

COINCIDENCE AND COMMON FIXED POINTS OF HYBRID CONTRACTIONS

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Abstract

In this paper, we show the existence of solutions of functional equations $f_i x \in Sx \cap Tx$ and $x = f_i x \in Sx \cap Tx$ under certain nonlinear hybrid contraction and asymptotic regularity conditions, generalize and improve a recent result due to Kaneko concerning common fixed points of multivalued mappings weakly commuting with a single-valued mapping and satisfying a generalized contraction type. Some related results are also obtained.

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1. Introduction

Nadler [12] proved a fixed point theorem for multi-valued contraction mappings, which is called Nadler's contraction principle. Subsequently, a number of generalization of Nadler's contraction principle were obtained by Ćirić [23], Khan [8], Kubiak [9], Kaneko [6, 7], Sessa [14, 19], Singh [10] and many others [22, 24].

Recently, non-linear hybrid contractions, that is, contraction types involving single-valued and multi-valued mappings have been studied by Mukherjee [11], Naimpally *et al.* [13], Rhoades *et al.* [16] and Sessa *et al.* [20, 19].

In this paper, we show the existence of solutions of functional equations

$f_i x \in Sx \cap Tx$ and $x = f_i \in Sx \cap Tx$ under certain non-linear hybrid contraction and asymptotic regularity conditions where $\{f_i\}$ is a family of single-valued mappings on a metric space, S and T are multi-valued mappings on a metric space. Our results are generalizations and improvements of some results due to Kaneko, Kubiak, Mukherjee, Nainpally *et al.*, Rhoades *et al.* and many others. Also, we obtain other related results by using the proximality of sets.

2. Preliminaries

Let (X, d) be a metric space. A subset K of X is said to be *proximal* if for each $x \in X$, there exists a point $y \in K$ such that $d(x, y) = D(x, K)$, where $D(x, A)$ denotes the ordinary distance between $x \in X$ and a non-empty subset A of X . We shall use the following notation and definitions:

$$CL(X) = \{A : A \text{ is a non-empty closed subset of } X\},$$

$$CB(X) = \{A : A \text{ is a non-empty closed and bounded subset of } X\},$$

$$C(X) = \{A : A \text{ is a non-empty compact subset of } X\} \text{ and}$$

$$P_x(X) = \{A : A \text{ is a non-empty proximal subset of } X\}.$$

For $A, B \in CL(X)$ and $\varepsilon > 0$.

$$N(\varepsilon, A) = \{x \in X : d(x, a) < \varepsilon \text{ for some } a \in A\},$$

$$E_{A,B} = \{\varepsilon > 0 : A \subseteq N(\varepsilon, B) \text{ and } B \subseteq N(\varepsilon, A)\}, \text{ and}$$

$$H(A, B) = \begin{cases} \inf E_{A,B}, & \text{if } E_{A,B} \neq \emptyset \\ +\infty, & \text{if } E_{A,B} = \emptyset. \end{cases}$$

H is called the generalized Hausdorff distance function for $CL(X)$ induced by the metric d , and H defined on $CB(X)$ is said to be the Hausdorff metric induced by d .

It is well-known that $P_x(X) \subset CL(X)$ and $C(X) \subset P_x(X)$ ([21]).

Let $\{f_i\}$ be a family of a single-valued mappings from X to itself and S, T be multi-valued mappings from X to the non-empty subsets of X .

DEFINITION 2.1. If, for $x_0 \in X$, there exist sequences $\{x_n\}$ and $\{y_n\}$ in X such that

$$\begin{aligned} y_{2n} &= f_{2n} x_{2n-1} \in Sx_{2n} & \text{for every } n \in \mathbb{N}, \\ y_{2n+1} &= f_{2n+1} x_{2n} \in Tx_{2n+1} & \text{for every } n \in \mathbb{N}_0 = \mathbb{N} \cup \{0\}, \end{aligned}$$

then $O_{f_i}(x_0) = \{y_n : n = 0, 1, 2, \dots\}$ is said to be the *orbit for* $(S, T; f_i)$ at x_0 . Further, $O_{f_i}(x_0)$ is called a *regular orbit for* $(S, T; f)$ if

$$d(y_n, y_{n+1}) \leq \begin{cases} H(Sx_{n-1}, Tx_n), & \text{if } n \text{ is odd,} \\ H(Tx_{n-1}, Sx_n), & \text{if } n \text{ is even.} \end{cases}$$

DEFINITION 2.2. If, for $x_0 \in X$, there exist sequences $\{x_n\}$ and $\{y_n\}$ in X such that every Cauchy sequence of the form $o_{f_i}(x_0)$ converges in X , then X is called $(S, T; f_i)$ -*orbitally complete with respect to* x_0 or simply $(S, T; f_i, x_0)$ -*orbitally complete*.

If, for each $i \in \mathbb{N}$, f_i is an identity mapping on X , then $O_{f_i}(x_0)$ is denoted by $O(x_0)$ and $(S, T; f_i, x_0)$ -*orbitally completeness* by $(S, T; x_0)$ -*orbital completeness*.

