

## ASYMPTOTIC BEHAVIOUR OF NON-AUTONOMOUS DISSIPATIVE SYSTEMS IN HILBERT SPACE

SONG GUOZHU

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### Abstract

In this paper we discuss the asymptotic behaviour, as  $t \rightarrow \infty$ , of the integral solution  $u(t)$  of the non-linear evolution equation  $u'(t) \in A(t)u(t) + g(t)$ ,  $t \geq s$ ,  $u(s) = x_0 \in \overline{D(A(s))}$ , where  $\{A(t)\}_{t \geq 0}$  is a family of  $m$ -dissipative operators in a Hilbert space  $H$ , and  $g \in L_{loc}(0, \infty; H)$ . We give some sufficient conditions and some sufficient and necessary conditions to ensure that  $\sigma(t) = t^{-1} \int_s^{s+t} u(\theta) d\theta$  and  $u(t)$  are weakly convergent.

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### 1. Introduction and preliminaries

Let  $H$  be a real Hilbert space with inner product  $(\cdot, \cdot)$  and norm  $|\cdot|$ . We consider the non-linear evolution equation

$$(1.1) \quad \begin{cases} u'(t) \in A(t)u(t) + g(t), & t \geq s \\ u(s) = x_0 \end{cases}$$

where  $\{A(t)\}_{t \geq 0}$  is a family of  $m$ -dissipative operators in  $H$ ,  $x_0 \in \overline{D(A(s))}$  and  $g \in L_{loc}(0, \infty; H)$ . Our objective is to study the asymptotic behaviour, as  $t \rightarrow \infty$ , of the integral solution  $u(t)$  of (1.1). In [6,7,9] the weak convergence of the autonomous dissipative system

$$\begin{cases} u'(t) \in Au(t) \\ u(0) = x_0 \end{cases}$$

where  $A$  is an  $m$ -dissipative operator in  $H$ ,  $x_0 \in \overline{D(A)}$ , has been studied. In [4, 10] Morosanu and Rouhani discussed the weak convergence of the quasi-autonomous dissipative system

$$\begin{cases} u'(t) \in Au(t) + g(t) \\ u(0) = x_0 \end{cases}$$

where  $g \in L(0, \infty; H)$  (or more generally,  $g - g_\infty \in L(0, \infty; H)$  for some  $g_\infty \in H$ ).

Throughout this paper we assume that  $A(t)$  satisfies the following conditions:

( $H_1$ ): there exists a continuous function  $f : R_+ \rightarrow H$  and a bounded (on bounded subsets) function  $L : R_+ \rightarrow R_+$  such that

$$(1.2) \quad (y_1 - y_2, x_1 - x_2) \leq |f(t) - f(s)| \cdot |x_1 - x_2| \cdot L(|x_2|)$$

for all  $0 \leq s \leq t$ ,  $[x_1, y_1] \in A(t)$ ,  $[x_2, y_2] \in A(s)$ .

( $H_2$ ): If  $t_n \uparrow t$  in  $[s, +\infty]$ ,  $x_n \in D(A(t_n))$ ,  $x_n \rightarrow x$  in  $H$ , then  $x \in \overline{D(A(t))}$ .

DEFINITION 1.1. If  $u(t)$  is continuous on  $[s, \infty)$ ,  $u(s) = x_0$ ,  $u(t) \in \overline{D(A(t))}$  for  $t \in [s, \infty)$  and satisfies the inequality

$$(1.3) \quad |u(\bar{t}) - x| \leq |u(t) - x| + \int_t^{\bar{t}} ((y + g(\theta), u(\theta) - x)_+ + c|f(\theta) - f(r)|) d\theta$$

for all  $s \leq t \leq \bar{t}$ ,  $r \geq s$  and  $[x, y] \in A(r)$ . Then  $u(t)$  is called an *integral solution* to (1.1). Here  $c = L(|x|)$ ,  $(y, x)_+ = \lim_{h \downarrow 0} (|x + hy| - |x|)/h$  and  $(y, x) = |x|(y, x)_+$ .

