

# SOME LIE ADMISSIBLE ALGEBRAS

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Several studies have been made to obtain larger classes of non-associative algebras from classes of algebras with a known structure. Thus, we have right alternative algebras **(2)\*** and non-commutative Jordan algebras **(6)**, **(7)**, **(8)**, and **(9)**. These algebras are defined by a subset of the set of identities of the algebras from which they derive their names. Also, Albert **(1)**, among others has studied Jordan admissible algebras. This paper is concerned with algebras which are related to Lie algebras in that they satisfy some of the identities of a Lie algebra and are Lie admissible. Theorem 2 answers a question raised by Albert in **(1)**.

**1.** For an algebra  $\mathfrak{A}$ , the algebra  $\mathfrak{A}^{(-)}$  is defined as the same vector space as  $\mathfrak{A}$ , but with a multiplication given by  $[x, y] = xy - yx$  where juxtaposition denotes multiplication in  $\mathfrak{A}$ . The algebra  $\mathfrak{A}^{(-)}$  is clearly an anticommutative algebra.  $\mathfrak{A}$  is said to be Lie admissible if  $\mathfrak{A}^{(-)}$  is a Lie algebra, that is,

$$[x, [y, z]] + [y, [z, x]] + [z, [x, y]] = 0$$

and

$$[x, y] + [y, x] = 0.$$

An algebra  $\mathfrak{A}$  is Lie admissible **(1, p. 573)** if and only if

$$(1) \quad R_{[x,y]} - L_{[x,y]} = [R_x - L_x, R_y - L_y]$$

where  $R_a$  and  $L_a$  are right and left multiplications by  $a$  in the algebra  $\mathfrak{A}$ .

Let  $\Phi$  be a field of characteristic  $\neq 2, 3$ . One way to generalize Lie algebras would be to study an algebra  $\mathfrak{A}$  which satisfies the identity

$$(2) \quad x(yz) + y(zx) + z(xy) = 0$$

or equivalently

$$(3) \quad L_y L_x + R_x L_y + R_{xy} = 0.$$

The identity (2) does not seem restrictive enough to allow a satisfactory structure theory. If we take the algebra over  $\Phi$  with basis  $s, t, u,$  and  $v$  and define  $su = tu = u^2 = vu = s, sv = tv = uv = v^2 = t,$  and all other products

Received May 17, 1961. Work by Laufer was carried out under a fellowship held at the Summer Research Institute of the Canadian Mathematical Congress. Work by Tomber was supported partly by the United States Air Force under Contract No. AF 49(638)-511, and partly by a grant from the National Science Foundation.

\*See Kleinfeld **(5)** for an extensive bibliography of works on right alternative algebras.

equal 0 we have an algebra which satisfies (2) but will not satisfy either of the equivalent identities

$$(4) \quad (xy)z + (yz)x + (zx)y = 0,$$

$$(5) \quad L_{xy} + L_yR_x + R_xR_y = 0.$$

For (4) implies  $3x^2x = 0$  or  $x^2x = 0$ , but  $v^2v = tv = t \neq 0$ .

Thus (2) is not sufficient to make an algebra power-associative. However, if (2) and (4) are assumed, then  $x^3 = x^2x = xx^2 = 0$  and (2) implies  $x^2(xx) + x(xx^2) + x(x^2x) = x^2x^2 = 0 = (x^2x)x$ . To complete a proof that an algebra satisfying (2) and (4) is power-associative, that is,  $x^\lambda x^\mu = x^{\lambda+\mu}$ , observe that  $x^n = x^{n-1}x = 0$  for  $n \geq 3$ .

The example given above also shows that an algebra may satisfy (2), but not be Lie admissible. For  $[t, [u, v]] + [u, [v, t]] + [v, [t, u]] = [t, t - s] + [u, -t] + [v, s] = 0 + s - t \neq 0$ . An algebra that satisfies (3) and (5) is Lie admissible. This is easily seen by rewriting (3) with  $x$  and  $y$  interchanged to obtain  $R_{[x,y]} = [L_x, L_y] + R_yL_x - R_xL_y$ . Likewise,  $L_{[x,y]} = -[R_x, R_y] + L_xR_y - L_yR_x$ . Subtraction yields (1).

An anticommutative algebra is flexible, that is  $(xy)x = x(yx)$ . As a first step towards generalizing Lie algebras it appears natural to study flexible algebras which satisfy (2) and (4). Such an algebra need not be a Lie algebra as shown by an algebra with basis  $u, v$  over  $\Phi$  and with multiplication given by  $v^2 = u$  and  $u^2 = uv = vu = 0$ .