DEFINITION 2.3. A pair (S, T) is said to be *asymptotically regular at* $x_0 \in X$ if for any sequence $\{x_n\}$ in X and each sequence $\{y_n\}$ in X such that $y_n \in Sx_{n-1} \cup Tx_{n-1}$, $\lim_{n \rightarrow \infty} d(y_n, y_{n+1}) = 0$.

We remark that Definitions 2.1–2.3 with $S = T$ and $f_i = f$ for each $i \in \mathbb{N}$ reduce to Definitions 4, 6 and 7 of [16], respectively, and orbital completeness need not imply the completeness of the space. Evidently, a complete space is orbitally complete.

DEFINITION 2.4. For each $i \in \mathbb{N}$, the mappings f_i and S are said to be *commuting at a point* $x \in X$ ([2]) if $f_i Sx \subseteq S f_i x$. The mappings f_i and S are said to be *commuting on* X if $f_i Sx \subseteq S f_i x$ for every point $x \in X$.

In [17], Sessa introduced the concept of weak commutativity for single-valued mappings on a metric space and Sessa *et al.* [19] extended this concept to the setting of a single-valued mapping and a multi-valued mapping on a metric space.

DEFINITION 2.5. For each $i \in \mathbb{N}$, the mappings f_i and S are said to be *weakly commuting at* $x \in X$ if $H(f_i Sx, S f_i x) \leq D(f_i x, Sx)$. The mapping f and S are said to be *weakly commuting on* X if they are weakly commuting at every $x \in X$.

Note that commutativity implies weak commutativity, but the converse need not be true even in the case of single-valued mappings as shown in Section 4.

EXAMPLE. Let $x = \{1, 2, 3, 4\}$, define a metric d on x and mappings f, S on X as follows:

$$d(1, 2) = d(3, 4) = 2, \quad d(1, 3) = d(2, 4) = 1$$

$$d(1, 4) = d(2, 3) = 3/2,$$

$$S(1) = S(3) = \{4\}, \quad S(2) = S = S(4) = \{3\},$$

$$f(1) = f(2) = f(4) = 2, \quad f(4) = 1, \text{ respectively.}$$

Then we have $Sf(1) = \{3\}$ and $fS(1) = \{1\}$ and so f and S do not commute at $x = 1$, but f and S are weakly commuting at $x = 1$ since

$$H(Sf(1), fS(1)) = D(f(1), S(1)) = 2.$$

Let \mathcal{F} be the family of all mappings ϕ from the set R^+ of non-negative real numbers to itself such that \emptyset is upper-semicontinuous, non-decreasing and $\phi(t) < t$ for any $t > 0$.

The following theorem is an interesting result for the existence of coincidence points of non-linear hybrid contractions:

THEOREM 2.1. [16] *Let T be a multi-valued mapping from a metric space X into $CL(X)$. If there exists a mapping f from X into itself such that $T(X) \subseteq f(X)$, for each $x, y \in X$ and $\phi \in \mathcal{F}$,*

- (2.1) $H(Tx, Ty) \leq \phi(\max(D(fx, Tx), D(fy, Ty), D(fx, Ty), D(fy, Tx), d(fx, fy)))$,
- (2.2) $\phi(t) < qt$ for each $t > 0$ and for some $0 < q < 1$,
- (2.3) *there exists a point $x_0 \in X$ such that T is asymptotically regular at x_0 and $f(X)$ is $(T; f, x_0)$ -arbitrarily complete, then f and T have a coincidence point in X .*

If f is not the identity mapping, then the commuting mappings f and T satisfying the hypotheses of Theorem 2.1 need not have a common fixed point in X .

Now we can consider: What additional conditions will guarantee the existence of a common fixed point of f and T ?

In [16], Rhoades *et al.* gave the solution to this problem. In this paper, we also investigate different sets of conditions under which the fixed point equation

$$x = f_i x \in Sx \cap Tx \quad \text{for } x \in X \text{ and each } i \in \mathbb{N}$$

possesses a solution.

3. Results

Now we are ready to give our main theorems:

THEOREM 3.1. *Let S and T be multi-valued mappings from a metric space X into $P_X(x)$ and let $\{f_i\}$ be the family of all continuous mappings from X into itself such that*

$$(3.1) \quad S(X) \cup T(X) \subset f_i(X) \text{ for each } i \in \mathbb{N},$$

$$(3.2) \quad H(Sx, Tx) \leq$$

$$\phi(\max(D(f_i x, Sx), D(f_j y, Ty), D(f_i x, Ty), D(f_j y, Sx), d(f_i x, f_j y)))$$

for each $x, y \in X, i, j \in \mathbb{N}, i \neq j$ and $\phi \in \mathcal{F}$,

$$(3.3) \quad \phi(t) \leq qt \text{ for each } t > 0 \text{ and for some fixed } q \in (0, 1),$$

(3.4) *there exists a point $x_0 \in X$ such that the pair (S, T) is asymptotically regular at x_0 , and*

(3.5) *for each $i \in \mathbb{N}$, $f_i(X)$ is $(S, T; f_i, x_0)$ -orbitally complete.*

Then (1) f_i, S and T have a coincidence point in X .

