

We study now the boundary layers. We notice that in (5.3), $\partial_t I_\nu$ has relative order τ_h^{-1} compared to $n \cdot \nabla_x I_\nu$. Therefore, any rescaling of the space variable by $\xi = -\frac{x-p}{\varepsilon^\alpha} \cdot n_p$ for $\varepsilon^\alpha \in \{\ell_M = \varepsilon, \ell_T\} \ll L$ and $p \in \partial\Omega$ yields the boundary layer equations constructed in Section 4.2. Indeed, under such a procedure, the system becomes

$$\begin{cases} \frac{\varepsilon^\alpha}{\tau_h} \partial_t I_\nu(t, \xi, n; p) - (n \cdot n_p) \partial_\xi I_\nu(t, \xi, n; p) = \alpha_\nu^a(p + \mathcal{O}(\varepsilon^\alpha)) \varepsilon^{\beta+\alpha} (B_\nu(T(t, \xi; p)) - I_\nu(t, \xi, n; p)) \\ \quad + \alpha_\nu^s(p + \mathcal{O}(\varepsilon^\alpha)) \varepsilon^{\gamma+\alpha} \left(\int_{\mathbb{S}^2} K(n, n') I_\nu(t, \xi, n'; p) dn' - I_\nu(t, \xi, n; p) \right) \\ \partial_t T(t, \xi; p) + \partial_t \left(\int_0^\infty d\nu \int_{\mathbb{S}^2} dn I_\nu(t, \xi, n; p) \right) - \varepsilon^{-\alpha} \tau_h \partial_\xi \left(\int_0^\infty d\nu \int_{\mathbb{S}^2} dn (n \cdot n_p) I_\nu(t, \xi, n; p) \right) = 0 \\ I_\nu(0, \xi, n; p) = I_0(\xi, n, \nu; p) \\ T(0, \xi) = T_0(\xi) \\ I_\nu(t, 0, n; p) = g_\nu(t, n) \end{cases} \quad n \cdot n_p < 0. \quad (5.10)$$

Under these rescalings, we obtain, namely, the Milne problems (3.8) for $\ell_M = \ell_T \ll \ell_s$ and (3.16) for $\ell_M = \ell_T = \ell_s \ll L$. In the case $\ell_M \ll \ell_T \ll L$, there are two boundary layers appearing described by the Milne problem (3.25) and by the thermalization equation (3.30). Finally, if $\ell_M \ll L \lesssim \ell_T$, the Milne boundary layer is described by (3.25).

5.3. Limit problems in the bulk

We summarize now the PDEs, which are expected to be solved by the solution of (1.10) in the limit $\ell_M = \varepsilon \rightarrow 0$ for any different choice of ℓ_T as the speed of light is finite, that is, $c = 1$.

(i) In the case when $\ell_M = \ell_T \ll \ell_s$, the limit problem is given by

$$\begin{cases} \partial_t T(t, x) + 4\pi\sigma \partial_t T^4(t, x) - \frac{4\pi}{3} \operatorname{div} \left(\int_0^\infty \frac{\nabla_x B_\nu(T(t, x))}{\alpha_\nu(x)} d\nu \right) = 0 & t > 0, x \in \Omega \\ T(0, x) = T_\infty(x) & x \in \Omega \\ T(t, x) = \lim_{y \rightarrow \infty} \left(\int_0^\infty \alpha_\nu^a(p) I_\nu(t, y, n; p) \right) & p \in \partial\Omega, \end{cases}$$

where $I_\nu(t, y, n; p)$ is the solution to the Milne problem (3.8) for the boundary value $g_\nu(t, n)$ and $T_\infty(x) = \lim_{\tau \rightarrow \infty} T(\tau, x)$ is defined as the limit of the solution to the initial layer (5.4).

- (ii) If $\ell_M = \ell_T = \ell_S \ll L$, that is, $\ell_S = \ell_A = \varepsilon$ and $\tau_h = \varepsilon^{-1}$, the limit problem that describes the temperature in the interior of Ω for positive times is

$$\left\{ \begin{array}{l} \partial_t T(t, x) + 4\pi\sigma \partial_t T^4(t, x) \\ \quad = \operatorname{div} \left(\int_0^\infty dv \frac{1}{\alpha_v^a(x) + \alpha_v^s(x)} \left(\int_{\mathbb{S}^2} dn n \otimes (Id - A_{v,x})^{-1}(n) \right) \nabla_x B_v(T(t, x)) \right) \quad t > 0, x \in \Omega \\ T(0, x) = T_\infty(x) = \lim_{\tau \rightarrow \infty} T(\tau, x) \quad x \in \Omega \\ T(t, x) = \lim_{y \rightarrow \infty} \left(\int_0^\infty \alpha_v^a(p) I_v(t, y, n; p) \right) \quad p \in \partial\Omega, \end{array} \right.$$

where $I_v(t, y, n; p)$ is the solution to the Milne problem (3.16) for the boundary value $g_v(t, n)$ and $T(\tau, x)$ is the solution to the initial layer (5.6).

- (iii) We move now to the case $\ell_M \ll \ell_T \ll L$; hence, we consider $\ell_S = \varepsilon$ and $\ell_A = \varepsilon^{-\beta}$ for $\beta \in (-1, 1)$ and $\tau_h = \varepsilon^{-1}$. The limit problem is

$$\left\{ \begin{array}{l} \partial_t T(t, x) + 4\pi\sigma \partial_t T^4(t, x) \\ \quad = \operatorname{div} \left(\int_0^\infty dv \frac{1}{\alpha_v^s(x)} \left(\int_{\mathbb{S}^2} dn n \otimes (Id - H)^{-1}(n) \right) \nabla_x B_v(T(t, x)) \right) \quad t > 0, x \in \Omega \\ T(0, x) = T_\infty(x) = \lim_{\tau \rightarrow \infty} T(\tau, x) \quad x \in \Omega \\ T(t, p) = \lim_{y \rightarrow \infty} \left(\int_0^\infty dv \alpha_v^a(p) \varphi_0(t, \eta, v; p) \right) \quad p \in \partial\Omega, \end{array} \right.$$

where $T(\tau, x)$ solves the initial layer (5.9) and φ_0 is the solution to the thermalization problem (3.30).

- (iv) If $\ell_M \ll L = \ell_T$, the limit problem is

$$\left\{ \begin{array}{l} \partial_t \phi_0(t, x, v) - \operatorname{div} \left(\frac{1}{\alpha_v^s(x)} \left(\int_{\mathbb{S}^2} n \otimes (Id - H)^{-1}(n) dn \right) \nabla_x \phi_0(t, x, v) \right) \\ \quad = (B_v(T(t, x)) - \phi_0(t, x, v)) \quad x \in \Omega, t > 0 \\ \partial_t T(t, x) + 4\pi \int_0^\infty dv \alpha_v^a(x) (B_v(T(t, x)) - \phi_0(t, x, v)) = 0 \quad x \in \Omega, t > 0 \\ \phi(0, x, v) = \varphi(x, v) = \int_{\mathbb{S}^2} I_0(x, n, v) dn \\ T(0, x) = T_0(x) \quad x \in \Omega \\ \phi_0(t, p, v) = \lim_{y \rightarrow \infty} \int_{\mathbb{S}^2} I_v(t, y, n, p) \quad p \in \partial\Omega, t > 0, \end{array} \right. \quad (5.11)$$

where $I_v(t, y, n, p)$ solves the Milne problem (3.25) for the boundary value $g_v(t, n)$ and $\varphi(p, v) = \lim_{\tau \rightarrow \infty} \varphi_0(\tau, p, n, v)$ for the solution to (5.7).