Clearly, a strong solution  $u(t)$  to (1.1) is automatically an integral solution to (1.1), and by [5] the problem (1.1) has a unique integral solution under our hypotheses, and the inequality (1.3) is equivalent to

$$(1.4) \quad \frac{1}{2}(|u(\bar{t}) - x|^2 - |u(t) - x|^2) \leq \int_t^{\bar{t}} (g(\theta) + y, u(\theta) - x) d\theta + L(|x|) \int_t^{\bar{t}} |u(\theta) - x| \cdot |f(\theta) - f(r)| d\theta$$

for all

$$s \leq t \leq \bar{t}, \quad r \geq s, \quad [x, y] \in A(r).$$

### 2. Weak convergence of the integral solution

LEMMA 2.1. *Suppose  $F$  is a non-empty closed convex set in  $H$ ,  $P_F$  is a projection on  $F$ . Then*

- (2.1)  $(x - P_F x, z - P_F x) \leq 0, \quad \forall z \in F, x \in H.$
- (2.2)  $|P_F x - P_F y| \leq |x - y| \quad \forall x, y \in H.$
- (2.3)  $|P_F x - z|^2 \leq |x - z|^2 - |P_F x - x|^2, \quad \forall x \in H, z \in F.$

Since Lemma 2.1 is well known, its proof will be omitted.

LEMMA 2.2. *Suppose  $u(t)$  is an integral solution to (1.1). If there are  $r_0 \geq s$  and  $g_\infty \in H$  such that  $f - f(r_0) \in L(0, \infty; H)$  and  $g - g_\infty \in L(0, \infty; H)$ , then  $u(t)$  is bounded on  $[s, \infty)$  if and only if  $A^{-1}(r_0)(-g_\infty) \neq \emptyset$ .*

PROOF. Firstly, we suppose that  $u(t)$  is bounded on  $[s, \infty)$ . Since  $u(t)$  is an integral solution of (1.1), then for all  $t \geq s \geq 0$  and  $[x, y] \in A(r_0)$  we have

$$(2.4) \quad \frac{1}{2}(|u(t) - x|^2 - |u_0 - x|^2) \leq \int_s^t (g(\theta) + y, u(\theta) - x) d\theta + L(|x|) \int_s^t |u(\theta) - x| \cdot |f(\theta) - f(r_0)| d\theta.$$

Dividing by  $t - s > 0$ , we obtain

$$(2.5) \quad \frac{1}{2(t-s)}(|u(t) - x|^2 - |u_0 - x|^2) \leq \frac{1}{t-s} \int_s^t (g(\theta) - g_\infty, u(\theta) - x) d\theta + (y + g_\infty, \sigma(t) - x) + \frac{L(|x|)}{t-s} \int_s^t |u(\theta) - x| \cdot |f(\theta) - f(r_0)| d\theta$$

for all  $t > s \geq 0, [x, y] \in A(r_0)$ , where  $\sigma(t) = (t - s)^{-1} \int_s^t u(\theta) d\theta$  is bounded on  $[s, \infty)$ . Therefore there exists a sequence  $t_n \rightarrow \infty$  such that  $\sigma(t_n)$  converges weakly to  $p \in H$ . If we take  $t = t_n$  in (2.5) and let  $n \rightarrow \infty$ , then

$$(2.6) \quad (y + g_\infty, x - p) \leq 0 \quad \text{for all } [x, y] \in A(r_0).$$

The maximality of  $A(r_0)$  implies that  $[p, -g_\infty] \in A(r_0)$ , that is,  $A^{-1}(r_0)(-g_\infty)$  is non-empty.

Conversely, if  $A^{-1}(r_0)(-g_\infty) \neq \emptyset$ , then there exists an element  $x \in D(A(r_0))$  such that  $-g_\infty \in A(r_0)x$ . We take  $y = -g_\infty$  in (2.4) and by a variant of Gronwall's Lemma (see [2, p. 157]) we deduce that  $u(t)$  is bounded on  $[s, \infty)$ . The proof is complete.

**THEOREM 2.3.** *Suppose  $u(t)$  is an integral solution to (1.1). If there are  $f_\infty, g_\infty \in H$  and  $\tau_n \rightarrow \infty$  such that  $f(\tau_n) = f_\infty$  ( $n \in N$ ),  $F = \bigcap_{n=1}^\infty A^{-1}(\tau_n)(-g_\infty) \neq \emptyset$ , then there is  $p \in F$  such that*

$$P_F u(t) \xrightarrow{s} p \quad \text{and} \quad \sigma(t) \xrightarrow{w} p \quad (t \rightarrow \infty).$$

**PROOF.** We may assume  $g_\infty = 0$ ,  $F = \bigcap_{n=1}^\infty A^{-1}(\tau_n)(0)$  (without loss of generality). Since  $A^{-1}(t)$  is maximal dissipative, then  $F$  is a closed convex subset in  $H$ . Take  $x \in F, r = \tau_n$ . By the ‘if’ part of Lemma 2.2,  $u(t)$  is bounded on  $[s, \infty)$  and for all  $x \in F, \bar{t} \geq t \geq s \geq 0$

$$(2.7) \quad |u(\bar{t}) - x| - |u(t) - x| \leq \int_s^{\bar{t}} (|g(\theta)| + L(|x|)|f(\theta) - f_\infty|) d\theta.$$