A flexible algebra satisfying (3) and (5) is a Jordan admissible algebra and by Schafer (7) is a non-commutative Jordan algebra. To see that such an algebra is Jordan admissible, write the condition for Jordan admissibility in the form  $[R_x + L_x, R(x^2) + L(x^2)] = 0$ , (1, p. 574). Let  $x = y$  in (3) and (5), then  $R(x^2) = -L_x^2 - R_xL_x$  and  $L(x^2) = -L_xR_x - R_x^2$ . In a flexible algebra  $R_x$  and  $L_x$  commute, so the commutator above is equal to 0.

In what follows, the full strength of (2), (4), and flexibility is not needed. The algebras we shall be concerned with are power-associative, flexible and Lie admissible. That these conditions are, in general, less restrictive may be seen by examining an associative algebra.

**2.** In this section extensive use will be made of the known structure of semi-simple Lie algebras of characteristic 0. The material that will be used may be found in (3), (4), or (11).

Albert has shown (1, p. 576) that an algebra is a flexible Lie admissible algebra if and only if

$$(6) \quad R_{[x,y]} = [R_x, R_y - L_y].$$

Let  $D_y = D(y)$  represent the linear transformation  $R_y - L_y$ , then (6) may be written as  $R(xD_y) = [R_x, D_y]$  or in a flexible Lie admissible algebra  $D_y$  is a derivation.

As in the study of Lie algebras we shall say that an element  $x$  of an algebra  $\mathfrak{A}$  belongs to the characteristic root  $\alpha$  of the linear transformation  $D_y$ , if for some integer  $h \geq 1$ ,  $x(D_y - \alpha I)^h = 0$ .

LEMMA. *Let  $\mathfrak{A}$  be a flexible Lie admissible algebra over an arbitrary algebraically closed field  $\Omega$  of characteristic 0. For  $x, y, z \in \mathfrak{A}$ , and  $\alpha, \beta \in \Omega$  roots of  $D_z$ , if  $x, y$  belong to  $\alpha, \beta$  respectively, then  $xy$  and  $yx$  belong to  $\alpha + \beta$  whenever  $\alpha + \beta$  is a root of  $D_z$  and equal 0 otherwise.*

Since  $D_z$  is a derivation,  $xy(D_z - (\alpha + \beta)I) = x(D_z - \alpha I)y + x(y(D_z - \beta I))$  and the lemma may be proved by induction just as for Lie algebras.

THEOREM 1. *Let  $\mathfrak{A}$  be a flexible, Lie admissible algebra over an arbitrary algebraically closed field  $\Omega$  of characteristic 0. If  $\mathfrak{A}^{(-)}$  is a semi-simple Lie algebra, then  $\mathfrak{A}$  is a direct sum of simple, flexible, Lie admissible algebras.*

Assuming that  $\mathfrak{A}$  is in addition power-associative, Weiner (10) obtained the same conclusion. Since very few results have been obtained for non-power-associative algebras we include a proof of Theorem 1.

Since  $\mathfrak{A}^{(-)}$  is semi-simple we may write  $\mathfrak{A}^{(-)} = \mathfrak{B}_1 \oplus \dots \oplus \mathfrak{B}_t$ , where the  $\mathfrak{B}_i, i = 1, 2, \dots, t$ , are simple Lie algebras. This decomposition of  $\mathfrak{A}^{(-)}$  will decompose the underlying vector space of  $\mathfrak{A}$  into a vector space direct sum of subspaces  $\mathfrak{A}_i, i = 1, 2, \dots, t$ , where the subspace  $\mathfrak{A}_i$  is the same vector space as  $\mathfrak{B}_i$ . We shall show that the  $\mathfrak{A}_i$  are ideals of  $\mathfrak{A}$  and that  $\mathfrak{A}$  is a direct sum of the  $\mathfrak{A}_i$ .