- (v) Finally, if $\ell_M \ll L \ll \ell_T$, the limit problem is with the same notation as in (5.11)

$$\left\{ \begin{array}{l} \operatorname{div} \left(\frac{1}{\alpha_v^s(x)} \left(\int_{\mathbb{S}^2} n \otimes (Id - H)^{-1}(n) dn \right) \nabla_x \phi_0(t, x, v) \right) = 0 \quad x \in \Omega, t > 0 \\ \partial_t T(t, x) + 4\pi \int_0^\infty dv \alpha_v^a(x) (B_v(T(t, x)) - \phi_0(t, x, v)) = 0 \quad x \in \Omega, t > 0 \\ T(0, x) = T_0(x) \quad x \in \Omega \\ \phi_0(t, p, v) = \lim_{y \rightarrow \infty} \int_{\mathbb{S}^2} I_v(t, y, n, p) \quad p \in \partial\Omega, t > 0. \end{array} \right. \quad (5.12)$$

5.4. Initial-boundary layers

We conclude Section 5 by considering the initial-boundary layer equations, which can be found by studying (5.10). This equation shows that, on the one hand, under the space rescale $\xi = -\frac{x-p}{\varepsilon^\alpha} \cdot n_p$ for $p \in \partial\Omega$ and $\varepsilon^\alpha \in \{\ell_M, \ell_T\}$, the time derivative term $\partial_t I_v$ becomes of the same order of $\partial_\xi I_v$ rescaling the time by $t = \frac{\varepsilon^\alpha}{\tau_h} \tau$, and on the other hand, it becomes of the same order of the absorption-emission term if we consider $t = \frac{\tau}{\varepsilon^\beta \tau_h}$. It is not difficult to see that rescaling the space variable according to the Milne length $\ell_M = \varepsilon$, we obtain a non-trivial equation of the leading order of I_v in both time and space variables only rescaling the time by $t = \frac{\varepsilon}{\tau_h} \tau$. In the case $\ell_M \ll \ell_T \ll L$, that is, when $\ell_S = \varepsilon$ and $\ell_A = \varepsilon^{-\beta}$ with $\beta \in (-1, 1)$ and $\tau_h = \frac{1}{\varepsilon}$, a thermalization layer also appears. It is described for small times and for $x \in \Omega$ close to $\partial\Omega$ by the equation obtained by rescaling the space variable by $\ell_T = \varepsilon^{\frac{1-\beta}{2}}$ and the time variable in a suitable way so that the resulting equation is non-trivial in both variables. This is the case when $t = \varepsilon^{1-\beta} \tau$.

- (i) If $\ell_M = \ell_T \ll \ell_S$, that is, if $\beta = -1$ and $\gamma > -1$ and $\tau_h = \varepsilon^{-1}$, rescaling the spatial variable by $y = -\frac{x-p}{\varepsilon} \cdot n_p$ for $p \in \partial\Omega$ and under the time rescaling $t = \varepsilon^2 \tau$, we obtain the initial-boundary layer equation

$$\left\{ \begin{array}{ll} \partial_\tau I_v(\tau, y, n; p) - (n \cdot n_p) \partial_y I_v(\tau, y, n; p) = \alpha_v^a(p)(B_v(T(\tau, y)) - I_v(\tau, y, n; p)) & y > 0, \tau > 0 \\ \partial_\tau T(\tau, y) + \int_0^\infty dv \int_{\mathbb{S}^2} dn \partial_\tau I_v(\tau, y, n; p) \\ \quad - \partial_y \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn (n \cdot n_p) I_v(\tau, y, n; p) \right) = 0 & y > 0, \tau > 0 \\ I_v(0, y, n; p) = I_0(p, n, v) & y > 0 \\ T(0, y; p) = T_0(p) & y > 0 \\ I_v(\tau, 0, n; p) = g_v(0, n) & n \cdot n_p < 0, \tau > 0. \end{array} \right.$$

- (ii) In the case $\ell_M = \ell_T = \ell_S$, we rescale again the variables according to $y = -\frac{x-p}{\ell_M} \cdot n_p$ for $p \in \partial\Omega$ and $t = \varepsilon^2 \tau$, and we obtain the following initial-boundary layer equation

$$\left\{ \begin{array}{ll} \partial_\tau I_v(\tau, y, n; p) - (n \cdot n_p) \partial_y I_v(\tau, y, n; p) = \alpha_v^a(p)(B_v(T(\tau, y)) - I_v(\tau, y, n; p)) \\ \quad + \alpha_v^s \left(\int_{\mathbb{S}^2} K(n, n') I_v(\tau, y, n'; p) dn' - I_v(\tau, y, n; p) \right) & y > 0, \tau > 0 \\ \partial_\tau T(\tau, y) + \int_0^\infty dv \int_{\mathbb{S}^2} dn \partial_\tau I_v(\tau, y, n; p) \\ \quad - \partial_y \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn (n \cdot n_p) I_v(\tau, y, n; p) \right) = 0 & y > 0, \tau > 0 \\ I_v(0, y, n; p) = I_0(p, n, v) & y > 0 \\ T(0, y; p) = T_0(p) & y > 0 \\ I_v(\tau, 0, n; p) = g_v(0, n) & n \cdot n_p < 0, \tau > 0. \end{array} \right.$$

- (iii) If $\ell_M \ll \ell_T \ll L$, there are two initial-boundary layers appearing. In order to find the initial-boundary layer equation describing the transition from T_∞ to $\lim_{y \rightarrow \infty} \left(\int_0^\infty dv \alpha_v^a(p) \varphi_0(t, \eta, v; p) \right)$,

we rescale first the space variable according to $\eta = \frac{x-p}{\ell_T} \cdot n_p$ for $p \in \partial\Omega$ with $\ell_T = \varepsilon^{\frac{1-\beta}{2}}$ and the time variable according to $t = \varepsilon^{1-\beta} \tau$, and following the same computations as we did in Section 4 in equation (4.17), we obtain the initial-boundary layer equation

$$\left\{ \begin{array}{ll} \partial_\tau \varphi_0(\tau, \eta, \nu; p) - \frac{1}{\alpha_v^s(p)} \left(\int_{\mathbb{S}^2} (n \cdot n_p) (Id - H)^{-1}(n) \cdot n_p \, dn \right) \partial_\eta^2 \varphi_0(\tau, \eta, \nu; p) \\ \quad = \alpha_v^a(p) (B_v(T(\tau, \eta; p)) - \varphi_0(\tau, \eta, \nu; p)) & \eta > 0, \tau > 0 \\ \partial_\tau T(\tau, \eta; p) + \int_0^\infty dv \int_{\mathbb{S}^2} dn \alpha_v^a(p) (B_v(T(\tau, \eta; p)) - \varphi_0(\tau, \eta, \nu; p)) = 0 & \eta > 0, \tau > 0 \\ \varphi_0(0, \eta, \nu; p) = \varphi(p, \nu) = \int_{\mathbb{S}^2} I_0(p, n, \nu) dn & \eta > 0 \\ T(0, \eta; p) = T_0(p) & \eta > 0 \\ \varphi_0(\tau, 0, \nu; p) = I(0, \nu; p) & n \cdot n_p < 0, \tau > 0, \end{array} \right.$$

where we used $I(0, \nu; p) = \lim_{y \rightarrow \infty} I_v(0, y, n; p)$ for the solution to the Milne problem (3.25) and also $\varphi(p, \nu) = \lim_{\tau \rightarrow \infty} \varphi_0(\tau, p, n, \nu)$ for the solution to (5.7).