Hence, for every  $x \in F$ , the function  $t \rightarrow |u(t) - x| - \int_0^t (g(\theta) - L(|x|)|f(\theta) - f_\infty|) d\theta$  is non-increasing and bounded on  $[s, \infty)$ . Since  $g, f - f_\infty \in L(0, \infty; H)$  we conclude that there exists a limit

$$(2.8) \quad \lim_{t \rightarrow \infty} |u(t) - x| = \alpha(x) \quad \text{for every } x \in F.$$

We set  $v(t) = P_F u(t)$ . According to Lemma 2.1 (ii),  $v(t)$  is bounded on  $[s, \infty)$ . Let  $C_1 = \sup_{t \geq s} L(|v(t)|)$ ; for fixed  $t \geq s$  we denote  $y_t(h) = u(t+h), h \geq 0$ . Then  $y_t(h)$  is an integral solution of the following equation:

$$(2.9) \quad \begin{cases} \frac{dy_t(h)}{dh} \in A(t+h)y_t(h) + g(t+h) \\ y_t(0) = u(t). \end{cases}$$

By the same argument above we obtain the function

$$h \rightarrow |y_t(h) - v(t)| - \int_0^h (|g(\theta+t)| + C_1|f(\theta+t) - f_\infty|) d\theta$$

is non-increasing. Hence  $\forall t \geq s, h \geq 0$ ,

$$(2.10) \quad |u(t+h) - v(t)| - \int_t^{t+h} (|g(\theta)| + C_1|f(\theta) - f_\infty|) d\theta \leq |u(t) - v(t)|.$$

This implies that for all  $t \geq s, h \geq 0$ ,

$$\begin{aligned} & |u(t+h) - v(t+h)| - \int_s^{t+h} (|g(\theta)| + C_1|f(\theta) - f_\infty|) d\theta \\ & \leq |u(t+h) - v(t)| - \int_s^t (|g(\theta)| + C_1|f(\theta) - f_\infty|) d\theta \\ & \quad - \int_t^{t+h} (|g(\theta)| + C_1|f(\theta) - f_\infty|) d\theta \\ & \leq |u(t) - v(t)| - \int_s^t (|g(\theta)| + C_1|f(\theta) - f_\infty|) d\theta. \end{aligned}$$

Thus the function  $t \rightarrow |u(t) - v(t)| - \int_s^t (|g(\theta)| + C_1|f(\theta) - f_\infty|) d\theta$  is non-increasing on  $[s, +\infty)$  and there exists  $\lim_{t \rightarrow \infty} |u(t) - v(t)|$ .

Next, by Lemma 2.1 (iii)

$$(2.11) \quad |v(t+h) - v(t)|^2 \leq |u(t+h) - v(t)|^2 - |v(t+h) - u(t+h)|^2.$$

From (2.10) and (2.11) one obtains

$$\begin{aligned} |v(t+h) - v(t)|^2 &\leq |u(t) - v(t)|^2 - |u(t+h) - v(t+h)|^2 \\ &\quad + 2|u(t) - v(t)| \cdot \int_t^{t+h} (|g(\theta)| + C_1|f(\theta) - f_\infty|) d\theta \\ &\quad + \left[ \int_t^{t+h} (|g(\theta)| + C_1|f(\theta) - f_\infty|) d\theta \right]^2. \end{aligned}$$

This implies that there exists  $\lim_{t \rightarrow \infty} v(t) = p$  and  $p \in F$ .

Now suppose  $\sigma(t_k) \xrightarrow{w} y$  ( $t_k \rightarrow \infty$ ). By the ‘only if’ part of Lemma 2.2 for every  $n \in \mathcal{N}$  we have  $y \in F_n = A^{-1}(\tau_n)(-g_\infty)$ ; thus  $y \in F$ . According to Lemma 2.1 (i) we have

$$(2.12) \quad \begin{aligned} (u(t) - v(t), z - v(t)) &\leq 0, \quad \forall z \in F, \\ \frac{1}{t_k} \int_s^{t_k+s} (u(\theta) - v(\theta), z - v(\theta)) d\theta &\leq 0, \quad \forall z \in F. \end{aligned}$$

Letting  $t_k \rightarrow \infty$  in (2.12), one obtains

$$(y - p, z - p) \leq 0, \quad \forall z \in F.$$

This implies that  $y = p$  and  $\sigma(t) \xrightarrow{w} p$  ( $t \rightarrow \infty$ ). The proof is complete.

