

On a nonlinear elliptic boundary-value problem

E.N. Dancer

We announce a number of results on the existence of solutions of nonlinear elliptic boundary value problems in the case where the dominating linear part is not invertible. Our theorems improve recent results of Landesman and Lazer, and Williams.

We announce results which improve theorems of Williams [11] and Landesman and Lazer [6] for a nonlinear elliptic boundary-value problem. Williams' result is an improvement on the main theorem in the pioneering paper [5] of Landesman and Lazer.

Suppose that Ω is a bounded domain in R^n , a_{ij} ($i, j = 1, \dots, n$), and c are in $L^\infty(\Omega)$, $a_{ij} = a_{ji}$ ($i, j = 1, \dots, n$), there is a constant $\mu > 0$ such that $a_{ij}(x)\zeta^i\zeta^j \geq \mu|\zeta|^2$ for all $x \in \Omega$ and $\zeta \in R^n$, $f \in L^2(\Omega)$ and $g : R \rightarrow R$ is continuous. Then we look for solutions of the equation

$$(1) \quad Lu = g(u) - f$$

where, for $u \in \dot{W}_2^1(\Omega)$, $Lu = -\frac{\partial}{\partial x_i} \left(a_{ij} \frac{\partial u}{\partial x_j} \right) + cu$. [Here the derivatives are distributional derivatives.]

Let $\lambda_1 < \lambda_2 < \dots$ denote the distinct eigenvalues of the linear problem $Lu = \lambda u$, $N_i = \left\{ u \in \dot{W}_2^1(\Omega) : Lu = \lambda_i u \right\}$, and h_1 the non-negative

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eigenfunction corresponding to λ_1 .

We say that $k : R \rightarrow R$ satisfies *Property P* if $\lim_{x \rightarrow \infty} k(x)$ and $\lim_{x \rightarrow -\infty} k(x)$ both exist. (where the limits may be $\pm\infty$) and there exist $r, d > 0$ such that $|k(sx)| \geq r|k(x)| - d$ if $|x| \geq d$ and $s \geq d$. We say that *Assumption S* holds if Ω has C^2 boundary and there is a compact subset T of Ω such that a_{ij} ($i, j = 1, \dots, n$) are Lipschitz continuous on $\overline{\Omega} \setminus T$.

THEOREM 1. *Suppose that there is a positive integer i such that $g(x) - \lambda_i x$ satisfies Property P, $\lambda_i \leq \liminf_{|x| \rightarrow \infty} x^{-1}g(x)$ $\limsup_{x \rightarrow \infty} x^{-1}g(x) \leq \lambda_{i+1}$, $\limsup_{x \rightarrow -\infty} x^{-1}g(x) \leq \lambda_{i+1}$ and one of the last two inequalities is a strict inequality. Let $I^\pm = \lim_{x \rightarrow \pm\infty} (g(x) - \lambda_i x)$. In addition, assume that one of the following three conditions holds:*

(a) $i > 1$, at least one of I^+ and I^- is infinite, $I^+ \neq I^-$ and $f \in L^p(\Omega)$ where $p > \max\{2, \frac{1}{2}n\}$;

(b) $i = 1$, Assumption S holds, $f \in L^p(\Omega)$ where $p > \max\{2, n\}$ $\int_{\Omega} fh_1 dx / \int_{\Omega} h_1 dx$ lies strictly between I^+ and I^- ;

(c) I^+ and I^- are both finite, $f \in L^2(\Omega)$ and either

(i) $I^+ > I^-$ and

$$I^+ \int_{\Omega^+} h dx + I^- \int_{\Omega^-} h dx > \int_{\Omega} fh dx$$

for all $h \in N_i$, or

(ii) $I^- > I^+$ and

(*)
$$I^- \int_{\Omega^+} h dx + I^+ \int_{\Omega^-} h dx > \int_{\Omega} fh dx$$

for all $h \in N_i$ (where $\Omega^+ = \{x \in \Omega : h(x) > 0\}$ and $\Omega^- = \{x \in \Omega : h(x) < 0\}$).

Then equation (1) has a solution.

