

Peirce Domains

Yung-Sheng Tai

Abstract. A theorem of Korányi and Wolf displays any Hermitian symmetric domain as a Siegel domain of the third kind over any of its boundary components. In this paper we give a simple proof that an analogous realization holds for any self-adjoint homogeneous cone.

1 Introduction

Suppose D is a Hermitian symmetric domain and F is a boundary component of D . Then the pair (D, F) admits a realization as a *Siegel domain of the third kind* [WK], [PS], [Sa]: there exists a real vectorspace U , a self-adjoint homogeneous cone $C_F \subset U$, a family of bilinear symmetric forms $h_t: \mathbb{C}^k \times \mathbb{C}^k \rightarrow U$ and an embedding $D \rightarrow F \times \mathbb{C}^k \times U(\mathbb{C})$ whose image is defined by the well-known inequality

$$D = \{(t, w, z) \in F \times \mathbb{C}^k \times U(\mathbb{C}) \mid \operatorname{Im}(z) - h_t(w, w) \in C_F\}.$$

In this short note we give a surprisingly simple proof that an analogous realization holds for any pair (C, C_1) where C is a self adjoint homogeneous cone and C_1 is a boundary component of C . Just as the Siegel domain realization of a Hermitian symmetric space D is used to describe the geometry of compactifications of arithmetic quotients $\Gamma \backslash D$ (where Γ is an arithmetic group) [AMRT], [BB], [Sa], the “Peirce domain” realization of the cone C , which we describe in this paper, is likely to be useful in describing compactifications of arithmetic quotients $\Gamma \backslash C$.

We would like to thank M. Goresky and A. Korányi for useful conversations. We would also like to thank the Institute for Advanced Study in Princeton, NJ, for their support and hospitality.

2 Statement of results

2.1

Let $C \subset V$ denote a self adjoint homogeneous (open) cone in a real vectorspace V and let $G = \operatorname{Aut}^0(C, V) \subset GL(V)$ denote the connected component of the group of (linear) automorphisms of C . Fix a basepoint $e \in C$. Then V admits the structure of a Euclidean (= formally real) Jordan algebra with identity element e , and

$$C = \{x^2 \mid x \in V \text{ is invertible}\}$$

may naturally be identified with the symmetric space G/K (where $K = \operatorname{Stab}_G(e)$). Moreover, the cone C , the Jordan algebra V , and the group G determine each other. For any

Received by the editors February 4, 1998; revised April 8, 1998.

AMS subject classification: 17C27.

©Canadian Mathematical Society 1999.

$v \in V$ let $T(v): V \rightarrow V$ denote Jordan multiplication by v and let $P(v): V \rightarrow V$ be the linear mapping given by

$$P(v)(t) = 2v(vt) - v^2t$$

for any $t \in V$. Then P is called the “quadratic representation” and its polarization $P(u, v) = \frac{1}{2}(P(u + v) - P(u) - P(v))$ determines a parametrized family of V -valued bilinear forms

$$h_t(u, v) = P(u, v)t^{-1}$$

for $t \in V$, so that $h_t(v, v) = P(v)(t^{-1})$.

Throughout this paper we fix an idempotent $\epsilon_1 \in V$ and let

$$V = V_1(\epsilon_1) \oplus V_{\frac{1}{2}}(\epsilon_1) \oplus V_0(\epsilon_1)$$

be the resulting Peirce decomposition into the 1, $\frac{1}{2}$, and 0-eigenspaces of $T(\epsilon_1)$, which we will often abbreviate as $V_1, V_{\frac{1}{2}}$, and V_0 whenever there is no danger of confusion. Set $\epsilon_0 = e - \epsilon_1$, and let C_1 (resp. C_0) denote the projection of the cone C to $V_1(\epsilon_1)$ (resp. to $V_0(\epsilon_1) = V_1(\epsilon_0)$). Then $C_1 \subset V_1$ is a self adjoint homogeneous cone with basepoint ϵ_1 and similarly for C_0 .