Rescaling now both space and time variables according to $y = \frac{x-p}{\varepsilon} \cdot n_p$ for $p \in \partial\Omega$ and $t = \varepsilon^2 \tau$, we obtain another initial-boundary layer equation, which explains the transition from $I(0, \nu; p)$ to $\varphi(p, \nu)$. This is given by the following equation

$$\left\{ \begin{array}{ll} \partial_\tau I_v(\tau, y, n; p) - (n \cdot n_p) \partial_y I_v(\tau, y, n; p) \\ \quad = \alpha_v^s \left(\int_{\mathbb{S}^2} K(n, n') I_v(\tau, y, n'; p) \, dn' - I_v(\tau, y, n; p) \right) & y > 0, \tau > 0 \\ \partial_\tau T(\tau, y) = 0 & y > 0, \tau > 0 \\ I_v(0, y, n; p) = I_0(p, n, \nu) & y > 0 \\ T(0, y; p) = T_0(p) & y > 0 \\ I_v(\tau, 0, n; p) = g_v(0, n) & n \cdot n_p < 0, \tau > 0. \end{array} \right. \quad (5.13)$$

(iv)+(v) If $\ell_T \gtrsim L$ under the rescaling $y = \frac{x-p}{\varepsilon} \cdot n_p$ for $p \in \partial\Omega$ and $t = \varepsilon^2 \tau$, we obtain the problem (5.13) as initial-boundary layer equation.

(v) Moreover, in the case $\ell_T \gg L$, we notice in equation (5.12) that the leading order ϕ_0 of the radiation intensity solves a stationary equation. The transition from the solution of a time-dependent equation, as in the original problem, to the solution of a stationary equation happens in times of order $\varepsilon^{\beta-1}$. Indeed, under a time rescaling $t = \varepsilon^{\beta-1} \tau = \frac{\tau}{\tau_h \varepsilon}$, we obtain the following equation solved by the leading order ϕ_0 in the bulk

$$\left\{ \begin{array}{ll} \partial_\tau \phi_0(\tau, x, \nu) - \operatorname{div} \left(\frac{1}{\alpha_v^s(x)} \left(\int_{\mathbb{S}^2} n \otimes (Id - H)^{-1}(n) \, dn \right) \nabla_x \phi_0(\tau, x, \nu) \right) = 0 & x \in \Omega, \tau > 0 \\ \partial_\tau T(\tau, x) = 0 & x \in \Omega, \tau > 0 \\ \phi(0, x, \nu) = \varphi(x, \nu) = \int_{\mathbb{S}^2} I_0(x, n, \nu) dn & x \in \Omega \\ T(0, x) = T_0(x) & x \in \Omega \\ \phi_0(\tau, p, \nu) = \lim_{y \rightarrow \infty} \int_{\mathbb{S}^2} I_v(\tau, y, n, p) & p \in \partial\Omega, \tau > 0, \end{array} \right. \quad (5.14)$$

where $\varphi(x, \nu)$ is defined by the initial layer equation (5.7). This equation can be derived in the same way as the outer problem (5.2), taking into account that under this time scale, the term containing $\partial_\tau I_v$ is of order $\varepsilon^{1-\beta} \gg \varepsilon^0$. Moreover, the second equation in (1.10) also gives $\partial_\tau T = 0$ since the absorption-emission terms are of order $\varepsilon^0 \ll \varepsilon^{1-\beta}$.

6. Time-dependent diffusion approximation: the case of non-dimensional speed of light scaling as a power law of the Milne length

In this last section, we repeat all the procedures used in Sections 3, 4 and 5, and we construct the limit problem solved by the solution of the time-dependent equation (1.10) when $\ell_M = \varepsilon \rightarrow 0$ and in the case in which the speed of light is a power-law of the form $c = \varepsilon^{-\kappa}$ for $\kappa > 0$. The strategy is the same as in Section 5. It will turn out that the limit problems valid at the interior of the domain Ω and for positive times are the same as the one we found in the case of infinite speed of light. On the other hand, unlike the case of infinite speed of light, in this case, time layers also appear in regions far from the boundary. Similarly as in Sections 4 and 5, the boundary layer equations are stationary and are the same equations constructed in Section 3. Finally, we will summarize the initial-boundary value problems that we have obtained, and we will construct the initial-boundary layer equations that we have to consider in order to describe the behaviour of the solution for small times in regions close to the boundary.

6.1. Outer problems

We consider equation (1.10) in the case $c = \varepsilon^{-\kappa}$, $\kappa > 0$. In order to find the outer problems solved in the limit, we proceed as we did in the previous three sections. It turns out that the outer problems are the same evolution equations obtained for the infinite speed of light case. Indeed, under the assumption $c = \varepsilon^{-\kappa}$ and $\ell_A = \varepsilon^{-\beta}$, $\ell_S = \varepsilon^{-\gamma}$ with $\min\{\alpha, \gamma\} = -1$, equation (1.10) becomes

$$\left\{ \begin{array}{ll} \varepsilon^\kappa \partial_t I_v(t, x, n) + \tau_h n \cdot \nabla_x I_v(t, x, n) = \alpha_v^\alpha(x) \varepsilon^\beta \tau_h (B_v(T(t, x)) - I_v(t, x, n)) \\ \quad + \alpha_v^\gamma(x) \varepsilon^\gamma \tau_h \left(\int_{\mathbb{S}^2} K(n, n') I_v(t, x, n') dn' - I_v(t, x, n) \right) & x \in \Omega, n \in \mathbb{S}^2, t > 0 \\ \partial_t T + \varepsilon^\kappa \partial_t \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn I_v(t, n, x) \right) \\ \quad + \tau_h \operatorname{div} \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn n I_v(t, n, x) \right) = 0 & x \in \Omega, n \in \mathbb{S}^2, t > 0 \\ I_v(0, x, n) = I_0(x, n, v) & x \in \Omega, n \in \mathbb{S}^2 \\ T(0, x) = T_0(x) & x \in \Omega \\ I_v(t, n, x) = g_v(t, n) & x \in \partial\Omega, n \cdot n_x < 0, t > 0. \end{array} \right. \quad (6.1)$$

Then, plugging the usual expansion (4.1) for I_v into equation (6.1) and identifying all terms of the same power of ε give the same results as in Section 4. This is due to the fact that in the first equation of (6.1), the term involving the time derivative of the radiation intensity is of order ε^κ , and hence, it is much smaller than $\varepsilon^0 \ll \varepsilon^{-1} \ll \tau_h \varepsilon^{-1}$, that is, the orders of magnitude which lead to the first terms in the expansion $I_v(t, x, n) = \phi_0(t, x, v) + \varepsilon \phi_1(t, x, n, v) + \varepsilon^\delta \psi_1 + \dots$ if $\delta < 1$. As we noticed in the previous sections, ϕ_0 is isotropic, and as long as $\ell_T \ll L$, it is the Planck distribution $B_v(T)$. Since, in the second equation of (6.1), the leading term containing $\partial_t T$ is also of order 1, the term $\varepsilon^\kappa \partial_t \int_0^\infty dv \int_{\mathbb{S}^2} dn I_v$ is negligible. Hence, the outer problems are, as in Section 4, equation (4.2) for $\ell_M = \ell_T \ll \ell_S$, equation (4.3) for $\ell_M = \ell_T = \ell_S$, equation (4.4) for $\ell_M \ll \ell_T \ll L$, the system (4.5) for $\ell_M \ll L = \ell_T$ and the system (4.6) for $\ell_M \ll L \ll \ell_T$.