If z is a coincidence point of f_i, S and T and $f_i z$ is a fixed point of f_i , then we have:

(2) $f_i z$ is also a fixed point of S provided f_i is weakly commuting with S at z for every even $i \in \mathbb{N}$ for any odd $j \in \mathbb{N}$;

(3) $f_i z$ is also a fixed point of T provided f_i is weakly commuting with T at z ;

(4) $f_i z$ is a common fixed point of S and T provided f_i is weakly commuting with each of S and T at z .

PROOF. (1) Let x_0 be a point in X satisfying (3.4). Since $S(X) \cup T(X) \subset f_i(X)$, for each $i \in \mathbb{N}$, we can find sequences $\{x_n\}$ and $\{y_n\}$ in X such that

$$y_{2n} = f_{2n} x_{2n-1} \in Sx_{2n} \quad \text{for every } n \in \mathbb{N},$$

$$y_{2n+1} = f_{2n+1} x_{2n} \in Tx_{2n+1} \quad \text{for every } n \in \mathbb{N}_0,$$

$$d(y_{2n}, y_{2n+1}) \leq q^{-1/2} H(Sx_{2n}, Tx_{2n+1}) \quad \text{and}$$

$$d(y_{2n+1}, y_{2n+2}) \leq q^{-1/2} H(Tx_{2n+1}, Sx_{2n+2}).$$

By (3.4), we have $\lim_{n \rightarrow \infty} d(y_n, y_{n+1}) = 0$.

Now, we want to show that $\{y_{2n}\}$ is a Cauchy sequence in $f_i(X)$. Suppose that the sequence $\{y_{2n}\}$ is not a Cauchy sequence. Then there exists a positive

number ε such that, for each positive integer κ , there exist integers $n(\kappa)$ and $m(\kappa)$ such that

$$(3.a) \quad \kappa \leq n(\kappa) < m(\kappa)$$

and

$$(3.b) \quad d(y_{2n(\kappa)}, y_{2m(\kappa)}) \geq \varepsilon.$$

Let $d_{i,j} = d(y_i, y_j)$ and $d_i = d(y_i, y_{i+1})$ for each $i, j \in \mathbb{N}$. Then, for each integer κ , we have

$$(3.c) \quad \varepsilon \leq d_{2n(\kappa), 2m(\kappa)} \leq d_{2n(\kappa), 2m(\kappa)-2} + d_{2m(\kappa)-2} + d_{2m(\kappa)-1}.$$

For each integer κ , let $m(\kappa)$ denote the smallest integer satisfying (3.a) and (3.b) for some $n(\kappa)$. Then we have $d_{2n(\kappa), 2m(\kappa)-2} < \varepsilon$ and it follows from (3.c) that

$$(3.d) \quad \lim_{\kappa \rightarrow \infty} d_{2n(\kappa), 2m(\kappa)} = \varepsilon.$$

Using the triangle inequality, we get

$$\begin{aligned} |d_{2n(\kappa), 2m(\kappa)-1} - d_{2n(\kappa), 2m(\kappa)}| &\leq d_{2m(\kappa)-1} \quad \text{and} \\ |d_{2n(\kappa)+1, 2m(\kappa)-1} - d_{2n(\kappa), 2m(\kappa)}| &\leq d_{2n(\kappa)} + d_{2m(\kappa)-1}, \end{aligned}$$

which yield

$$\lim_{\kappa \rightarrow \infty} d_{2n(\kappa), 2m(\kappa)-1} = \lim_{\kappa \rightarrow \infty} d_{2n(\kappa)+1, 2m(\kappa)-1} = \varepsilon$$

in view of (3.4) and (3.d) and so, by (3.2), we have

$$\begin{aligned} d_{2n(\kappa), 2m(\kappa)} &\leq d_{2n(\kappa)} + d_{2n(\kappa)+1, 2m(\kappa)} \\ &\leq d_{2n(\kappa)} + q^{-1/2} H(Sx_{2m(\kappa)}, Tx_{2n(\kappa)+1}) \\ &\leq d_{2n(\kappa)} + q^{-1/2} \phi \left(\max \left(D(f_{2m(\kappa)+1}x_{2m(\kappa)}, Sx_{2m(\kappa)}), \right. \right. \\ &\quad D(f_{2n(\kappa)+2}x_{2n(\kappa)+1}, Tx_{2n(\kappa)+1}), D(f_{2n(\kappa)+2}x_{2n(\kappa)+1}, Sx_{2m(\kappa)}), \\ &\quad \left. \left. D(f_{2m(\kappa)+1}x_{2m(\kappa)}, Tx_{2n(\kappa)+1}), d(f_{2m(\kappa)+1}x_{2m(\kappa)}, f_{2n(\kappa)+2}x_{2n(\kappa)+1}) \right) \right), \\ &\leq d_{2n(\kappa)} + q^{-1/2} \phi \left(\max \left(d_{2m(\kappa)}, d_{2n(\kappa)+1}, d_{2n(\kappa)+2, 2m(\kappa)}, \right. \right. \\ &\quad \left. \left. d_{2n(\kappa)+1, 2m(\kappa)+1}, d_{2n(\kappa)+2, 2m(\kappa)+1} \right) \right). \end{aligned}$$