In (b), we may omit Assumption S provided that we replace " $s \geq d$ " by " $|s| \geq d$ " in the definition of Property P. If $\liminf_{x \rightarrow \infty} x^{-1}g(x) > \lambda_i$ or $\liminf_{x \rightarrow -\infty} x^{-1}g(x) > \lambda_i$, we need not assume that $I^+ \neq I^-$ in (a) and we may replace " $f \in L^p(\Omega)$ " by " $f \in L^2(\Omega)$ " in (a). If $\liminf_{|x| \rightarrow \infty} x^{-1}g(x) > \lambda_i$, we may replace " $f \in L^p(\Omega)$ " by " $f \in L^2(\Omega)$ " in (b). In (c), we may replace ">" by " \geq " in condition (*) and replace " $I^- > I^+$ " by " $I^- \geq I^+$ " if we assume that $f \in L^p$ where $p > \max\{2, \frac{1}{2}n\}$ and $\limsup_{x \rightarrow \pm\infty} x(g(x) - \lambda_i x - I^\pm) < 0$. This improves the result in [2]. The last condition can be weakened under further regularity assumptions on $L, \partial\Omega$, and f .

The case where $I^- > I^+$ and the assumptions of (c) are satisfied is essentially the result in [11] while the case where

$$\lambda_i < \liminf_{|x| \rightarrow \infty} x^{-1}g(x) \leq \limsup_{|x| \rightarrow \infty} x^{-1}g(x) < \lambda_{i+1}$$

is the result in [6].

The proof of Theorem 1 depends on two lemmas which are of independent interest. By a scalar product on a Banach space X , we mean a symmetric bilinear mapping from $X \times X$ to R .

LEMMA 1. Suppose that X and Y are Banach spaces, $A : X \rightarrow Y$ is a continuous linear Fredholm operator of index zero with range $R(A)$ and null-space $N(A)$, Y_2 is a complement of $R(A)$ in Y , X_2 is a closed complement of $N(A)$ in X , Q is the projection onto $R(A)$ parallel to Y_2 , B is a linear isomorphism from $N(A)$ to Y_2 , and $\langle \cdot, \cdot \rangle$ is a scalar product on Y_2 . Assume that $K : X \rightarrow Y$ is completely continuous, $\limsup_{\|x\| \rightarrow \infty} \|QK(x)\|/\|x\| = M < \infty$ and there exist $\varepsilon, r > 0$ such that

$$(**) \quad \langle (I-Q)K(x_1+x_2), Bx_1 \rangle < 0$$

if $x_1 \in N(A)$, $x_2 \in X_2$, $\|x_1\| \geq r$ and $\|x_2\| \leq \epsilon \|x_1\|$. There exists an $r_1 > 0$ such that, if $t \neq 0$ and

$$|t|M \leq \frac{1}{2}\epsilon \inf\{\|Ax\|/\|x\| : x \in X_2, x \neq 0\},$$

then the equation $Au = tK(u)$ has a solution u with $\|u\| \leq r_1$ and no solutions with $\|u\| > r_1$.

The proof of this lemma is an easy modification of the proof of Theorem 2.6.2 in [8]. In the proof, it is established that a mapping similar to that in the proof of Theorem 2.6.2 in [8] has non-zero degree. Theorem 1 can easily be deduced from Lemma 1 if $\limsup_{|x| \rightarrow \infty} |x^{-1}g(x) - \lambda_i|$ is sufficiently small. The only difficulty is to verify condition (**). This is achieved by some simple estimations. In the proof, we use some of the regularity results in [10] for weak solutions of elliptic partial differential equations.

LEMMA 2. Suppose that $\epsilon > 0$ and that the assumptions of Theorem 1 hold. There exists an $r_2 > 0$ such that, if u is a solution of

$$(2) \quad Lu = \lambda_i u + t(g(u) - \lambda_i u - f)$$

where $\epsilon \leq t \leq 1$, then $\|u\|_2 \leq r$ (where $\|\cdot\|_2$ denotes the usual norm on $L^2(\Omega)$).