6.2. Initial layer equations and boundary layer equations

In contrast to Section 4 (i.e. the case $c = \infty$), besides the formation of boundary layers, time layers also appear. The equations describing them can be obtained similarly as in Section 5. The first equation in

(6.1) has leading order $\tau_h \varepsilon^{-1}$; hence, a time rescaling $t = \frac{\varepsilon^{1+\kappa}}{\tau_h} \tau$ gives

$$\partial_\tau I_\nu = \varepsilon^{\beta+1} \alpha_\nu^a(x) (B_\nu(T) - I_\nu) + \varepsilon^{\gamma+1} \alpha_\nu^s(x) \left(\int_{\mathbb{S}^2} K(n, n') I_\nu dn' - I_\nu \right) - \varepsilon n \cdot \nabla_x I_\nu$$

and

$$\varepsilon^{-\kappa} \partial_\tau T + \partial_\tau \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn I_\nu \right) + \varepsilon \operatorname{div} \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn n I_\nu \right) = 0,$$

which implies $\partial_\tau T = 0$ at the leading order. Hence, an initial layer of thickness of order $\frac{\varepsilon^{1+\kappa}}{\tau_h}$ is appearing for any choice of ℓ_A and ℓ_S . This is the so-called initial Milne layer.

(i) If $\ell_M = \ell_T \ll \ell_S$, the initial Milne layer is described by

$$\begin{cases} \partial_\tau \varphi_0(\tau, x, n, \nu) = \alpha_\nu^a(x) (B_\nu(T_0(x)) - \varphi_0(\tau, x, n\nu)) & \text{if } \tau > 0 \\ \varphi_0(0, x, n, \nu) = I_0(x, n, \nu). \end{cases} \quad (6.2)$$

Therefore, as $\tau \rightarrow \infty$, we obtain using a simple ODE argument $\lim_{\tau \rightarrow \infty} \varphi_0(\tau, x, n, \nu) = B_\nu(T_0(x))$.

(ii) In the case $\ell_M = \ell_T = \ell_S$ and hence $\tau_h = \frac{1}{\varepsilon}$ with the scaling $t = \tau \varepsilon^{2+\kappa}$, we obtain on the one hand $\partial_\tau T = 0$ and on the other hand for the first order φ_0 the identity

$$\partial_\tau \varphi_0(\tau, x, n, \nu) = \alpha_\nu^a(x) (B_\nu(T_0(x)) - \varphi_0(\tau, x, n\nu)) + \alpha_\nu^s(x) \left(\int_{\mathbb{S}^2} K(n, n') \varphi_0(\tau, x, n', \nu) dn' - \varphi_0(\tau, x, n, \nu) \right).$$

Again, using semigroup theory, we can write the solution as

$$\varphi_0 = e^{-\alpha_\nu^a(x)\tau} \left(e^{-\alpha_\nu^s(x)\tau} I_0 \right) + (1 - e^{-\alpha_\nu^a(x)\tau}) B_\nu(T_0).$$

Hence, we have once more $\lim_{\tau \rightarrow \infty} \varphi_0(\tau, x, n, \nu) = B_\nu(T_0(x))$.

(iii) For all cases $\ell_M \ll \ell_T \ll L$, that is, $\ell_S = \varepsilon$ and $\ell_A = \varepsilon^{-\beta}$ for $\beta \in (-1, 1)$ and $\tau_h = \frac{1}{\varepsilon}$, under the scaling $t = \tau \varepsilon^{2+\kappa}$, we have the initial Milne layer equation

$$\begin{cases} \partial_\tau \varphi_0(\tau, x, n, \nu) = \alpha_\nu^s(x) \left(\int_{\mathbb{S}^2} K(n, n') \varphi_0(\tau, x, n', \nu) dn' - \varphi_0(\tau, x, n, \nu) \right) & \tau > 0 \\ \partial_\tau T(\tau, x) = 0 & \tau > 0 \\ \varphi_0(0, x, n, \nu) = I_0(x, n, \nu) \\ T(0, x) = T_0(x). \end{cases} \quad (6.3)$$

This is exactly the same equation as (5.7). Thus, an application of spectral theory implies again

$$\lim_{\tau \rightarrow \infty} \varphi_0(\tau, x, n, \nu) = \varphi(x, \nu) = \int_{\mathbb{S}^2} I_0(x, n, \nu) dn.$$

However, as for the finite speed of light case, there is also a thermalization layer appearing. Indeed, with a time rescaling $t = \varepsilon^{1-\beta+\kappa} \tau$, the term involving $\partial_\tau I_\nu$ becomes of the same order as the emission-absorption term according to

$$\begin{cases} \partial_\tau I_\nu(\tau, x, n) + \varepsilon^{-\beta} n \cdot \nabla_x I_\nu(\tau, x, n) = \alpha_\nu^a(x) (B_\nu(T(x)) - I_\nu(\tau, x, n)) \\ \quad + \frac{\alpha_\nu^s(x)}{\varepsilon^{1+\beta}} \left(\int_{\mathbb{S}^2} K(n, n') I_\nu(\tau, x, n') dn' - I_\nu(\tau, x, n) \right) \\ \frac{1}{\varepsilon^\kappa} \partial_\tau T(\tau, x) + \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn \partial_\tau I_\nu(\tau, x, n) \right) + \varepsilon^{-\beta} \operatorname{div} \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn n I_\nu(\tau, x, n) \right) = 0. \end{cases} \quad (6.4)$$

Hence, as we have seen in (5.8), the leading order φ_0 of I_ν in (6.4) is isotropic, as well as the term of order ε^β for $\beta \geq 0$. Moreover, once more, the temperature T is just the initial temperature

$T_0(x)$ to the leading order. This yields the initial thermalization layer equation

$$\begin{cases} \partial_\tau \varphi_0(\tau, x, v) = \alpha_v^a(x) (B_v(T_0(x)) - \varphi_0(\tau, x, v)) & \tau > 0 \\ \varphi_0(0, x, v) = \varphi(x, v). \end{cases}$$

Hence, similarly to (6.2), we have $\lim_{\tau \rightarrow \infty} \varphi_0 = B_v(T_0(x))$ as $\tau \rightarrow \infty$.

(iv)+(v) For the cases $\ell_M \ll L \lesssim \ell_T$, the initial Milne layer equation is obtained again by rescaling the time variable by $t = \frac{\varepsilon^{1+\kappa}}{\tau_h} \tau$, and it is given by equation (6.3).

For the boundary layer equations, we argue similarly as in the case $c = \infty$ and c bounded. Rescaling the space variable by $\xi = -\frac{x-p}{\varepsilon^\alpha} \cdot n_p$ for $\varepsilon^\alpha \in \{\ell_M, \ell_T\}$ and $p \in \partial\Omega$, equation (6.1) becomes

$$\begin{cases} -(n \cdot n_p) \partial_\xi I_v(t, \xi, n; p) = \alpha_v^a(p + \mathcal{O}(\varepsilon^\alpha)) \frac{\varepsilon^\alpha}{\ell_A} (B_v(T) - I_v) \\ \quad + \frac{\varepsilon^\alpha}{\ell_S} \alpha_v^s(p + \mathcal{O}(\varepsilon^\alpha)) \left(\int_{\mathbb{S}^2} K(n, n') I_v dn' - I_v \right) - \frac{\varepsilon^{\alpha+\kappa}}{\tau_h} \partial_t I_v(t, \xi, n) + \varepsilon^{2\alpha} \dots & \xi > 0 \\ \partial_t T(t, \xi; p) + \varepsilon^\kappa \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn \partial_t I_v \right) + \varepsilon^{-\alpha} \tau_h \operatorname{div} \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn n I_v \right) = 0 & \xi > 0 \\ I_v(0, \xi, n; p) = I_0(p, n, v) \\ T(0, \xi; p) = T_0(p) \\ I_v(t, 0, n; p) = g_v(t, n) \end{cases} \quad n \cdot n_p < 0. \quad (6.5)$$

Therefore, the boundary layers are described by the same stationary equations that we constructed in Section 3. Indeed, we obtain for $\ell_M = \ell_T \ll \ell_S$ the Milne problem (3.8) and for $\ell_M = \ell_T = \ell_S \ll L$ the Milne problem (3.16). The two boundary layers appearing in the case $\ell_M \ll \ell_T \ll L$ are described by the Milne problem (3.25) and by the thermalization equation (3.30). Finally, if $\ell_M \ll L \lesssim \ell_T$, the Milne problems are given by (3.25).