Theorem 2.2 *The cone C is given by*

$$\begin{aligned} C &= \{ (t, w, z) \mid t \in C_1 \text{ and } z - h_t(w, w) \in C_0 \} \\ &= \{ (t, w, z) \mid z \in C_0 \text{ and } t - h_z(w, w) \in C_1 \}. \end{aligned}$$

3 Preliminaries

3.1

Let us first recall some standard facts about Jordan algebras, most of which may be found in [FK] and [AMRT, Section II]. The cone $C \subset V$ is self-adjoint with respect to some inner product $\langle \cdot, \cdot \rangle$ on V , which may be taken to be given by $\langle x, y \rangle = \text{tr}(T(xy))$ [FK, III.4.1]. This determines an involution $g \mapsto {}^t g$ on G by $\langle gx, y \rangle = \langle x, {}^t gy \rangle$. Moreover, $\theta(g) = {}^t g^{-1}$ is the Cartan involution on G with respect to the choice $e \in C$ of basepoint [AMRT, II Section 3.1] and for all $g \in G$ we have

$$(3.1.1) \quad \theta(g)(e) = {}^t g^{-1}(e) = (ge)^{-1}$$

(the latter inverse taken in the Jordan algebra). For all $g \in G$ and all $v \in V$ we have [FK, III.5.2],

$$(3.1.2) \quad P(gv) = gP(v){}^t g.$$

Let $Q = \text{Norm}(C_1(\epsilon_1)) \subset G$ denote the parabolic subgroup which normalizes $C_1(\epsilon_1)$. Let $\mathcal{U}(Q)$ denote its unipotent radical and $L(Q) = Q/\mathcal{U}(Q)$ its Levi quotient. Then the choice $e \in C$ of basepoint determines a canonical lift [BS] $L(Q) \subset G$ of the Levi quotient; it is the subgroup of G which normalizes both $C_1(\epsilon_1)$ and $C_0(\epsilon_1)$.

Lemma 3.2 *In these coordinates, the action of Q on V is given by*

$$g.v = \begin{pmatrix} A & M & N \\ 0 & C & D \\ 0 & 0 & B \end{pmatrix} \begin{pmatrix} v_1 \\ v_{\frac{1}{2}} \\ v_0 \end{pmatrix}$$

(where A, M, N, C, D and B are linear mappings which depend on g). Furthermore,

1. $g \in L(Q)$ iff $M = 0, N = 0, D = 0$.
2. If $g \in \mathcal{U}(Q)$ then $A = I$ and $B = I$.
3. The orbit of the basepoint $e = (\epsilon_1, 0, \epsilon_0)$ under $L(Q)$ is the product $C_1 \times \{0\} \times C_0$.

If $x = (x_1, x_{\frac{1}{2}}, x_0)$ satisfies $x_{\frac{1}{2}} = 0$ then $x \in C$ iff $x_1 \in C_1$ and $x_0 \in C_0$.

The Jordan product satisfies: $V_1V_1 \subset V_1, V_0V_0 \subset V_0, V_1V_0 = \{0\}, V_{\frac{1}{2}}V_{\frac{1}{2}} \subset V_1 \oplus V_0, V_1V_{\frac{1}{2}} \subset V_{\frac{1}{2}},$ and $V_0V_{\frac{1}{2}} \subset V_{\frac{1}{2}}$. If $x = (x_1, x_{\frac{1}{2}}, x_0)$ let $x' = (x_1, -x_{\frac{1}{2}}, x_0)$. Then $(xy)' = x'y'$ for all $x, y \in V$, as may be seen by setting $y = (y_1, y_{\frac{1}{2}}, y_0)$ and multiplying out both sides. Hence, $x \in V$ is invertible iff x' is invertible, and in this case $(x')^{-1} = (x^{-1})'$. Similarly, $x = u^2$ for some $u \in V$ iff $x' = (u')^2$. From this it follows that