In each  $\mathfrak{B}_i$  fix a Cartan subalgebra  $\mathfrak{H}_i$  and relative to  $\mathfrak{H}_i$  a classical basis of  $\mathfrak{B}_i$ . Let  $x, y$  be arbitrary elements of  $\mathfrak{A}_k$ . Since  $xy \in \mathfrak{A}$ , we may write  $xy = \sum b_i, b_i \in \mathfrak{A}_i$  and  $\mathfrak{B}_i$ . If  $b_j \neq 0$ , then there is an  $x_j \in \mathfrak{B}_j$  such that  $b_j x_j - x_j b_j \neq 0$ , for otherwise  $\Omega b_j$  would be an ideal of the simple algebra  $\mathfrak{B}_j$ . For any  $x_j \in \mathfrak{B}_j, (xy)D(x_j) = \sum b_i D(x_j) = (xD(x_j))y + x(yD(x_j)) = b_j D(x_j)$  since  $\mathfrak{A}^{(-)}$  is a direct sum of the  $\mathfrak{B}_i$ . For the same reason  $(xy)D(x_j) = 0$ , if  $j \neq k$ . Thus for all  $j \neq k, b_j D(x_j) = [b_j, x_j] = 0$  and by the remark above  $b_j = 0$ . Hence  $xy = b_k$  and we have shown that  $\mathfrak{A}_k$  is a subalgebra of  $\mathfrak{A}$ .

It should be noted that the notion of belonging to a root in  $\mathfrak{A}$ , as defined, is the same as belonging to a root in  $\mathfrak{A}^{(-)}$ . Furthermore, since the non-zero root spaces of  $\mathfrak{B}_i$  are one dimensional, the non-zero root spaces in the algebra  $\mathfrak{A}_i$  are also of dimension one.

Let  $x \in \mathfrak{A}_j, y \in \mathfrak{A}_k, j \neq k$  and in addition suppose that  $x$  belongs to a non-zero root of  $\mathfrak{H}_j \subset \mathfrak{A}_j$ . Thus, there is an  $h \in \mathfrak{H}_j$  such that  $x D_h = \alpha x$  where  $\alpha \neq 0$  and  $\alpha \in \Omega$ . Write  $xy = \sum b_i$ . Apply  $D_h$  to obtain  $(xy)D_h = (xD_h)y + x(yD_h) = \alpha xy = [b_j, h]$ . Since  $\alpha \neq 0, xy \in \mathfrak{A}_j$ . Let  $h \in \mathfrak{H}_j$  and let  $x_\beta$  be the basis element belonging to the root  $\beta$ . Also, let  $y \in \mathfrak{A}_k, k \neq j$ . The quantity  $x_\beta y \in \mathfrak{A}_j$ . For  $x_{-\beta}$  belonging to the root  $-\beta, (x_\beta y)D(x_{-\beta}) = [x_\beta, x_{-\beta}]y = h_\beta y$  which also is an element of  $\mathfrak{A}_j$ . From the distributive laws, we have that each  $\mathfrak{A}_j$  is an ideal of  $\mathfrak{A}$ . It follows that  $\mathfrak{A} = \mathfrak{A}_1 \oplus \dots \oplus \mathfrak{A}_t$ . Each  $\mathfrak{A}_i$  is simple, for each (two-sided) ideal of  $\mathfrak{A}$  is an ideal of  $\mathfrak{A}^{(-)}$ .

**COROLLARY.** *Let  $\mathfrak{A}$  be a flexible algebra over a field  $\Phi$  of characteristic 0. If  $\mathfrak{A}^{(-)}$  is the direct sum of central simple Lie algebras, then  $\mathfrak{A}$  is a direct sum of simple, flexible, Lie admissible algebras.*

The decomposition of  $\mathfrak{A}^{(-)}$  decomposes  $\mathfrak{A}$  into a vector space direct sum  $\mathfrak{A} = \mathfrak{A}_1 + \dots + \mathfrak{A}_i$ . Let  $\Omega$  be the algebraic closure of  $\Phi$ . Apply the theorem to  $\mathfrak{A}_\Omega = \mathfrak{A}_{1\Omega} + \dots + \mathfrak{A}_{i\Omega}$ . Each  $\mathfrak{A}_{i\Omega}$  is a simple, flexible, Lie admissible algebra and  $\mathfrak{A}_{i\Omega}\mathfrak{A}_{j\Omega} = 0$ ,  $i \neq j$ . If  $u \in \mathfrak{A}$  and  $x \in \mathfrak{A}_i$ , then  $ux, xu \in \mathfrak{A}_{i\Omega}$ . Also,  $ux, xu \in \mathfrak{A}$  and therefore  $ux, xu \in \mathfrak{A}_i$ .