6.3. Limit problems in the bulk

We now summarize the PDE problems which are expected to be solved by the solution of (1.10) when $c = \varepsilon^{-\kappa}$, $\kappa > 0$ in the limit $\ell_M = \varepsilon \rightarrow 0$ for any choice of ℓ_A and ℓ_S . Matching the solution to the outer problems valid in the bulk for positive times $t > 0$ with the solution to the initial layer equations and boundary layer equations, we obtain as a limit equation exactly the same PDE problems in Section 4. Indeed, on the one hand, the boundary layer problems are exactly the Milne and thermalization problems constructed for the stationary problem and are also valid for the time-dependent problem. On the other hand, in the initial layer equations derived in the previous Subsection 6.2, the temperature is constant; hence, it is $T = T_0$, the same result that we obtained in the case $c = \infty$ in Subsection 4.2. Therefore, since the outer problems coincide in both cases when $c = \infty$ and $c = \varepsilon^{-\kappa}$ with $\kappa > 0$ and $\varepsilon \rightarrow 0$, we conclude as in Section 4 that the limit PDE problems are given by (4.11) if $\ell_M = \ell_T \ll \ell_S$, by (4.12) if $\ell_M = \ell_T = \ell_S$, by (4.13) if $\ell_M \ll \ell_T \ll L$, by (4.14) if $\ell_M \ll L = \ell_T$ and finally by (4.15) if $\ell_M \ll L \ll \ell_T$.

6.4. Initial-boundary layers

As in Sections 4 and 5, we will derive the initial-boundary layer equations, which describe the behaviour of the solutions for very small times and in regions close to the boundary. The initial-boundary layer equations are obtained by rescaling in a suitable way the space and time variables. Considering equation (6.5) resulting from the space rescale according to the Milne length or the thermalization length, we notice that the term involving the time derivative of the radiation intensity has order $\frac{\varepsilon^{\alpha+\kappa}}{\tau_h}$. Hence, the initial-boundary Milne layer equation is obtained by the rescaling $y = -\frac{x-p}{\varepsilon} \cdot n_p$ and $t = \frac{\varepsilon^{1+\kappa}}{\tau_h} \tau$ for $p \in \partial\Omega$.

In the case $\ell_M \ll \ell_T \ll L$ (i.e. when $\ell_A = \varepsilon^\beta$ for $\beta \in (-1, 1)$, $\ell_S = \varepsilon$ and $\tau_h = \frac{1}{\varepsilon}$), the initial-boundary thermalization equation is obtained by rescaling $\eta = -\frac{x-p}{\ell_T} \cdot n_p$ and $t = \varepsilon^{1-\beta+\kappa}$, where $\ell_T = \varepsilon^{-\frac{1-\beta}{2}}$ and $p \in \partial\Omega$.

- (i) If $\ell_M = \ell_T \ll \ell_S$, rescaling the spatial variable by $y = -\frac{x-p}{\varepsilon} \cdot n_p$ for $p \in \partial\Omega$ and the time variable by $t = \varepsilon^{2+\kappa} \tau$, we see that the initial-boundary layer equation is given by

$$\begin{cases} \partial_\tau I_v(\tau, y, n; p) - (n \cdot n_p) \partial_y I_v(\tau, y, n; p) = \alpha_v^a(p)(B_v(T_0(p)) - I_v(\tau, y, n; p)) & y > 0, \tau > 0 \\ I_v(0, y, n; p) = I_0(p, n, v) & y > 0, \tau > 0 \\ I_v(\tau, 0, n; p) = g_v(0, n) & n \cdot n_p < 0, \tau > 0, \end{cases}$$

where we used that equation

$$\begin{cases} \frac{1}{\varepsilon^\kappa} \partial_\tau T(\tau, y) + \partial_\tau \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn I_v(\tau, y, n; p) \right) \\ = \partial_y \left(\int_0^\infty dv \int_{\mathbb{S}^2} dn (n \cdot n_p) I_v(\tau, y, n; p) \right) & y > 0, \tau > 0 \\ T(0, y; p) = T_0(p) & y > 0, \end{cases} \quad (6.6)$$

implies $T(\tau, y; p) = T_0(p)$.

- (ii) If $\ell_M = \ell_T = \ell_S$, rescaling the variables according to $y = -\frac{x-p}{\varepsilon} \cdot n_p$ for $p \in \partial\Omega$ and $t = \varepsilon^{2+\kappa} \tau$, we obtain the following initial-boundary layer equation

$$\begin{cases} \partial_\tau I_v(\tau, y, n; p) - (n \cdot n_p) \partial_y I_v(\tau, y, n; p) = \alpha_v^a(p)(B_v(T_0(p)) - I_v(\tau, y, n; p)) \\ + \alpha_v^s \left(\int_{\mathbb{S}^2} K(n, n') I_v(\tau, y, n'; p) dn' - I_v(\tau, y, n; p) \right) & y > 0, \tau > 0 \\ I_v(0, y, n; p) = I_0(p, n, v) & y > 0 \\ I_v(\tau, 0, n; p) = g_v(0, n) & n \cdot n_p < 0, \tau > 0, \end{cases}$$

where we used (6.6) again.

- (iii) If $\ell_M \ll \ell_T \ll L$, there are again two different initial-boundary layers. We consider first the thermalization problem. We hence rescale the space variable according to $\eta = \frac{x-p}{\varepsilon^{\frac{1-\beta}{2}}} \cdot n_p$ for $p \in \partial\Omega$ and the time variable according to $t = \varepsilon^{\kappa+1-\beta} \tau$. Following the same computations as we did in Section 4 in equation (4.17) and using a similar argument as in (6.6), we obtain the following initial-boundary layer equation

$$\begin{cases} \partial_\tau \varphi_0(\tau, \eta, v; p) - \frac{1}{\alpha_v^s(p)} \left(\oint_{\mathbb{S}^2} (n \cdot n_p)(Id - H)^{-1}(n) \cdot n_p dn \right) \partial_\eta^2 \varphi_0(\tau, \eta, v; p) \\ = \alpha_v^a(p) (B_v(T_0(p)) - \varphi_0(\tau, \eta, v; p)) & \eta > 0, \tau > 0 \\ \varphi_0(0, \eta, v; p) = \varphi(p, v) & \eta > 0 \\ \varphi_0(\tau, 0, v; p) = I(0, v; p) & p \in \partial\Omega, \tau > 0, \end{cases}$$

where $I(0, v; p) = \lim_{y \rightarrow \infty} I_v(0, y, n; p)$ for the solution to the Milne problem (3.25) for the boundary value $g_v(t, n)$ and $\varphi(p, v) = \lim_{\tau \rightarrow \infty} \varphi_0(\tau, p, n, v)$ for the solution to (6.3).