Using the upper semicontinuity of ϕ and letting $\kappa \rightarrow \infty$, this inequality yields

$$\varepsilon \leq q^{-1/2} \phi(\varepsilon) \leq q^{-1/2} q\varepsilon < \varepsilon$$

since $\varepsilon > 0$ and $q^{1-1/2} < 1$, which contradicts the choice of ε and so the sequence $\{y_{2n}\}$ is a Cauchy sequence. Similarly, we can prove that $\{y_{2n+1}\}$ is also a Cauchy sequence in $f_i(X)$.

Since $f_i(X)$ is $(S, T; f_i, x_0)$ -orbitally complete, the Cauchy sequence $\{y_{2n}\}$ has a limit u in $f_i(X)$ for each $i \in \mathbb{N}$. By condition (3.4), we have

$$0 = \lim_{n \rightarrow \infty} d(y_{2n}, y_{2n+1}) = \lim_{n \rightarrow \infty} d(u, y_{2n+1})$$

and so $\{y_{2n+1}\}$ also converges to u .

Hence there is a point $z \in X$ such that $f_i z = u$. By condition (3.2), for any even $i \in \mathbb{N}$,

$$\begin{aligned} D(f_i z, Sz) &\leq d(f_i z, y_{2n+1}) + D(y_{2n+1}, Sz) \\ &\leq d(f_i z, y_{2n+1}) + H(Sz, Tx_{2n+1}) \\ &\leq d(f_i z, y_{2n+1}) + \phi \left(\max \left(D(f_i z, Sz), D(f_{2n+2} x_{2n+1}, Tx_{2n+1}), \right. \right. \\ &\quad \left. \left. D(f_i z, Tx_{2n+1}), D(f_{2n+2} x_{2n+1}, Sz), d(f_i z, f_{2n+2} x_{2n+1}) \right) \right) \\ &\leq d(f_i z, y_{2n+1}) + \phi \left(\max \left(D(f_i z, Sz), D(y_{2n+2}, Tx_{2n+1}), \right. \right. \\ &\quad \left. \left. D(f_i z, Tx_{2n+1}), D(y_{2n+2}, Sz), d(f_i z, y_{2n+2}) \right) \right) \\ &\leq d(f_i z, y_{2n+1}) + \phi \left(\max \left(D(f_i z, Sz), d(y_{2n+2}, y_{2n+1}), \right. \right. \\ &\quad \left. \left. d(f_i z, y_{2n+1}), d(y_{2n+2}, f_i z) + D(f_i z, Sz), d(f_i z, y_{2n+2}) \right) \right). \end{aligned}$$

Letting $n \rightarrow \infty$, this inequality yields

$$D(f_i z, Sz) \leq \phi \left(\max \left(D(f_i z, Sz) 0, 0, D(f_i z, Sz), 0 \right) \right).$$

If $f_i z \notin Sz$ for any even $i \in \mathbb{N}$, then $D(f_i z, Sz) > 0$ and the above inequality implies

$$D(f_i z, Sz) \leq \phi(D(f_i z, Sz)) < D(f_i z, Sz),$$

which is a contradiction.

Hence $f_i z \in Sz$ for every even $i \in \mathbb{N}$ since every proximal set is closed. Similarly, we have $f_i z \in Tz$ for any odd $i \in \mathbb{N}$. Therefore, z is a coincidence point of f_i, S and T for each $i \in \mathbb{N}$.

(2) If for any even $i \in \mathbb{N}$, $u = f_i z$ is a fixed point of f_i , then $u = f_i u = f_i f_i z \in f_i Sz$. If f_i is weakly commuting with S at z , then $f_i Sz = S f_i z$ since

$f_i z \in Sz$. Therefore, we have $u \in f_i Sz = S f_i z = Su$; that is, u is a fixed point of S .

We can also prove (3) by the same techniques, and by (2) and (3), we have (4).

Since (2.3) implies (3.2), Theorem 3.1 with $S = T$ and $f_i = I_X$ (the identity mapping on X) improves slightly Theorem 2.1. Theorem 3.1 remains true when we replace $P_x(X)$ by $CL(X)$.