REMARK 2.4. If  $A(t) \equiv A$ ,  $s = 0$  and  $F = A^{-1}(-g_\infty) \neq \emptyset$ , then from Theorem 2.3 we may obtain respectively the Ergodic Theorem of autonomous systems and quasi-autonomous dissipative systems in [4, 10, 5].

LEMMA 2.5. Suppose  $u(t)$  is an integral solution to (1.1). Then for all  $T > 0$ ,  $h > 0$ ,  $r \geq \tau \geq s \geq 0$  and  $r + h \leq T$ , we have

$$(2.13) \quad \begin{aligned} |u(r+h) - u(\tau+h)| &\leq |u(r) - u(t)| \\ &\quad + \int_\tau^{\tau+h} (C_2|f(\theta + (r - \tau)) - f(\theta)| + |g(\theta + (r - \tau)) - g(\theta)|) d\theta \end{aligned}$$

where  $C_2 = \sup\{L(t) : 0 \leq t \leq \sup\{|u(\theta)| : s \leq \theta \leq T + (r - \tau)\} + 1\}$ .

PROOF. From Theorem 1 (ii) in [11] we get

$$(2.14) \quad |u(t + h_1) - u(t)| \leq |u(\tau + h_1) - u(\tau)| + \int_{\tau}^t (\tilde{C}|f(\theta + h_1) - f(\theta)| + |g(\theta + h_1) - g(\theta)|) d\theta$$

for all  $s \leq \tau \leq t \leq T$  and  $h_1 > 0$ , where  $\tilde{C} = \sup\{L(t) : 0 \leq t \leq \sup\{|u(\theta + h_1)| : s \leq \theta \leq T\} + 1\}$ .

For  $h > 0$ ,  $r \geq \tau \geq s$ , let  $t = \tau + h$  and  $r - \tau = h_1$  in (2.14). One obtains (2.13). The proof is complete.

**THEOREM 2.6.** *Suppose  $u(t)$  is an integral solution to (1.1). If there are  $r_0 \geq s$  and  $g_{\infty} \in H$  such that  $-g_{\infty} \in R(A(r_0))$ ,  $f - f(r_0) \in L(0, \infty; H)$  and  $g - g_{\infty} \in L(0, \infty; H)$ , then there exists  $p \in A^{-1}(r_0)(-g_{\infty})$  such that  $w\text{-}\lim_{t \rightarrow \infty} \sigma(t) = p$ .*

PROOF. Firstly, by Lemma 2.2,  $\sup_{t \geq s} |u(t)| = M < \infty$ . We set  $\epsilon_1(r, \tau) =$

$$\begin{cases} \int_{\tau}^{\infty} M|f(\theta + (r - \tau) - f(\theta)| d\theta + \int_{\tau}^{\infty} |g(\theta + (r - \tau)) - g(\theta)| d\theta, & r \geq \tau, \\ \int_r^{\infty} M|f(\theta + (r - \tau) - f(\theta)| d\theta + \int_r^{\infty} |g(\theta + (r - \tau)) - g(\theta)| d\theta, & r < \tau. \end{cases}$$

Then  $\lim_{r, \tau \rightarrow \infty} \epsilon_1(r, \tau) = 0$ . By Lemma 2.5 and Definition 3.1 in [10] we know that the curve  $(u(t))_{t \geq s}$  is almost non-expansive in  $H$ . Hence by Theorem 3.8 in [10] and the ‘only if’ part of Lemma 2.2 there exists  $w\text{-}\lim_{t \rightarrow \infty} \sigma(t) = p$  and  $p \in A^{-1}(r_0)(-g_{\infty})$ .