As we have seen in Section 5, there is another initial-boundary value equation that describes the transition from the initial value $\varphi(x, v)$ to the boundary value $I(0, v; p)$. This is obtained by rescaling the space variable according to $y = \frac{x-p}{\varepsilon} \cdot n_p$ for $p \in \partial\Omega$ and the time variable according

to $t = \varepsilon^{\kappa+2} \tau$. Hence, using (6.6), we obtain

$$\begin{cases} \partial_\tau I_v(\tau, y, n; p) - (n \cdot n_p) \partial_y I_v(\tau, y, n; p) \\ \qquad \qquad \qquad = \alpha_v^s \left(\int_{\mathbb{S}^2} K(n, n') I_v(\tau, y, n'; p) dn' - I_v(\tau, y, n; p) \right) & y > 0, \tau > 0 \\ I_v(0, y, n; p) = I_0(p, n, v) & y > 0 \\ I_v(\tau, 0, n; p) = g_v(0, n) & n \cdot n_p < 0, \tau > 0. \end{cases}$$

(iv) In the case $\ell_M \ll \ell_T = L$, rescaling $\eta = \frac{x-p}{\varepsilon} \cdot n_p$ for $p \in \partial\Omega$ and $t = \varepsilon^{2+\kappa} \tau$, we also obtain the initial-boundary layer equation for this case

$$\begin{cases} \partial_\tau I_v(\tau, y, n; p) - (n \cdot n_p) \partial_y I_v(\tau, y, n; p) \\ \qquad \qquad \qquad = \alpha_v^s \left(\int_{\mathbb{S}^2} K(n, n') I_v(\tau, y, n'; p) dn' - I_v(\tau, y, n; p) \right) & y > 0, \tau > 0 \\ I_v(0, y, n; p) = I_0(p, n, v) & y > 0 \\ I_v(\tau, 0, n; p) = g_v(0, n) & n \cdot n_p < 0, \tau > 0. \end{cases} \quad (6.7)$$

Similar to the case where $\ell_T \gg 1$ and $c = 1$ in Section 5, we notice that the radiation intensity I_v has a transition from a solution of a time-dependent equation, as it was in the original problem (1.10), to a solution of a stationary equation, as it is in (4.14). This transition takes place at times of order ε^κ . Indeed, under the time rescaling $t = \varepsilon^\kappa \tau$, we obtain the following equation for the leading order ϕ_0 of I_v for all $x \in \Omega$

$$\begin{cases} \partial_\tau \phi_0(\tau, x, v) - \operatorname{div} \left(\frac{1}{\alpha_v^s(x)} \left(\oint_{\mathbb{S}^2} n \otimes (Id - H)^{-1}(n) dn \right) \nabla_x \phi_0(\tau, x, v) \right) \\ \qquad \qquad \qquad = (B_v(T(\tau, x)) - \phi_0(\tau, x, v)) & x \in \Omega, \tau > 0 \\ \partial_\tau T(\tau, x) = 0 & x \in \Omega, \tau > 0 \\ \phi(0, x, v) = \varphi(x, v) & x \in \Omega \\ T(0, x) = T_0(x) & x \in \Omega \\ \phi_0(\tau, p, v) = \lim_{y \rightarrow \infty} \oint_{\mathbb{S}^2} I_v(0, y, n, p) & p \in \partial\Omega, \tau > 0, \end{cases} \quad (6.8)$$

where $I_v(0, y, n, p)$ solves the Milne problem (3.25) for the boundary value $g_v(0, n)$, and we used the notation $\varphi(x, v) = \lim_{\tau \rightarrow \infty} \phi_0(\tau, x, n, v)$ for the solution to (6.3). In order to derive equation (6.8), we notice that under the time rescale $t = \varepsilon^\kappa \tau$, the term in the first equation of (1.10) containing $\partial_\tau I_v$ becomes of order ε^0 as the absorption-emission term. This implies the first equation in (6.8) as we did in Section 5 for (5.1). On the other hand, in the second equation of (6.8), the leading term is $\partial_\tau T$ of order $\varepsilon^{-\kappa} \gg \varepsilon^0$.

(v) Finally, if $\ell_M \ll L \ll \ell_T$, the initial-boundary layer equation is again (6.7). Also, for this last case, we notice that the leading order ϕ_0 of I_v , which solves a time-dependent equation (1.10), solves in the limit a stationary equation (4.15). The transition from time-dependent solution to stationary solution takes place at times of order $\varepsilon^{\beta-1+\kappa}$. Under the time rescale $t = \varepsilon^{\beta-1+\kappa} \tau$, we derive, in the same way as for equation (5.14), the equation solved by ϕ_0 in the bulk describing this transition. It turns out that it is exactly given by (5.14) for the initial condition $\phi(0, x, v) = \varphi(x, v)$ given by the solution to (6.3).

7. Concluding remarks

In this paper, we considered the problem of describing the temperature distribution in a body where the heat is transported only by radiation. We considered the case where the mean free path of the radiative process tends to zero, that is, $\ell_M \rightarrow 0$. Therefore, we coupled the radiative transfer equation (1.1) with the energy balance equation (1.2), and we studied the diffusion approximation for the time-dependent equations (1.10) and (1.11) and the stationary equation (1.12).

For all different scaling limit regimes, using the method of asymptotic expansions, we derived the full limit models describing the temperature of the body and the radiation intensity. The resulting models have been classified depending on the form of the radiation intensity at the leading order in the bulk of the domain. The cases where the isotropic leading order of the radiation intensity is given by the Planck distribution for the temperature yield the equilibrium diffusion approximation, while the models in which the radiation intensity is not approximated by the Planck distribution are denoted by non-equilibrium diffusion approximation. Notice that the diffusion approximation is valid only in the bulk of the domain Ω where the leading order of the radiation intensity is isotropic. On the other hand, at the boundary layers and at the initial layers, the diffusion approximation fails. We also described for each considered case the boundary and initial layers appearing. Moreover, a summary of the available results about the diffusion approximation and the boundary layer problems for similar settings is included. Many of the derived problems in this article still need to be studied.

For the time-dependent problem, we studied three different cases. First, we analysed the problem for the speed of light assumed to be $c = \infty$, that is, when the transport of radiation can be assumed to be instantaneous. We then considered the case where the speed of light is of order 1, that is, when the time used by the light for spanning distances of order 1 is of the same order as the time needed by the temperature for having meaningful changes. Finally, we studied the case where the speed of light scales as a power law of the Milne length, that is, $c = \varepsilon^{-\kappa}$ for $\kappa > 0$ and $\ell_M = \varepsilon$.

7.1. A numerical simulation showing the Milne layer

We have not attempted in this paper to do systematic numerical simulations of all the asymptotic regimes considered in these pages. However, we have computed a particular example. This corresponds to a stationary one-dimensional problem for which scattering and absorption lengths are comparable, the scattering kernel is constant and the scattering and absorption coefficients are constant, that is, the so-called grey approximation. In this case, the problem is equivalent to a one-speed neutron transport equation (cf. equation (1.13)), and it is given by

$$\begin{cases} n\partial_x J(x, n) = \frac{1}{\varepsilon} \left(\frac{1}{2} \int_{-1}^1 J(x, n') dn' - J(x, n) \right) & x \in (0, 1), \quad n \in [-1, 1], \\ J(0, n) = n & n > 0, \\ J(1, n) = 0 & n < 0, \end{cases} \quad (7.1)$$

where $J(x, n) = \int_0^\infty I_\nu(x, n) d\nu$. Problem (7.1) can be solved numerically by discretizing both variables x and n and using an upwind scheme in order to approximate the transport term. For more details on the problem and on the numerical scheme, we refer to Appendix B.

The numerical result exhibits the expected behaviour, that is, the onset of a Milne layer close to the boundary $x = 0$ in which $J(x, n)$ becomes isotropic. Moreover, in the bulk of the domain, $J(x, n)$ is linear, solving the Laplace equation. This is due to the fact that in this region, the diffusion approximation holds.

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Appendix A. Proof of Proposition 2.1

We prove now Proposition 2.1. To this end, we need the following auxiliary Lemma.

Lemma A.1. *Let $K \in C(\mathbb{S}^2 \times \mathbb{S}^2)$, invariant under rotations, non-negative and satisfying*

$$\int_{\mathbb{S}^2} K(n, n') dn = 1.$$

Let $n, \omega \in \mathbb{S}^2$. Then there exists finitely many $n_1, \dots, n_N \in \mathbb{S}^2$ such that

$$K(n_{i-1}, n_i) > 0 \text{ for all } i \in \{1, \dots, N+1\}, \quad (\text{A.1})$$

where we defined $n_0 = n$ and $n_{N+1} = \omega$.