**THEOREM 2.** *Let  $\mathfrak{A}$  be a flexible, power-associative algebra, over an arbitrary, algebraically closed field  $\Omega$  of characteristic 0. If  $\mathfrak{A}^{(-)}$  is a simple Lie algebra, then  $\mathfrak{A}$  is a simple Lie algebra isomorphic to  $\mathfrak{A}^{(-)}$ .*

Since  $\mathfrak{A}^{(-)}$  is a simple Lie algebra over an algebraically closed field of characteristic 0, we may fix a classical basis of  $\mathfrak{A}^{(-)}$ . Let  $\bar{\mathfrak{H}}$  be the fixed Cartan subalgebra of  $\mathfrak{A}^{(-)}$  and  $\mathfrak{H}$  the corresponding subspace of  $\mathfrak{A}$ . If  $x, y$  belong to the roots  $\alpha(\mathfrak{H})$  and  $\beta(\mathfrak{H})$ , then  $xy$  and  $yx$  belong to the root  $(\alpha + \beta)(\mathfrak{H})$  (provided  $\alpha(\mathfrak{H}) + \beta(\mathfrak{H})$  is a root). Thus  $[x, y] \in \Omega z$ , where  $z$  belongs to the root  $(\alpha + \beta)(\mathfrak{H})$ . In a simple Lie algebra the non-zero root spaces are one dimensional and it follows that  $xy, yx \in \Omega z$ .

The elements of  $\mathfrak{H}$  belong to the root zero and hence  $\mathfrak{H}$  is a power-associative subalgebra of  $\mathfrak{A}$ . Also,  $\mathfrak{H}$  is commutative, for  $[h, h'] = 0$ ,  $h, h' \in \bar{\mathfrak{H}}$ . The proof of the theorem will follow readily once we further determine the structure of  $\mathfrak{H}$ . We shall do this in several steps.

(i) The algebra  $\mathfrak{H}$  is a nil algebra. For suppose  $h \in \mathfrak{H}$  is not nilpotent, then the subalgebra  $\mathfrak{F}$  of  $\mathfrak{H}$  generated by  $h$  is an associative non-nilpotent algebra and has an idempotent. Let  $e$  be this idempotent,  $e \in \bar{\mathfrak{H}}$ . For an element  $x$  of the fixed basis of  $\mathfrak{A}^{(-)}$  belonging to a non-zero root,  $\alpha(\mathfrak{H})$ , there exists  $\alpha, \beta \in \Omega$  such that  $ex - xe = \alpha x$  and  $ex = \beta x$ . This implies that  $xe = (\beta - \alpha)x$ . We use the identity  $(R_e + L_e - I)(R_e - L_e) = 0$  (**1**, (11)) which is valid in a power-associative algebra of characteristic 0. For  $x \neq 0$ , this identity applied to  $x$  yields  $2\alpha\beta = \alpha^2 + \alpha$ . Thus  $\alpha = 0$  or  $\alpha = 2\beta - 1$ . Since  $\mathfrak{A}^{(-)}$  is simple,  $x$  may be further restricted so that  $\alpha \neq 0$ . Let  $y \neq 0$  belong to the root  $-\alpha(\mathfrak{H})$ . Then  $[x, y] \neq 0$  and  $[x, y] \in \mathfrak{H}$ . Not both  $xy$  and  $yx$  can equal 0. Set  $ey = \beta'y$ ,  $[e, y] = \alpha'y = -\alpha y$  and  $ye = (\beta' - \alpha)y = (\beta' + \alpha)y$ . From the lemma  $xy$  belongs to the root  $\beta + \beta'$ , relative to  $e$ , if  $\beta + \beta'$  is a root. Also,  $xy \in \mathfrak{H}$ , that is,  $xy$  is either 0 or  $xy$  belongs to the root zero. Likewise  $yx$  is either 0 or belongs to the root zero. Thus, either  $\beta + \beta' = 0$  or  $(\beta' + \alpha) + (\beta - \alpha) = 0$ . In either case  $\beta' = -\beta$ . As for  $\alpha$  and  $\beta$  we may obtain the result,  $\alpha' = -\alpha = 2\beta' - 1$ . Combining  $-\alpha = -2\beta - 1$  and  $\alpha = 2\beta - 1$  we reach a contradiction.