**COROLLARY 2.7.** *Suppose  $u(t)$  is an integral solution to (1.1). If there are  $f_{\infty}, g_{\infty} \in H$  and  $T > 0$  such that  $f - f_{\infty} \in L(0, \infty; H)$ ,  $g - g_{\infty} \in L(0, \infty; H)$  and  $F = \bigcap_{t \geq T} A^{-1}(t)(-g_{\infty}) \neq \emptyset$ , then  $\sigma(t)$  is weakly convergent as  $t \rightarrow \infty$ .*

**THEOREM 2.8.** *Suppose  $u(t)$  is an integral solution to (1.1). If there exist  $r_0 \geq s$  and  $g_{\infty} \in H$  such that  $f - f(r_0) \in L(0, \infty; H)$  and  $g - g_{\infty} \in L(0, \infty; H)$ , then there exists  $w\text{-}\lim_{t \rightarrow \infty} u(t)$  if and only if  $F = A^{-1}(r_0)(-g_{\infty}) \neq \emptyset$  and  $\omega_w(x_0) \subset F$ , where  $\omega_w(x_0)$  is the set of weak cluster points of  $\{u(t) : t \geq s\}$ .*

PROOF. ‘Only if’ part: Suppose  $w\text{-}\lim_{t \rightarrow \infty} u(t) = p$ . This implies that  $w\text{-}\lim_{t \rightarrow \infty} \sigma(t) = p$ . From (2.5) it follows that  $p \in F$ .

‘If’ part: Since  $F \neq \emptyset$  and  $\omega_w(x_0) \subset F$ , according to Lemma 2.2,  $\omega_w(x_0) \neq \emptyset$ . Let  $p, q$  be arbitrary in  $\omega_w(x_0) \subset F$ . We have

$$(2.15) \quad |u(t) - p|^2 = |u(t) - q|^2 + 2(u(t) - q, q - p) + |q - p|^2, \quad t \geq s.$$

Now for all  $\bar{t} \geq t \geq s$ ,  $x \in F$  we have

$$|u(\bar{t}) - x| - |u(t) - x| \leq \int_t^{\bar{t}} (|g(\theta) - g_\infty| + L(|x|)|f(\theta) - f(r_0)|) d\theta.$$

Thus the function

$$t \rightarrow |u(t) - x| + \int_0^t (|g(\theta) - g_\infty| + L(|x|)|f(\theta) - f(r_0)|) d\theta$$

is non-increasing on  $[s, \infty)$  and there exists  $\lim_{t \rightarrow \infty} |u(t) - x| = \alpha(x)$ . Now  $p, q \in F$ ; then from (2.15) we get

$$(2.16) \quad \alpha^2(p) - \alpha^2(q) = |q - p|^2$$

and

$$(2.17) \quad \alpha^2(q) - \alpha^2(p) = |p - q|^2.$$

Hence  $p = q$ ,  $\omega_w(x_0)$  contains only one element and  $w\text{-}\lim_{t \rightarrow \infty} u(t) = p$ . The proof is complete.

**LEMMA 2.9.** *Suppose  $u(t)$  is an integral solution to (1.1) with  $g(t) \equiv 0$  and  $x_0 = x$  and  $F$  is a closed subset of  $H$ . If  $\omega_w(x) \subset F$  for all  $x \in D(A(s))$  then  $\omega_w(x) \subset F$  for all  $x \in \overline{D(A(s))}$ .*

**PROOF.** Let  $x \in \overline{D(A(s))}$  and let  $x_n \rightarrow x$  with  $x_n \in D(A(s))$ . If  $y \in \omega_w(x)$  then there exists a sequence  $t_k \rightarrow \infty$  such that  $u(t_k) = U(t_k, s)x \xrightarrow{w} y$ , where  $U(t, s)$  is an evolution operator generated by  $A(t)$ . For every fixed  $n$  the sequence  $|U(t_k, s)x_n|$  is bounded and therefore  $U(t_k, s)x_n$  has a weakly convergent subsequence  $U(t_{k_j}, s)x_n \xrightarrow{w} y_n$ . Clearly  $y_n \in \omega_w(x_n) \subset F$  and

$$|y_n - y| \leq \liminf_{j \rightarrow \infty} |U(t_{k_j}, s)x_n - U(t_{k_j}, s)x| \leq |x_n - x|.$$

Thus  $y_n \rightarrow y$  and  $y \in F$ . The proof is complete.

**THEOREM 2.10.** *Suppose  $u(t)$  is an integral solution to (1.1) with  $g(t) \equiv 0$  and  $x_0 = x$ , the function  $f(t)$  in the condition  $(H_1)$  is of bounded variation on  $[s, T]$  and  $\bigvee_s^T(f) = M_T \leq M_0 < \infty$  for all  $T > s$ . If there exist  $T_0 > s$  and  $f_\infty \in H$  such that  $F = \bigcap_{t \geq T_0} A^{-1}(t)(0) \neq \emptyset$ ,  $f - f_\infty \in L(0, \infty; H)$  and satisfying the condition*

$(H_3)$ : *There exists  $x_0 \in F$  such that  $x_n \xrightarrow{w} x$ ,  $y_n \in A(t_n)x_n$  ( $t_n \rightarrow \infty$ ) and  $\lim_{n \rightarrow \infty} (y_n, x_n - x_0) = 0$  imply  $x \in F$ .*

Then  $u(t) = U(t, s)x$  is weakly convergent as  $t \rightarrow \infty$ .