Proof. Since $K \geq 0$ but it is not equal zero, there exists a pair $n', n'' \in \mathbb{S}^2$ such that $K(n', n'') > 0$. Hence, applying the rotation $\mathcal{R}_{n,n'}$ yields the existence of n_* such that $K(n, n_*) > 0$. By continuity, the set $B_n = \{\tilde{n} \in \mathbb{S}^2 : K(n, \tilde{n}) > 0\}$ is open. Hence, there exists $\delta > 0$ and $n_1 \in \mathbb{S}^2$ such that $B_\delta(n_1) \subset B_n$. We remark that $\delta > 0$ is independent of the choice of $n \in \mathbb{S}^2$. Indeed, for any $n' \in \mathbb{S}^2$, there exists some $n'' \in \mathbb{S}^2$ such that $B_\delta(n'') \subset B_{n'}$. This is a consequence of the invariance under rotations of K . Indeed, it is not difficult to see that $\mathcal{R}_{n,n'}(B_n) = B_{n'}$ and so $\mathcal{R}_{n,n'}(B_\delta(n_1)) = B_\delta(\mathcal{R}_{n,n'}(n_1)) \subset B_{n'}$.

Let us consider the set

$$A_n = \{\tilde{n} \in \mathbb{S}^2 : \text{there exists } n_1, \dots, n_N \in \mathbb{S}^2 \text{ such that (A.1) holds for } n_0 = n \text{ and } n_{N+1} = \tilde{n}\}.$$

By the previous consideration, we know that A_n is not empty. We claim now that $B_\delta(n') \subset A_n$ for any $n' \in A_n$. Indeed, let $\delta > 0$ as above. Since $n' \in A_n$, then $B_{n'}$ is not empty, and there exists some $n_1 \in \mathbb{S}^2$ such that $B_\delta(n_1) \subset B_{n'}$. It is easy to see that $n_1 \in A_n$. Let now $\tilde{n} \in B_\delta(n')$, then $\mathcal{R}_{n',n_1}(\tilde{n}) \in B_\delta(n_1)$. Hence, $K(n', \mathcal{R}_{n',n_1}(\tilde{n})) = K(n_1, \tilde{n}) > 0$. Since also $K(n', n_1) > 0$, we conclude that $B_\delta(n') \subset A_n$ for all $n' \in A_n$. Hence, A_n is open, and it is the whole sphere \mathbb{S}^2 . Indeed, assume $A_n \neq \mathbb{S}^2$. Then, since A_n is open, the boundary $\partial A_n = \bar{A}_n \setminus A_n$ is not empty. Let $n^* \in \partial A_n$ and let $n_0 \in A_n$ with $d(n^*, n_0) < \frac{\delta}{3}$, where $d(n^*, n_0)$ is the distance on \mathbb{S}^2 between the two points $n^*, n_0 \in \mathbb{S}^2$. Since $n^* \in \partial A_n$, it is true that

$$B_{\frac{\delta}{3}}(n^*) \cap A_n \neq \emptyset \text{ and } B_{\frac{\delta}{3}}(n^*) \cap A_n^c \neq \emptyset.$$

On the other hand, we know that $B_\delta(n_0) \subset A_n$ and therefore

$$B_{\frac{\delta}{3}}(n^*) \subset B_{\frac{\delta}{2}}(n^*) \subset B_\delta(n_0) \subset A_n.$$

This contradiction concludes the proof of Lemma A.1. □

Proof of Proposition 2.1. We first show that φ is continuous. Let $\varepsilon > 0$. By the continuity of the kernel K , there exists some $\delta > 0$ such that

$$|K(n_1, n'_1) - K(n_2, n'_2)| < \frac{\varepsilon}{4\pi \|\varphi\|_\infty}$$

for all $n_1, n_2, n'_1, n'_2 \in \mathbb{S}^2$ with $d(n_1, n_2) + d(n'_1, n'_2) < \delta$. Let hence $n_1, n_2 \in \mathbb{S}^2$ with $d(n_1, n_2) < \delta$, then it is easy to see that φ is continuous since

$$\begin{aligned} |\varphi(n_1) - \varphi(n_2)| &= |H[\varphi](n_1) - H[\varphi](n_2)| \\ &\leq \int_{\mathbb{S}^2} |K(n_1, n') - K(n_2, n')| |\varphi(n')| dn' < \varepsilon. \end{aligned}$$

We move now to the proof of claim (ii). Let $M = \max_{n \in \mathbb{S}^2} (\varphi(n))$. By continuity, there exists some $n_* \in \mathbb{S}^2$ such that $M = \varphi(n_*)$. We define the set $A_M = \{n \in \mathbb{S}^2 : \varphi(n) = M\}$. Thus, A_M is not empty, and by continuity, it is also closed. We claim that A_M is also open, which implies claim (ii). Let $n \in A_M$. Consider $B_n = \{\tilde{n} \in \mathbb{S}^2 : K(n, \tilde{n}) > 0\}$. Let $\varepsilon > 0$ and $B_n^\varepsilon = \{\tilde{n} \in B_n : \varphi(\tilde{n}) < M - \varepsilon\}$. We show $\varphi(\tilde{n}) = M$ for all $\tilde{n} \in B_n$.

It is easy to see that this is true if $B_n^\varepsilon = \emptyset$ for all $\varepsilon > 0$. If not, let $\varepsilon > 0$ so that $B_n^\varepsilon \neq \emptyset$. Then

$$M = \varphi(n) = \int_{B_n^\varepsilon} K(n, n') \varphi(n') dn' + \int_{(B_n^\varepsilon)^c} K(n, n') \varphi(n') dn' < M - \varepsilon \int_{B_n^\varepsilon} K(n, n') dn' < M.$$

Arguing as in the proof of Lemma A.1, there exists a $\delta > 0$ such that $B_\delta(n_0) \subset B_n$ for some $n_0 \in B_n$. Hence, using the same argument, since $n_0 \in A_M$, it is also true that $\varphi(\tilde{n}) = M$ for all $\tilde{n} \in B_{n_0}$. Using the rotation invariance of the kernel analogously as we have done in Lemma A.1, we see that

$$\mathcal{R}_{n, n_0}(B_\delta(n_0)) = B_\delta(n) \subset \mathcal{R}_{n, n_0}(B_n) = B_{n_0} \subset A_M.$$

We have just proved that the closed non-empty set A_M is open, and hence, it must be the whole sphere \mathbb{S}^2 .

Finally, we prove claim (iii). To this end, we notice that the linear operator H maps L^p -functions to continuous bounded functions. Analogously as in the proof of (i), this is a direct consequence of the Hölder inequality and the fact that the scattering kernel K is continuous. Hence, $(Id - H)_1: L^1(\mathbb{S}^2) \rightarrow L^1(\mathbb{S}^2)$ given by $(Id - H)_1 \varphi = \varphi - H[\varphi]$ is a well-defined operator, which maps integrable functions to integrable functions. Since $H[\varphi] \in C(\mathbb{S}^2)$ for any $\varphi \in L^1(\mathbb{S}^2)$, if $(Id - H)_1 \varphi = 0$, then (ii) also applies and hence $\varphi = \text{const}$. This means that the null space of $(Id - H)_1$ as an operator acting on $L^1(\mathbb{S}^2)$ is given by

$$\mathcal{N}((Id - H)_1) = \text{span}\langle 1 \rangle = \{f = c: c \in \mathbb{R}\}.$$