$$(3.2.1) \quad x \in C \iff x' \in C.$$

Every $x \in V$ has an eigenvalue decomposition $x = \sum_{i=1}^r \lambda_i f_i$ where the f_i form a Jordan frame, (i.e., they are orthogonal idempotents, $f_1 + \dots + f_r = e$, and $r = \dim_{\mathbb{R}}(V)$) and where $\{\lambda_i\} \subset \mathbb{R}$ are the eigenvalues of the linear transformation $T(x): V \rightarrow V$. Moreover $x \in C$ iff $\lambda_i > 0$ for $i = 1, 2, \dots, r$.

Lemma 3.3 *Let $b \in V_{\frac{1}{2}}$. Then $e + b \in C \iff e - b^2 \in C$.*

Proof 3.4 Let $\lambda_1, \lambda_2, \dots, \lambda_r$ denote the eigenvalues of b . Then the eigenvalues of $e - b$ are $\{1 - \lambda_i\}$ and the eigenvalues of $e - b^2$ are $\{1 - \lambda_i^2\}$. By (3.2.1) we see that $e + b \in C$ iff $(e + b)' = e - b \in C$ iff $e \pm b \in C$ iff $1 \pm \lambda_i > 0$ iff $1 - \lambda_i^2 > 0$ iff $e - b^2 \in C$. ■

Lemma 3.5 *Let $b \in V_{\frac{1}{2}}$ and set $b^2 = (y_1, 0, y_0)$. Then $y_1 = \epsilon_1 b^2, y_0 = \epsilon_0 b^2$, and $b y_1 = b y_0$.*

Proof 3.6 Compute $\epsilon_1 b^2 = \epsilon_1(y_1 + y_0) = \epsilon_1 y_1 = y_1$ and similarly $\epsilon_0 b^2 = y_0$. Hence $b y_1 = b(b^2 \epsilon_1) = b^2(b \epsilon_1) = b^2 \frac{1}{2} b$. But a similar calculation gives $b y_0 = \frac{1}{2} b^3$. ■

Proposition 3.7 *Let $b \in V_{\frac{1}{2}}$ and write $b^2 = (y_1, 0, y_0)$. Then $e + b \in C$ iff $\epsilon_1 - y_1 \in C_1$ iff $\epsilon_0 - y_0 \in C_0$.*

Proof 3.8 By Lemma 3.3, $e + b \in C$ iff $e - b^2 = (\epsilon_1 - y_1, 0, \epsilon_0 - y_0) \in C$ iff $\epsilon_1 - y_1 \in C_1$ and $\epsilon_0 - y_0 \in C_0$. So it suffices to show that $\epsilon_1 - y_1 \in C_1$ iff $\epsilon_0 - y_0 \in C_0$. Find Jordan frames for $y_1 \in V_1$ and $y_0 \in V_0$, say $y_1 = \sum_{i=1}^m \lambda_i c_i$ and $y_0 = \sum_{j=1}^n \mu_j d_j$ with $\sum c_i = \epsilon_1$ and $\sum d_j = \epsilon_0$, so that

$$(3.8.1) \quad b^2 = \sum_{i=1}^m \lambda_i c_i + \sum_{j=1}^n \mu_j d_j.$$

We claim that (for any $b \in V_{\frac{1}{2}}$), the set of nonzero eigenvalues $\{1 - \lambda_i\}$ of $e_1 - y_1$ coincides with the set of nonzero eigenvalues $\{1 - \mu_j\}$ of $e_0 - y_0$.