Replacing the condition (3.1) of Theorem 3.1 by orbital regularity, we have the following:

THEOREM 3.2. *Let S and T be multi-valued mappings from a metric space X into $P_x(X)$ and let $\{f_i\}$ be the family of all continuous mappings from X into itself such that the conditions (3.2) holds,*

$$(3.6) \quad \phi(t) < t \text{ for each } t > 0 \text{ and some } \phi \in \mathcal{F} ,$$

(3.7) *for some $x_0 \in X$, and each $i \in \mathbb{N}$, there exist sequences $\{x_n\}$ and $\{y_n\}$ in X such that the orbit $O_{f_i}(x_0)$ is regular, the pair (S, T) is asymptotically regular at x_0 and $f(X)$ is $(S, T; f_i, x_0)$ -orbitally complete. Then we have:*

- (1) *for each $i \in \mathbb{N}$, f_i, S and T have a coincidence point in X ,*
- (2) *if the limit of $O_{f_i}(x_0)$ is a fixed point of f_i , then the conclusions (2) and (3) of Theorem 3.1 are also true.*

We remark that Theorem 3.2 with $S = T$ and $f = f_i$ for each $i \in \mathbb{N}$ is Theorem 2 in [16].

It is well known that if S is a multi-valued mapping from X into $C(X)$, then for every $x, y \in X$ and $u \in Sx$, there exists a point $v \in Sy$ such that

$$d(u, v) \leq H(Sx, Sy).$$

Hence, if S and T are multi-valued mappings from X into $CL(X)$, then orbital regularity in Theorem 3.2 can be dropped.

THEOREM 3.3. *Let S and T be multi-valued mappings from a metric space X into $C(X)$ and let $\{f_i\}$ be the family of continuous mappings fro X into itself such that the conditions (3.1), (3.2), (3.4), (3.5) and (3.6) hold. Then all the conclusions of Theorem 3.2 are also true.*

Consider the following condition:

$$(3.8) \quad H(Sx, Ty) \leq \phi(\max(D(f_i x, Sx), D(f_j y, Ty), D(f_i x, Ty), D(f_j y, Sx), d(f_i x, f_j(y))))$$

for each $x, y \in X, i, j \in \mathbb{N}, i \neq j$, and $\phi \in \mathcal{F}$.

In Theorem 3.1, if we replace (3.2) by (3.8), the asymptotic regularity of (S, T) , (3.4), is not needed.

In fact, we have the following:

THEOREM 3.4. *Let S and T be multi-valued mappings from a metric space X into $P_x(X)$ and let $\{f_i\}$ be the family of continuous mappings from X into itself such that the conditions (3.1), (3.5) and (3.8) hold. Then all the conclusions of Theorem 3.1 are also true.*

In Theorems 3.1 and 3.3, taking $f = f_i$ on X for each $i \in \mathbb{N}$ and defining $\phi(t) = qt, 0 < q < 1$, we have the following:

COROLLARY 3.5. *Let S and T be multi-valued mappings from a metric space into $P_x(X)$ and let f be a continuous mapping from X into itself such that the condition (3.4) holds, as well as*

$$(3.9) \quad S(X) \cup T(X) \subseteq f(X);$$

$$(3.10) \quad H(Sx, Ty) \leq q \max(D(fx, Sx), D(fy, Ty), D(fx, Ty), D(fy, Sx), d(fx, fy))$$

for each $x, y \in X$ and for some $0 < q < 1$,

$$(3.11) \quad f(X) \text{ is } (S, T, f, x_0)\text{-orbitally complete, and}$$

$$(3.12) \quad f \text{ is weakly commuting with each of } S \text{ and } T.$$

Then f, S and T have a common fixed point in X .

COROLLARY 3.6. *Let S and T be multi-valued mappings from a metric space X into $P_x(X)$ and let f be a continuous mapping from X into itself such that the conditions (3.9) and (3.12) hold, and*

$$(3.13) \quad H(Sx, Ty) \leq q \max(D(fx, Sx), D(fy, Ty), \frac{1}{2}(D(fy, Sx) + D(fx, Ty)), d(fx, fy))$$

for each $x, y \in X$ and for some $0 < q < 1$.

Then f, S and T have a common fixed point in X .

The following theorem is an extension of a recent result due to Kubiak [9]:

THEOREM 3.7. *Let S, T be multi-valued mappings from a metric space X into $P_x(f(X) \cap g(X))$ and f, g be continuous mappings from X into itself such that the conditions (3.12) and (3.13) hold. Then f, g, S and T have a common fixed point in X .*

REMARK. Our results extend some theorems of Hadzic [1] and Sessa *et al.* [20] to the version of hybrid contraction mappings.

4. Some related results

Let X be a reflexive Banach space and $WC(X)$ denote the family of non-empty weakly compact subsets of X . Note that every non-empty weakly compact subset of a reflexive Banach space is proximal [21] and so closed.