PROOF. Since  $F$  is a closed convex subset of  $H$ , by Lemma 2.9 it is sufficient to prove that  $\omega_w(x) \subset F$  for every  $x \in D(A(s))$ . Let  $x \in D(A(s))$  and  $y \in \omega_w(x)$  be such that  $u(t_k) = U(t_k, s)x \xrightarrow{w} y$  ( $t_k - t_{k-1} > 1, t_k \rightarrow \infty$ ). Set

$$\check{D}(A(s)) = \{x \in \overline{D(A(s))} : L(s, x) = \lim_{h \rightarrow 0^+} h^{-1} |U(h + s, s)x - x| < \infty\}.$$

Then  $D(A(s)) \subset \check{D}(A(s)) \subset \overline{D(A(s))}$  and for  $x \in D(A(s))$  we have

$$(2.18) \quad |U(\bar{t} + s, s)x - U(t + s, s)x| \leq \omega^{-1}(e^{\omega \bar{t}} - e^{\omega t})[L(s, x) + M_T], \quad \forall \omega > 0$$

(see [5, p. 25]). Since for  $x \in D(A(s))$ ,  $u(t) = U(t, s)x$  is a strong solution to (1.1) with  $g(t) \equiv 0$  and  $x_0 = x$ , we obtain

$$\frac{1}{2} \frac{d}{dt} |u(t) - x_0|^2 = (u'(t), u(t) - x_0), \quad \text{a.e. } t \geq s.$$

Analogously to Theorem 2.8 we can prove that there exists  $\lim_{t \rightarrow \infty} |u(t) - x_0|$  for  $x_0 \in F$ . Thus  $h(t) = (u'(t), u(t) - x_0) \in L(s, +\infty)$ . We shall now prove that there exists a sequence  $\tau_j$  such that  $\tau_j \rightarrow \infty, h(\tau_j) \rightarrow 0$  and  $U(\tau_j, s)x \xrightarrow{w} y$ . For every  $\epsilon > 0$  ( $\epsilon < 1/2$ ) let  $Q_\epsilon = \{t \geq s : h(t) \geq \epsilon\}$ . The measure of  $Q_\epsilon$  is finite since  $h(t) \in L(s, +\infty)$  and therefore  $Q_\epsilon$  can contain at most a finite number of the intervals  $(t_k - \epsilon, t_k)$ . It follows that there exists a  $\tau$  large enough such that  $h(\tau) < \epsilon$  and  $0 < t_k - \tau < \epsilon$  for some  $t_k$  large enough. Therefore, we can choose a sequence  $\tau_j$  such that  $\tau_j \rightarrow \infty, 0 < t_{k_j} - \tau_j < 1/j$  and  $h(\tau_j) < 1/j$ . By (2.18) we have

$$\begin{aligned} |U(t_{k_j}, s)x - U(\tau_j, s)x| &\leq \frac{1}{j}(L(s, x) + M_0), \\ u(\tau_j) &= U(\tau_j, s)x \xrightarrow{w} y. \end{aligned}$$

Since  $u'(\tau_j) \in A(\tau_j)u(\tau_j), \lim_{j \rightarrow \infty} h(\tau_j) = (u'(\tau_j), u(\tau_j) - x_0) = 0$ . By the condition  $(H_3)$  one obtains  $y \in F$ . The proof is complete.

Next, we shall consider the quasi-autonomous dissipative system

$$(2.19) \quad \begin{cases} u'(t) \in Au(t) + f(t), & t > 0 \\ u(0) = x, & x \in \overline{D(A)} \end{cases}$$

where  $A$  is an  $m$ -dissipative operator and  $f \in L(0, \infty; H)$ .