The vectorspace $V_{\frac{1}{2}}$ decomposes,

$$V_{\frac{1}{2}} = \bigoplus_{i=1}^m \bigoplus_{j=1}^n V_{\frac{1}{2}}(c_i) \cap V_{\frac{1}{2}}(d_j)$$

with respect to which we may write $b = \sum_{i,j} b_{ij}$. So

$$by_1 = \left(\sum_{i=1}^m \sum_{j=1}^n b_{ij} \right) \left(\sum_{k=1}^m \lambda_k c_k \right) = \sum_{k=1}^m \sum_{j=1}^n \lambda_k \frac{1}{2} b_{kj}$$

since $c_k b_{ij} = 0$ for $k \neq i$ and $c_k b_{kj} = \frac{1}{2} b_{kj}$. Similarly,

$$by_0 = \left(\sum_{i=1}^m \sum_{j=1}^n b_{ij} \right) \left(\sum_{\ell=1}^n \mu_\ell d_\ell \right) = \sum_{\ell=1}^n \frac{1}{2} \sum_{i=1}^m \mu_\ell b_{i\ell}.$$

By Lemma 3.5 these are equal, hence equating components we obtain:

$$(3.8.2) \quad \text{if } b_{ij} \neq 0 \text{ then } \lambda_i = \mu_j.$$

Therefore it suffices to show that if $\lambda_i \neq 0$ (with $1 \leq i \leq m$) there exists a j such that $b_{ij} \neq 0$, (and that if $\mu_j \neq 0$ (with $1 \leq j \leq n$) there exists an i such that $b_{ij} \neq 0$).

To see this, first compute $b^2 = (\sum_{i,j} b_{ij})(\sum_{k,\ell} b_{k\ell})$. Then we find

1. $b_{ij}b_{k\ell} = 0$ if $i \neq k$ and $j \neq \ell$
2. $b_{ij}b_{kj} \in V_{\frac{1}{2}}(c_i) \cap V_{\frac{1}{2}}(c_k)$ for $i \neq k$
3. $b_{ij}b_{i\ell} \in V_{\frac{1}{2}}(d_j) \cap V_{\frac{1}{2}}(d_\ell)$ for $j \neq \ell$
4. $b_{ij}b_{ij} = \frac{1}{2} \|b_{ij}\|^2 (c_i + d_j)$.

But $b^2 \in \bigoplus_{i=1}^m V_1(c_i) \oplus \bigoplus_{j=1}^n V_1(d_j)$ so terms of type (2) and (3) (namely $\sum_{j=1}^n b_{ij}b_{kj}$ for $i \neq k$ and $\sum_{i=1}^m b_{ij}b_{i\ell}$ for $j \neq \ell$) must vanish, i.e.,

$$b^2 = \sum_{i=1}^m \sum_{j=1}^n \frac{1}{2} \|b_{ij}\|^2 (c_i + d_j).$$

Comparing this with (3.8.1) we obtain

$$\lambda_i = \frac{1}{2} \sum_{j=1}^n \|b_{ij}\|^2 \quad \text{and} \quad \mu_j = \frac{1}{2} \sum_{i=1}^m \|b_{ij}\|^2.$$

It follows that if $\lambda_i \neq 0$ then $b_{ij} \neq 0$ for some j (in which case (3.8.2) implies that $\lambda_i = \mu_j$), and similarly if $\mu_j \neq 0$ then $b_{ij} \neq 0$ for some i (in which case (3.8.2) implies that $\mu_j = \lambda_i$). This concludes the proof that $e_1 - y_1$ has the same eigenvalues as $e_0 - y_0$ so it also concludes the proof of Proposition 3.7. ■

Lemma 3.9 Let $b \in V_{\frac{1}{2}}$. Set $b^2 = (y_1, 0, y_0)$ as above. Then $P(b)(\epsilon_0) = y_1$ and $P(b)(\epsilon_1) = y_0$. Moreover, if $v_0 \in C_0$ then $P(b)(v_0) \in \overline{C_1}$. If $v_1 \in C_1$ then $P(b)(v_1) \in \overline{C_0}$.