(ii) The algebra  $\mathfrak{H}$  is a nil algebra of bounded index; that is, there is a  $t > 1$  such that  $h^t = 0$  for all  $h \in \mathfrak{H}$ . For  $h \in \mathfrak{H}$  the algebra  $\mathfrak{F}$  generated by  $h$  is an associative nil algebra. Thus  $\mathfrak{F}^{k+1} = 0$  for  $k \leq \dim \mathfrak{F} \leq \dim \mathfrak{H}$ . In particular  $h^t = 0$  for  $t = \dim \mathfrak{H} + 1$ .

(iii) The algebra  $\mathfrak{S}$  is such that  $\mathfrak{S}^2 = 0$ . Let  $x^t = 0$  for all  $x \in \mathfrak{S}$ ,  $t \geq 3$ . Let  $n$  be the least positive integer such that  $3n \geq t$ . Since  $\mathfrak{A}$  is power associative,  $x^{3n} = 0$ . Let  $h \in \mathfrak{S}$  and set  $g = h^n$ . Also, let  $x$  be a basal element of  $\mathfrak{A}^{(-)}$  belonging to a non-zero root relative to  $\overline{\mathfrak{S}}$ . From the lemma and the known structure of  $\mathfrak{A}^{(-)}$ , there exist  $\alpha, \beta, \gamma, \delta \in \Omega$  such that  $gx - xg = \alpha x$ ,  $gx = \beta x$ ,  $g^2x - xg^2 = \gamma x$ , and  $g^2x = \delta x$ . From this we may write  $xg = (\beta - \alpha)x$  and  $xg^2 = (\delta - \gamma)x$ .

The flexible law implies

$$(g^2g^2)x - g^2(g^2x) + (xg^2)g^2 - x(g^2g^2) = 0.$$

Since  $g^3 = 0$ ,  $g^4 = 0$ ; and it follows that  $-\delta^2x + (\delta - \gamma)^2x = 0$ . Thus  $\gamma = 0$  or  $\gamma = 2\delta$ , since  $x \neq 0$ . The flexible law also states  $(gg^2)x - g(g^2x) + (xg^2)g - x(g^2g) = 0$ . However,  $g^3 = 0$ , so  $-\beta\delta x + (\beta - \alpha)(\delta - \gamma)x = 0$ . If  $\gamma \neq 0$ , then  $\alpha = 2\beta$ . We may also write,  $(gg)x - g(gx) + (xg)g - x(gg) = 0$ . This implies that  $\gamma x - \beta^2x + (\beta - \alpha)^2x = 0$ . If  $\gamma \neq 0$ , this is a contradiction. Thus  $\gamma = 0$  and  $[g^2, x] = 0$ . By linearity  $[g^2, u] = 0$ , for all  $u \in \mathfrak{A}^{(-)}$ . Since  $\mathfrak{A}^{(-)}$  is simple,  $g^2 = 0$ , that is,  $h^{2n} = 0$ .

By repeated application of the above, we have  $h^t = h^{2n} = h^{2m} = \dots = 0$  with  $t \geq 2n \geq 2m \geq \dots \geq 2$ . Equality between two components will occur only when the left-hand exponent is 2 or 4. We will now examine the situation when  $h^4 = 0$ . Set  $hx - xh = \lambda x$ ,  $hx = \mu x$ ,  $h^2x - xh^2 = \nu x$ , and  $h^2x = \xi x$ . If we apply the flexible law to the triple  $h^2, h^2, x$ , we have  $(-2\nu\xi + \nu^2)x = 0$  and  $\nu = 0$  or  $\nu = 2\xi$ .

Since  $h^5 = 0$ , if  $\nu \neq 0$ ,  $(h^3h^2)x - h^3(h^2x) + (xh^2)h^3 - x(h^2h^3) = 0$  yields  $xh^3 + h^3x = 0$ . Substitute  $h^3x$  for  $-xh^3$  after using the flexible law with the triple  $h^2, h, x$ . This gives  $4h^3x - \nu(2\mu - \lambda)x = 0$ . This result may be used to simplify  $(hh^3)x - h(h^3x) + (xh^3)h - x(h^3h) = 0$  and we find  $2\mu = \lambda$ . This implies  $h^3x - xh^3 = 0$ .

If  $\nu = 0$ ,  $h^2x = xh^2$ . The first equation in the preceding paragraph may be rewritten as  $[h^3, h^2x] = 0$  or  $[h^3, \xi x] = 0$ . Also  $h^3x - h(h^2x) + (xh^2)h - xh^3 = 0$  or  $[h^3, x] - \lambda\xi x = 0$ . It follows that  $[h^3, x] = 0$ .