DEFINITION 2.11. A dissipative set  $A$  is 3-dissipative if  $\forall u_1, u_2, u_3 \in D(A)$

$$(2.20) \quad (Au_1, u_1 - u_2) + (Au_2, u_2 - u_3) + (Au_3, u_3 - u_1) \leq 0.$$

**THEOREM 2.12.** *Suppose  $u(t)$  is an integral solution to (2.19),  $F = A^{-1}(0) \neq \emptyset$ . If  $A$  is 3-dissipative, then for every  $x \in \overline{D(A)}$ ,  $\omega_w(x) \subset F$  and  $u(t)$  is weakly convergent as  $t \rightarrow \infty$*

**PROOF.** Firstly, suppose  $f(t)$  is of continuous bounded variation on  $[0, T]$ ,  $\int_0^T (f) = M_T \leq M_0 < \infty (\forall T > 0)$ , and there exists  $T_0 > s$  such that  $f(t) = 0$  for  $t \geq T_0$ . Set  $A(t)x = Ax + f(t)$  for all  $x \in D(A)$  and  $t \geq 0$ . Then the equation (2.19) is equivalent to the evolution equation

$$(2.21) \quad \begin{cases} u'(t) \in A(t)u(t), & t > 0 \\ u(0) = x, & x \in \overline{D(A(0))} = \overline{D(A)} \end{cases}$$

where  $A(t)$  is  $m$ -dissipative,  $F = \bigcap_{t \geq T_0} A^{-1}(t)(0) = A^{-1}(0) \neq \emptyset$  and satisfies the conditions  $(H_1)$  and  $(H_2)$ . Take  $x_0 \in F$ , let  $x_n \xrightarrow{w} x$ ,  $y_n \in A(t_n)x_n = Ax_n + f(t_n)$  ( $t_n \rightarrow \infty$ ) and  $(y_n, x_n - x_0) \rightarrow 0$ . By Definition 2.11, for  $u \in D(A)$  and  $v \in Au$  we have

$$\begin{aligned} 0 &\geq (Ax_n, x_n - x_0) + (A^0x_0, x_0 - u) + (v, u - x_n) \\ &= (y_n, x_n - x_0) + (A^0x_0, x_0 - u) + (v, u - x_n) - (f(t_n), x_n - x_0). \end{aligned}$$

Letting  $n \rightarrow \infty$ , one obtains  $(v, u - x) \leq 0, \forall [u, v] \in A$ .

Thus  $x \in F$  and the condition  $(H_3)$  is valid. By Theorem 2.10, for every  $x \in \overline{D(A)}$ ,  $\omega_w(x) \subset F$  and there is  $w\text{-}\lim_{t \rightarrow \infty} u(t)$ .

For  $f \in L(0, \infty; H)$  there exists  $f_n \in C_0^\infty(0, \infty; H)$  such that  $f_n \rightarrow f$  (in  $L(0, \infty; H)$ ). If  $u_n(t)$  is an integral solution of an initial value problem

$$(2.22) \quad \begin{cases} u'_n(t) \in Au_n(t) + f_n(t), & t > 0 \\ u_n(0) = x, & x \in \overline{D(A)} \end{cases}$$

then clearly, there exists  $s\text{-}\lim_{t \rightarrow \infty} u_n(t) = u(t)$  and the limit is uniformly convergent on  $t \geq 0$ . Moreover, by the proof above, for every  $n$  there exists  $w\text{-}\lim_{t \rightarrow \infty} u_n(t) = p_n$ . This implies that there exist  $s\text{-}\lim_{t \rightarrow \infty} p_n = p$  and  $w\text{-}\lim_{t \rightarrow \infty} u(t) = p$ . The proof is complete.

**REMARK 2.13.** If  $f(t) \equiv 0$  in Theorem 2.12, then for every  $x \in \overline{D(A)}$  there exists  $w\text{-}\lim_{t \rightarrow \infty} S(t)x$ , where  $S(t)$  is a non-linear contraction semigroup generated by  $A$ . This implies the conclusion of Proposition 2.14 in [7].

Let  $-A = \partial\varphi$  be the subdifferential of an l.s.c proper convex function. Then  $A$  is a maximal 3-dissipative operator. Hence we get the conclusion of Theorem 2.3 in [4].

**COROLLARY 2.14.** *Let  $-A = \partial\varphi$  be the subdifferential of an l.s.c proper convex function,  $f \in L(0, \infty; H)$  and  $u(t)$  be an integral solution to (2.19). If  $A^{-1}(0) \neq \emptyset$ , then for every  $x \in \overline{D(A)}$  there exists  $w\text{-}\lim_{t \rightarrow \infty} u(t)$ .*

### 3. Examples

Let  $\Omega$  be a bounded domain in  $\mathbb{R}^n$  with smooth boundary  $\partial\Omega$  and  $H = L^2(\Omega)$ . Let  $\beta \subset \mathbb{R}^1 \times \mathbb{R}^1$  be a maximal monotone and  $0 \in D(\beta)$ . Then there exists an l.s.c proper convex function  $j : \mathbb{R}^1 \rightarrow (-\infty, +\infty]$  such that  $\beta = \partial j$ .