Proof 3.10 Compute $P(b)(\epsilon_1) = 2b(b\epsilon_1) - b^2\epsilon_1 = 2b(\frac{1}{2}b) - b^2\epsilon_1 = b^2(e - \epsilon_1) = \epsilon_0 b^2 = y_0$. Similarly for $P(b)(\epsilon_0)$. Now let $v_0 \in C_0$. Let $L(Q)$ be the Levi subgroup of G which preserves both $C_1(\epsilon_1)$ and $C_0(\epsilon_0)$. Then there exists $g \in L(Q)$ so that $g\epsilon_0 = v_0$. By (3.1.2) we see that $P({}^tgb) = {}^t gP(b)g$ hence

$$P(b)v_0 = P(b)(g\epsilon_0) = ({}^t g)^{-1}P({}^tgb)(\epsilon_0).$$

By Lemma 3.2, the element $\tilde{b} = {}^tgb \in V_{\frac{1}{2}}$ so by the first part of Lemma 3.9, $P(\tilde{b})(\epsilon_0) \in \overline{C_1}$ hence the same is true for $({}^t g)^{-1}P(\tilde{b})(\epsilon_0)$. Similar remarks apply to $P(b)(v_1)$. ■

4 Proof of Theorem 2.2

Let $x = (t, w, z) \in V$ and suppose that $t \in C_1$ and $z - P(w)t^{-1} \in C_0$. By Lemma 3.9, $P(w)t^{-1} \in \overline{C_0}$ hence $z \in C_0$. So there exists $g \in L(Q)$ in so that $gt = \epsilon_1$ and $gz = \epsilon_0$. Set $b = g(w) \in V_{\frac{1}{2}}$. Then $g(z - P(w)t^{-1}) \in C_0$, which is

$$\begin{aligned} g(z - P(w)t^{-1}) &= \epsilon_0 - P(gw)({}^t g)^{-1}t^{-1} \quad \text{by (3.1.2)} \\ &= \epsilon_0 - P(b)\epsilon_1 \quad \text{by (3.1.1)} \\ &= \epsilon_0 - y_0 \quad \text{by 3.9} \end{aligned}$$

where $b^2 = (y_1, 0, y_0)$. By Proposition 3.7, $e + b = (\epsilon_1, b, \epsilon_0) \in C$, hence $g^{-1}(e + b) = (t, w, z) \in C$.

The reverse implication is similar: if $x = (t, w, z) \in V$ then $t \in C_1$ and $z \in C_0$ hence there exists $g \in L(Q)$ so that $gt = \epsilon_1$, $gz = \epsilon_0$ and we set $b = gw \in V_{\frac{1}{2}}$. Hence $e + b = gx \in C$ so by Proposition 3.7, $\epsilon_0 - y_0 \in C_0$. Running the above equalities backwards, we find $g(z - P(w)t^{-1}) \in C_0$ hence also $z - P(w)t^{-1} \in C_0$. ■

References

- [AMRT] A. Ash, D. Mumford, M. Rapoport and Y.-S. Tai, *Smooth Compactification of Locally Symmetric Varieties*. Math. Sci. Press, Brookline, MA, 1975.
- [BB] W. Baily and A. Borel, *Compactifications of arithmetic quotients of bounded symmetric domains*. Ann. Math. **84**(1966), 442–528.
- [BS] A. Borel and J.-P. Serre, *Corners and arithmetic groups*. Comment. Math. Helv. **48**(1973), 436–491.
- [FK] J. Faraut and A. Korányi, *Analysis on Symmetric Cones*. Oxford University Press, Oxford, 1994.
- [PS] I. I. Piatetskii-Shapiro, *Automorphic Functions and the Geometry of Classical Domains*. Gordon and Breach, NY, 1969. (Russian edition published earlier.)
- [Sa] I. Satake, *Algebraic Structures of Symmetric Domains*. Princeton University Press, Princeton, NJ, 1980.
- [WK] J. Wolf and A. Korányi, *Generalized Cayley transformations of bounded symmetric domains*. Amer. J. Math. **87**(1965), 899–939.

Department of Mathematics
Haverford College
Haverford, PA
USA