We need the following lemma for our main theorems:

LEMMA 4.1. ([10]) *Let $f \in \mathcal{F}$ and $t_0 > 0$. If $t_{n+1} \leq f(t_n)$ for all $n \in \mathbb{N}$, then the sequence $\{t_n\}$ converges to 0.*

The following theorem is an extension of a result due to Kaneko [7]:

THEOREM 4.2. *Let X be a reflexive Banach space and let $\{S_n\}, \{T_n\}$ be sequences of mappings from X into $WC(X)$ such that*

$$(4.1) \quad H(S_m x, T_n y) \leq \phi \left(\max \left(D(x, S_m x), D(y, T_n y), \frac{1}{2}(D(x, T_n y) + D(y, S_m x)), d(x, y) \right) \right) \\ \text{for each } x, y \in X \text{ and for some } \phi \in \mathcal{F}.$$

Then there exists a point $z \in X$ such that $z \in S_m z \cap T_n z$ for each $m, n \in \mathbb{N}$.

PROOF. First, we assume that $h = 0$. Let $x_0 = X$ be an arbitrary point. Then there exists a point $x_1 \in S_1 x_0$ such that $d(x_0, x_1) = D(x_0, S_1 x_0)$. This is possible because $S_1 x_0$ is a non-empty weakly compact subset of a reflexive Banach space and so is proximal.

Now, for all $n \in \mathbb{N}$, we have $D(x_1, T_n x_1) \leq H(S_1 x_0, T_n x_1) = 0$ and hence we have $x_1 \in T_n x_1$. Similarly, for all $n \in \mathbb{N}$,

$$D(x_1, S_1 x_1) \leq H(T_n x_1, S_1 x_1) = 0 \quad \text{yields } x_1 \in S_n x_1.$$

Thus x_1 is a common fixed point of the two equations $\{S_n\}$ and $\{T_n\}$.

Next, we assume that $h \neq 0$. Let $x_0 \in X$ be arbitrary but fixed.

Construct a sequence $\{x_n\}$ in X such that

$$\begin{aligned}x_{2n-1} &\in S_n x_{2n-2}, & x_{2n} &\in T_n x_{2n-1}, \\d(x_{2n-2}, x_{2n-1}) &= D(x_{2n-2}, S_n x_{2n-2}), & \text{and} \\d(x_{2n-1}, x_{2n}) &= D(x_{2n-1}, T_n x_{2n}).\end{aligned}$$

The existence of such a sequence in X is guaranteed by the proximality of $S_m(x)$ and $T_n(x)$ for each $m, n \in \mathbb{N}$.

Now, suppose that $x_n = x_{n+1}$ for some $n \in \mathbb{N}$. If $n \in \mathbb{N}$ is even, then we have $x_{2n} \in S_{n+1} x_{2n}$.

Further, for each $m \in \mathbb{N}$, we have

$$\begin{aligned}D(x_{2n}, T_m x_{2n}) &\leq H(S_{n+1} x_{2n}, T_m x_{2n}) \\&\leq \phi \left(\max \left(D(x_{2n}, S_{n+1} x_{2n}), D(x_{2n}, T_m x_{2n}), \right. \right. \\&\quad \left. \left. \frac{1}{2} (D(x_{2n}, T_m x_{2n}) + D(x_{2n}, S_{n+1} x_{2n})), d(x_{2n}, x_{2n}) \right) \right) \\&= \phi \left(D(x_{2n}, T_m x_{2n}) \right).\end{aligned}$$

If $D(x_{2n}, T_m x_{2n}) > 0$, then it follows from the above inequality that

$$D(x_{2n}, T_m x_{2n}) < D(x_{2n}, T_m x_{2n}),$$

which is a contradiction.

Thus, we have $x_{2n} \in T_m x_{2n}$ for each $m \in \mathbb{N}$.

Similarly, $D(x_{2n}, S_m x_{2n}) \leq H(S_m x_{2n}, T x_{2n}) \leq \phi(D(x_{2n}, S_m x_{2n}))$ gives $x_{2n} \in S_m x_{2n}$ for each $m \in \mathbb{N}$.

For an odd number $n \in \mathbb{N}$, we have also the same results.

Therefore, in each case, we have a common fixed point for the sequences $\{S_m\}$ and $\{T_n\}$.

Suppose now that $x_n \neq x_{n+1}$ for all $n \in \mathbb{N}$. We shall show that $\{x_n\}$ is a Cauchy sequence in X . Let us first observe that

$$\begin{aligned}d(x_{2n}, x_{2n+1}) &= D(x_{2n}, S_{n+1} x_{2n}) \\&\leq H(T_n x_{2n-1}, S_{n+1} x_{2n}) \\&\leq \phi \left(\max \left(D(x_{2n-1}, S_{n+1} x_{2n}), D(x_{2n-1}, T_n x_{2n-1}), \right. \right. \\&\quad \left. \left. \frac{1}{2} (D(x_{2n}, T_n x_{2n-1}) + D(x_{2n-1}, S_{n+1} x_{2n})), d(x_{2n}, x_{2n-1}) \right) \right)\end{aligned}$$

$$\begin{aligned}
 &= \phi \left(\max \left(d(x_{2n-1}, x_{2n}), d(x_{2n}, x_{2n+1}), \frac{1}{2}d(x_{2n-1}, x_{2n+1}) \right) \right) \\
 &\leq \phi \left(\max \left(d(x_{2n-1}, x_{2n}), d(x_{2n}, x_{2n+1}), \right. \right. \\
 &\quad \left. \left. \frac{1}{2}(d(x_{2n-1}, x_{2n}) + d(x_{2n}, x_{2n+1})) \right) \right).
 \end{aligned}$$