EXAMPLE 3.1. Consider the equation

$$(3.1) \quad \begin{cases} \frac{\partial u}{\partial t} \in \Delta u - \beta(u(t, x)) + f(t, x), & t > 0, \text{ a.e. } x \in \Omega \\ u(t, x) = 0, & x \in \partial\Omega, t \geq 0 \\ u(0, x) = u_0(x), & \text{a.e. } x \in \Omega. \end{cases}$$

Assume  $0 \in R(\beta)$ . For example

$$\beta(x) = \begin{cases} [-e^{-1}, e^{-1}] & \text{if } x = 0 \\ e^{-1}(1 + x) & \text{if } x > 0 \\ e^{-1}(x - 1) & \text{if } x < 0. \end{cases}$$

Then  $\beta \subset \mathbb{R}^1 \times \mathbb{R}^1$  is maximal monotone and  $0 \in \beta(0)$ . We set

$$\varphi(u) = \begin{cases} 2^{-1} \int_{\Omega} |\text{grad } u|^2 dx + \int_{\Omega} j(u) dx, & u \in H_0^1(\Omega), j(u) \in L(\Omega), \\ +\infty & \text{otherwise.} \end{cases}$$

Then  $\varphi : H \rightarrow (-\infty, +\infty]$  is an l.s.c proper convex function. The subdifferential

$$\partial\varphi(u) = \{v \in L^2(\Omega) : v(x) \in \beta(u(x)) - \Delta u(x), \text{ a.e. } x \in \Omega\}$$

and  $\partial\varphi^{-1}(0) \neq \emptyset$ . If  $u_0 \in L^2(\Omega)$  and  $f(t, x) \in L(0, \infty; H)$ , by Corollary 2.14 the integral solution  $u(t)$  of the problem (3.1) is weakly convergent as  $t \rightarrow \infty$  in  $L^2(\Omega)$ .

EXAMPLE 3.2. Let

$$\beta(t)x = \begin{cases} [-e^{-1}, e^{-1}], & \text{if } x = 0 \\ e^{-1}(1 + x) + e^{-t}x, & \text{if } x > 0 \\ e^{-1}(x - 1) + e^{-t}x, & \text{if } x < 0. \end{cases} \text{ for } t \geq 0$$

Then  $\beta(t)$  is a maximal monotone set in  $\mathbb{R}^1 \times \mathbb{R}^1$  for each  $t \geq 0$ ,  $0 \in D(\beta(t))$ ,  $0 \in \beta(t)(0)$  for  $t \geq 0$  and  $D(\beta(t)) = \mathbb{R}^1$  is independent of  $t$ . We consider the equation

$$(3.2) \quad \begin{cases} \frac{\partial u}{\partial t} \in \Delta - \tilde{\beta}(t)u + g(t, x), & t \geq 0, \text{ a.e. } x \in \Omega \\ u(t, x) = 0 & x \in \partial\Omega, t \geq 0 \\ u(0, x) = u_0(x), & \text{a.e. } x \in \Omega \end{cases}$$

where  $g(t, x) \in L(0, \infty; H)$  and  $\tilde{\beta}(t) = \{[u, v] : u, v \in L^2(\Omega) \text{ and } v(x) \in \beta(t)u(x), \text{ a.e. } x \in \Omega\}$ . Let

$$D(A(t)) = H^2(\Omega) \cap H_0^1(\Omega) \cap D(\tilde{\beta}(t)), \quad t \geq 0$$

and

$$A(t)u = \Delta u - \tilde{\beta}(t)u \quad \text{for } u \in D(A(t)).$$

Clearly, each  $A(t)$  is  $m$ -dissipative in  $H$ ,  $D(A(t)) = \mathcal{D}$  is independent of  $t$  and  $0 \in A^{-1}(t)(0)$  for all  $t \geq 0$ . Hence  $(H_2)$  is satisfied. Further we can prove that  $A(t)$  satisfies the condition  $(H_1)$  and the conditions in Corollary 2.7 are valid. By Corollary 2.7, if  $u_0(x) \in L^2(\Omega)$  and  $u(t)$  is an integral solution of the problem (3.2), then  $\sigma(t)$  is weakly convergent as  $t \rightarrow \infty$  in  $L^2(\Omega)$ .

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Department of Mathematics  
Nanjing University  
Nanjing 210008  
China