

CORRIGENDUM

Corrigendum: Multi-contact bipedal robotic locomotion

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doi:10.1017/S0263574715000995

Published by Cambridge University Press, 2 December, 2015.

In Eq. (22), the x symbol was incorrectly represented by an @ symbol, therefore the equation should correctly read as

$$\begin{aligned}\dot{x} &= f_v(x) + g_v(x)u, \\ y_v &= y_v^a(x) - y_v^d(x).\end{aligned}$$

Similar errors were also found in the sentence following Eq. (22). In this sentence, the correct math symbol should be $y_v^a(x)$ and $y_v^d(x)$ instead of $y_v^a(@)$ and $y_v^d(@)$.

References

1. H., Zhao, A., Hereid, W.-L., Ma and A. D. Ames, “Multi-contact bipedal robotic locomotion,” *Robotica*, Available on CJO2015. doi: 10.1017/S0263574715000995.