If $d(x_{2n-1}, x_{2n}) < d(x_{2n}, x_{2n+1})$, then the above inequality yields

$$d(x_{2n}, x_{2n+1}) \leq \phi(d(x_{2n}, x_{2n+1})) < d(x_{2n}, x_{2n+1}),$$

which is a contradiction. Therefore, we get

$$d(x_{2n}, x_{2n+1}) \leq \phi(d(x_{2n-1}, x_{2n})).$$

Similarly, we can show that

$$d(x_{2n+1}, x_{2n+2}) \leq \phi(d(x_{2n}, x_{2n+1})).$$

It follows from the above relations that

$$d(x_n, x_{n+1}) \leq \phi(d(x_n, x_{n-1})).$$

By Lemma 4.1, we have $\lim_{n \rightarrow \infty} d(x_n, x_{n+1}) = 0$, which yields that $\{x_n\}$ is a Cauchy sequence in X . Since X is a Banach space, this Cauchy sequence converges to a point in X . Let $\lim_{n \rightarrow \infty} x_n = z$. Then we have

$$\begin{aligned}
 D(x_{2n-1}, T_m z) &\leq H(S_n x_{2n-2}, T_m z) \\
 &\leq \phi \left(\max \left(D(x_{2n-2}, S_n x_{2n-2}), D(z, T_m z), \right. \right. \\
 &\quad \left. \left. \frac{1}{2}(D(x_{2n-2}, T_m z) + D(z, S_n x_{2n-2})), d(x_{2n-2}, z) \right) \right) \\
 &\leq \phi \left(\max \left(d(x_{2n-2}, x_{2n-1}), D(z, T_m z), \right. \right. \\
 &\quad \left. \left. \frac{1}{2}(D(x_{2n-2}, T_m z) + d(z, x_{2n-1})), d(x_{2n-2}, z) \right) \right).
 \end{aligned}$$

Letting $n \rightarrow \infty$, the above inequality yields

$$D(z, T_m z) = 0.$$

Since $T_m z$ is closed, $z \in T_m z$ for all $m \in \mathbb{N}$.

Similarly, we have also $z \in S_m z$ for all $m \in \mathbb{N}$.

Therefore, z is a common fixed point of the sequence $\{S_n\}$ and $\{T_n\}$. This completes the proof.

Let f, g be single-valued mappings from a metric space X into itself. Recall that the mappings f and g are said to be weakly commuting [17] if $d(fgx, gfx) \leq d(fx, gx)$ for any $x \in X$.

Clearly two commuting mappings [4] (that is, $fgx = gfx$ for any $x \in X$) are weakly commuting but the converse is not true.

EXAMPLE. Let $X = [0, 1]$ with the Euclidean metric d and let $f, g : X \rightarrow X$ be defined by $f(x) = 2x/(x + 1)$ and $g(x) = x/(2x + 1)$ for all $x \in X$. Then the mappings f and g are weakly commuting but not commuting.

Some fixed point theorems for commuting and weakly commuting mappings may be found in [3–5] and [14–18, 20].

COROLLARY 4.3. *Let f, g, S and T be single-valued mappings from a complete metric space X into itself such that*

$$(4.2) \quad d(fx, gy) \leq \varphi \left(\max \left(d(fx, Sx), d(gy, Ty), \frac{1}{2}(d(fx, Ty) + d(gy, Sx)), d(Sx, Ty) \right) \right)$$

for each $x, y \in X$ and for some $\varphi \in \mathcal{F}$,

$$(4.3) \quad (f, S) \text{ and } (g, T) \text{ are weakly commuting pairs.}$$

Then f, g, S and T have a unique common fixed point in X .

PROOF. Define two mappings A, B by $Ax = \{fx\}$ and $Bx = \{gx\}$ for any $x \in X$. Then (A, S) and (B, T) are weakly commuting pairs. Now in view of Theorem 4.2, there exists a point $z \in X$ such that $Sz \in Az$ and $Tz \in Bz$, which yields $Sz = fz$ and $Tz = gz$. Substituting in (4.2), we obtain

$$d(fz, gz) \leq \varphi \left(\max \left\{ d(fz, Sz), d(gz, Tz), \frac{1}{2}[d(fz, Tz) + d(gz, Sz)], d(Sz, Tz) \right\} \right) \\ = \varphi \left(\max \{ 0, 0, d(fz, gz), d(fz, gz) \} \right) = \phi(d(fz, gz)).$$

If $fz \neq gz$, then we obtain the contradiction $d(fz, gz) < d(fz, gz)$. Therefore z is a common coincidence point of f, g, S , and T .