By linearity,  $[h^3, u] = 0$  for all  $u \in \mathfrak{A}$ . The simplicity of  $\mathfrak{A}^{(-)}$  implies  $h^3 = 0$ . We may now conclude  $h^2 = 0$  for all  $h \in \mathfrak{S}$ . To complete the proof that  $\mathfrak{S}^2 = 0$ , we observe that  $(h + h')^2 = 0$  and  $[h, h'] = 0$ .

We may now determine the remainder of the structure of  $\mathfrak{A}$ . Let  $x \neq 0$  be a basis vector of  $\mathfrak{A}$  and  $(\mathfrak{A}^{(-)})$  belonging to a non-zero root of  $\mathfrak{S}$ . For  $h \in \mathfrak{S}$ , there exist  $\alpha, \beta \in \Omega$  such that  $hx - xh = \alpha x$ ,  $hx = \beta x$ , and  $xh = (\beta - \alpha)x$ . From  $h^2 = 0$  and  $(hh)x - h(hx) + (xh)h - x(hh) = 0$  it follows that  $\alpha = 0$  or  $2\beta = \alpha$ . More precisely, it is always true that  $2\beta = \alpha$ . For there is an  $h' \in \mathfrak{S}$  such that  $[h', x] \neq 0$ , since  $x$  belongs to a non-zero root. In case  $\alpha = 0$  we may write  $(h'h)x - h'(hx) + (xh)h' - x(hh') = 0 = [xh, h'] = [x, h']$  or  $\beta = 0$ .

Next let  $x, y$  be basis vectors of  $\mathfrak{A}$  belonging to non-zero roots  $\alpha(\mathfrak{S})$  and  $\rho(\mathfrak{S})$  respectively. If  $\alpha(\mathfrak{S}) + \rho(\mathfrak{S})$  is not a root, then by the lemma  $xy = yx = 0$ .

Otherwise let  $z \neq 0$  belong to the root  $\alpha(\mathfrak{H}) + \rho(\mathfrak{H})$  and then there exist  $\sigma, \tau \in \Omega$  such that  $xy - yx = \sigma z$ ,  $xy = \tau z$ , and  $yx = (\tau - \sigma)z$ . From the above, if  $[h, x] = \alpha x$  and  $[h, z] = \omega z$ , then  $2hx = -2xh = \alpha x$  and  $2hz = -2zh = \omega z$ . We use the flexible law once again to write  $(hx)y - h(xy) + (yx)h - y(xh) = 0$ . Thus  $\frac{1}{2}\alpha xy - \tau hz + (\tau - \sigma)zh + \frac{1}{2}\alpha yx = \frac{1}{2}[\alpha\tau - \omega\tau - (\tau - \sigma)\omega + \alpha(\tau - \sigma)]z = 0$ . Since  $z \neq 0$ ,  $\alpha = \omega$  or  $2\tau - \sigma = 0$ . The quantity  $2\tau - \sigma$  is independent of which  $h \in \mathfrak{H}$  is used. If  $2\tau - \sigma \neq 0$  then  $\alpha(h) = \omega(h)$  and the root forms  $\alpha(\mathfrak{H})$  and  $\omega(\mathfrak{H})$  are equal. This implies  $y$  belongs to the root zero which is a contradiction, thus  $2\tau - \sigma = 0$ .

This completes the multiplication table of  $\mathfrak{A}$  and  $\mathfrak{A}$  is seen to be a Lie algebra. The mapping  $u \rightarrow \frac{1}{2}u$  gives the isomorphism between  $\mathfrak{A}$  and  $\mathfrak{A}^{(-)}$ .

**COROLLARY.** *Let  $\mathfrak{A}$  be a flexible, strictly power-associative algebra over a field  $\Phi$  of characteristic 0. If  $\mathfrak{A}^{(-)}$  is a central simple Lie algebra, then  $\mathfrak{A}$  is a simple Lie algebra isomorphic to  $\mathfrak{A}^{(-)}$ .*

Let  $\Omega$  be the algebraic closure of  $\Phi$ . By the theorem,  $\mathfrak{A}_\Omega$  is a Lie algebra. Since  $\mathfrak{A}$  is an algebra contained in  $\mathfrak{A}_\Omega$ ,  $\mathfrak{A}$  is anticommutative and satisfies the Jacobi identity. Thus  $\mathfrak{A}$  is a Lie algebra.

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