The proof of this resembles the proof of Lemma 4.6 in [1]. Outline of the proof in the case where (a) of Theorem 1 holds and

$$\limsup_{x \rightarrow \infty} x^{-1}g(x) < \lambda_{i+1}.$$

Suppose by way of contradiction that there exist

solutions u_n of (2) (for $t = t_n$) such that $\epsilon \leq t_n \leq 1$ for all n and

$\|u_n\|_2 \rightarrow \infty$ as $n \rightarrow \infty$. By choosing a subsequence, we may assume that

$$(\|u_n\|_2)^{-1}u_n \text{ converges strongly in } \dot{W}_2^1(\Omega) \cap L^\infty(\Omega) \text{ to } v \text{ and } t_n \rightarrow t^* \text{ as } n \rightarrow \infty,$$

where $v \neq 0$, $\epsilon \leq t^* \leq 1$, and

$$(3) \quad Lv = \lambda_i v + t^*kv.$$

Here $k \in L^\infty(\Omega)$, $0 \leq k(x) \leq \lambda_{i+1} - \lambda_i$ on Ω and $k(x) < \lambda_{i+1} - \lambda_i$ when $v(x) > 0$. (In showing that v satisfies (3), we show that

$(\|u_n\|_2)^{-1}(g(u_n) - \lambda_i u_n)$ converges weakly to k in $L^2(\Omega)$.) By comparison arguments, it is shown that (3) is impossible unless $v \in N_i$. In this

case, we obtain a contradiction by noting that

$$\int_{\Omega} (g(u_n) - \lambda_i u_n) v dx = \int_{\Omega} f v dx$$

and then using the inequalities needed to verify condition (**) of Lemma 1.

The proof of Theorem 1 can now be completed by constructing a similar mapping to that in the proof of Theorem 2.6.2 in [8] and then using Lemma 1, a remark after Lemma 1, Lemma 2 and the homotopy invariance of the degree.

THEOREM 2. *Suppose that $x^{-1}g(x) \rightarrow a$ as $x \rightarrow \infty$, $x^{-1}g(x) \rightarrow b$ as $x \rightarrow -\infty$,*

$$(***) \quad (a - \lambda_i) \int_{\Omega^+} h^2 dx + (b - \lambda_i) \int_{\Omega^-} h^2 dx > 0 \quad (< 0)$$

for every $h \in N_i$, and $|a - \lambda_i| + |b - \lambda_i|$ is sufficiently small. Then (1) has a solution for every $f \in L^2(\Omega)$.

This follows easily from Lemma 1. This result should be contrasted with Theorem 3.1 in [1]. On the other hand, if $N_i = \{\alpha h : \alpha \in R\}$ and condition (***) is replaced by:-

$$(a - \lambda_i) \int_{\Omega^+} h^2 dx + (b - \lambda_i) \int_{\Omega^-} h^2 dx$$

and

$$(a - \lambda_i) \int_{\Omega^-} h^2 dx + (b - \lambda_i) \int_{\Omega^+} h^2 dx$$

are both non-zero and have opposite signs, it can be shown that

$\{f \in L^2(\Omega) : (1) \text{ has a solution}\}$ is a closed proper subset of $L^2(G)$.
(If $i = 1$, we need only assume that $a < \lambda_1 < b \leq \lambda_2$ or

$$b < \lambda_1 < a \leq \lambda_2 .)$$

THEOREM 3. Let $I^+ = \limsup_{x \rightarrow \infty} (g(x) - \lambda_1 x)$ and $I^- = \liminf_{x \rightarrow -\infty} (g(x) - \lambda_1 x)$. If $f \in L^2(\Omega)$ and $I^+ < \int_{\Omega} f h_1 dx / \int_{\Omega} h_1 dx < I^-$, then (1) has a solution.

This result can easily be proved by using the results in [4]. Alternatively, it can be proved by applying Theorem 1 to a truncated equation and then passing to the limit. This theorem improves a result in Schatzman [9].

If the assumptions of one of the theorems holds, $f \in L^p(\Omega)$ where $p > \frac{n}{2}$, and u is a solution of (1) (with $g(u) \in L^1(\Omega)$ if the assumptions of Theorem 3 hold), it can be shown that $u \in L^\infty(\Omega)$. It is easy to prove additional regularity results under stronger assumptions. The solutions in Theorems 1 and 3 are unique under additional assumptions on g .

Our methods can be applied to a number of other problems. For example, they could be used to improve the main result in [7] and some of the results in [3] on the existence of periodic solutions of ordinary differential equations.

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Department of Mathematics,
University of New England,
Armidale,
New South Wales.