It is not difficult to see that the dual operator $(Id - H)_1^*: L^\infty(\mathbb{S}^2) \rightarrow L^\infty(\mathbb{S}^2)$ is exactly given by $(Id - H)$. Indeed, let $f \in L^1(\mathbb{S}^2)$ and $g \in L^\infty(\mathbb{S}^2)$. We compute using the invariance under rotations of the kernel K

$$\begin{aligned} \int_{\mathbb{S}^2} dn g (Id - H)_1[f] &= \int_{\mathbb{S}^2} dn g(n) f(n) - \int_{\mathbb{S}^2} dn \int_{\mathbb{S}^2} dn' K(n, n') g(n) f(n') \\ &= \int_{\mathbb{S}^2} dn g(n) f(n) - \int_{\mathbb{S}^2} dn' \int_{\mathbb{S}^2} dn K(n', n) g(n) f(n') = \int_{\mathbb{S}^2} dn (Id - H)[g] f. \end{aligned}$$

Therefore, by the orthogonality of the null space to the range of the dual operator, we conclude

$$\begin{aligned} \text{Ran}(Id - H) &= \left\{ \varphi \in L^\infty(\mathbb{S}^2): \int_{\mathbb{S}^2} \varphi(n) f(n) dn = 0 \forall f \in \mathcal{N}((Id - H)_1) \right\} \\ &= \left\{ \varphi \in L^\infty(\mathbb{S}^2): \int_{\mathbb{S}^2} \varphi(n) dn = 0 \right\}. \end{aligned}$$

□

Appendix B Details of the numerical simulation

In Section 7.1, we presented a numerical result for problem (7.1). We now explain the derivation of (7.1) from the stationary problem (1.12), and we present the discretization used in order to solve this problem numerically. For more details about the code, we refer to [15]. First of all, we assume $\alpha_v^a = \alpha_v^s = \frac{1}{2}$; moreover, we set $\ell_A = \ell_S = \varepsilon$, and we consider the case of a constant scattering kernel, namely, $K(n, n') = \frac{1}{4\pi}$.

We also consider the domain $[0, 1] \times \mathbb{R}^2$, and we assume that the radiation intensity depends only on the spatial coordinate x_1 and on the angle between $n \in \mathbb{S}^2$ and e_1 . Thus, $I_v(x, n) = I_v(x_1, n_1)$ solves the

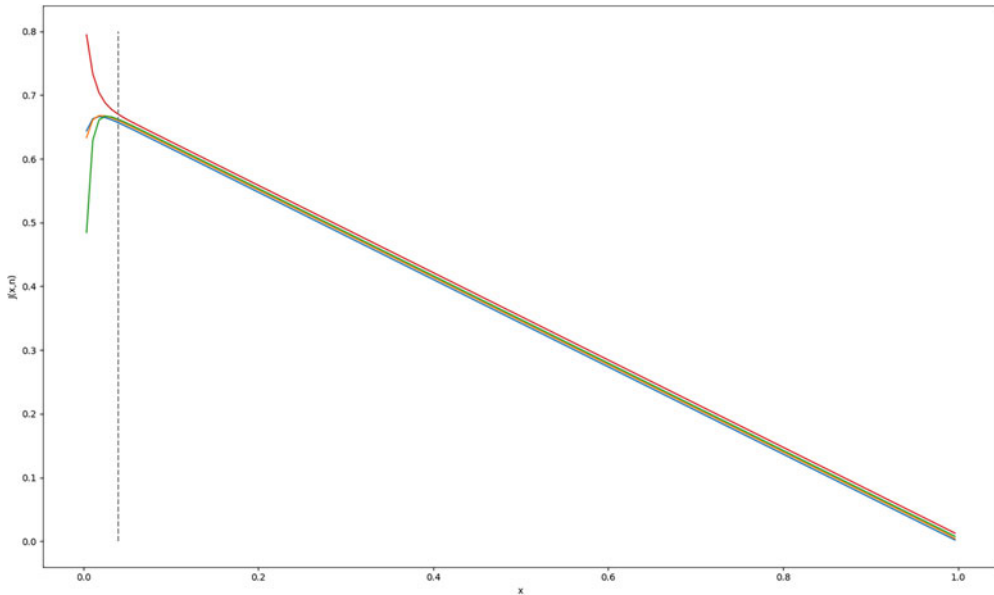


Figure 2. Plot of the approximate solution to the problem (7.1), cf. [15]. The blue line represents $J(x, -0.7)$, the orange line $J(x, -0.2)$, the green line $J(x, 0.15)$ and finally the red line $J(x, 0.86)$. The grey dashed line is $x = 0.04$ and shows the thickness of the Milne layer, which is, as expected, of the same order of $\ell_M = \varepsilon = 0.01$.

one-dimensional problem

$$\begin{cases} n_1 \partial_{x_1} I_v(x_1, n_1) = \frac{1}{2\varepsilon} \left[B_v(T(x_1)) + \frac{1}{2} \int_{-1}^1 I_v(x_1, n'_1) dn'_1 - 2I_v(x_1, n_1) \right] & x_1 \in (0, 1), \quad n_1 \in [-1, 1] \\ \partial_{x_1} \int_0^\infty \int_{-1}^1 n_1 I_v(x_1, n_1) dn_1 dv = 0 & x_1 \in (0, 1), \quad n_1 \in [-1, 1] \\ I_v(0, n_1) = n_1 e^{-v} & n_1 > 0 \\ I_v(1, n_1) = 0 & n_1 < 0, \end{cases}$$

where we chose as boundary condition at $x = 0$ an anisotropic function and at $x = 1$ an isotropic function. Denoting by (x, n) the coordinates (x_1, n_1) , defining the function $J(x, n) = \int_0^\infty I_v(x, n) dv$, using the divergence-free condition for the flux of radiation and the isotropy of the Planck distribution, we obtain

$$2 \int_0^\infty B_v(T(x)) dv = \int_{-1}^1 J(x, n) dn.$$

This implies that $J(x, n)$ solves (7.1), which is then discretized as follows. Let $N > 0$. Then, for $i, j \in \{0, \dots, 2N - 1\}$, we define the grid

$$x_i = \frac{1 + 2i}{4N} \in (0, 1) \quad \text{and} \quad n_j = \frac{1 + 2j}{2N} - 1 \in (-1, 1).$$

Hence, according to the upwind scheme, we have to solve the following system of linear equations

$$\begin{cases} 2Nn_j [J(x_{i+1}, n_j) - J(x_i, n_j)] - \frac{1}{\varepsilon} \left[\frac{1}{2N} \sum_{k=0}^{2N-1} J(x_i, n_k) - J(x_i, n_j) \right] = 0 & j < N, i \neq 2N-1, \\ 2Nn_j [J(x_i, n_j) - J(x_{i-1}, n_j)] - \frac{1}{\varepsilon} \left[\frac{1}{2N} \sum_{k=0}^{2N-1} J(x_i, n_k) - J(x_i, n_j) \right] = 0 & j \geq N, i \neq 0, \\ -4Nn_j J(x_{2N-1}, n_j) - \frac{1}{\varepsilon} \left[\frac{1}{2N} \sum_{k=0}^{2N-1} J(x_{2N-1}, n_k) - J(x_{2N-1}, n_j) \right] = 0 & j < N, i = 2N-1, \\ 4Nn_j [J(x_0, n_j) - n_j] - \frac{1}{\varepsilon} \left[\frac{1}{2N} \sum_{k=0}^{2N-1} J(x_0, n_k) - J(x_0, n_j) \right] = 0 & j \geq N, i = 0, \end{cases}$$

where we used $x_{i+1} - x_i = \frac{1}{2N}$, $n_{j+1} - n_j = \frac{1}{N}$ and the considered boundary conditions. The results represented in Figure 2 were obtained by solving this system with Python for $N = 70$ and $\varepsilon = 0.01$ and plotting the results obtained for $j \in \{20, 55, 80, 130\}$. Finally, we remark that we observe the formation of a Milne layer only close to $x = 0$ since the boundary condition at $x = 1$ is already isotropic.