We shall now show that fz is a common fixed point of f, g, S and T .

Since f and S weakly commute, $d(Sfz, fSfz) \leq d(Sx, fx) = 0$ and $Sfz = fSfz$. But $Sz = fz$. Therefore $Sfz = fSfz = f^2z$ and fz is a common coincidence point of f and S .

Since g and T weakly commute, $d(gtZ, Tgz) \leq d(Tz, gz) = 0$ and $gTz = Tgz$. Since $gz = Tz$ we obtain $Tgz = gTz = g^2z$ and gz is a common coincidence point of f, g, S and T . Since $fz = gz$, fz is a common coincidence point of f, g, S and T .

From (4.2), we obtain

$$\begin{aligned} d(fz, gfx) &\leq \varphi\left(\max\{d(fz, Sz), d(gfx, Tfx), \right. \\ &\quad \left. \frac{1}{2}[d(fz, Tfx) + d(gfx, Sz)], d(Sz, Tfx)\}\right) \\ &= \varphi\left(\max\{0, 0, d(fz, gfx), d(fz, gfx)\}\right) \\ &= \varphi(d(fz, gfx)), \end{aligned}$$

which forces $fz = gfx$ and fz is a fixed point of g . From $Tgz = g^2z$ and $fz = gz$, it follows that fz is also a fixed point of T .

If we can show that fz is also a fixed point of f , then, from $Sfz = f^2z = fz$, it follows that fz is also a fixed point of S . So consider

$$\begin{aligned} d(ffz, fz) &= d(ffz, gz) \\ &\leq \varphi\left(\max\{d(ffz, Sfz), d(gz, Tz), \right. \\ &\quad \left. \frac{1}{2}[d(ffz, Tz) + d(gz, Sfz)], d(Sfz, Tz)\}\right) \\ &= \varphi\left(\max\{0, 0, d(ffz, fz), d(ffz, fz)\}\right) \\ &= \varphi(d(ffz, fz)), \end{aligned}$$

which implies that $ffz = fz$.

We shall now show uniqueness. Suppose that u and v are common fixed points of f, g, S and T . Then, from (4.2),

$$\begin{aligned} d(u, v) &= d(fu, gv) \\ &\leq \phi\left(\max\{d(fu, Su), d(gv, Tv), \right. \\ &\quad \left. \frac{1}{2}[d(fu, Tv) + d(gv, Su)], d(Su, Tv)\}\right) \\ &= \phi\left(\max\{0, 0, d(u, v), d(u, v)\}\right) \\ &= \phi(d(u, v)), \end{aligned}$$

which implies that $u = v$.

COROLLARY 4.4. [20] *Let S and T be two continuous mappings from a complete metric space X into itself. Then S and T have a common fixed point in X if and only if there are two self-mappings A and B on X such that*

$$(4.4) \quad A(X) \cup B(X) \subset S(X) \cap T(X)$$

$$(4.5) \quad d(Ax, By) \leq \phi(\max(d(Sx, Ax), d(Ty, By), \frac{1}{2}(d(Sx, By) + d(Ty, Ax)), d(Sx, Ty)))$$

for each $x, y \in X$ and for some $\phi \in \mathcal{F}$,

$$(4.6) \quad (A, S) \text{ and } (B, T) \text{ are weakly commuting pairs.}$$

Further, z is the unique common fixed point of A, B, S and T .

THEOREM 4.5. *Let X be a compact metric space and let S, T be multi-valued mappings from X into $P_x(X)$ such that either S or T is continuous,*

$$(4.7) \quad H(Sx, Ty) \leq \phi\left(\max(d(x, Sx), d(y, Ty), \frac{1}{2}(d(x, Ty) + d(y, Sx)), d(x, y))\right)$$

for each $x, y \in X, x \neq y,$

and for some $\phi \in \mathcal{F}$. Then either S or T has a fixed point in X .

PROOF. Suppose that S is continuous. Define $\varphi : X \rightarrow \mathbb{R}$ by $\varphi(x) = D(x, Sx)$ for all $x \in X$. Then φ is continuous on X . Since X is compact, there exists a point $x_0 \in X$ such that $\varphi(x_0) = \min\{\varphi(x) : x \in X\}$. Now, choose $x_1 \in Sx_0$ such that $d(x_0, x_1) = D(x_0, Sx_0)$. This is possible because Sx_0 is proximal. Similarly, we can choose $x_2 \in Tx_1$ and $x_3 \in Sx_2$ such that

$$d(x_1, x_2) = D(x_1, Tx_1) \quad \text{and} \quad d(x_2, x_3) = D(x_2, Sx_2).$$

Let us suppose that $d(x_0, Sx_0) > 0$ and $d(x_1, Tx_1) > 0$. Then we have

$$\begin{aligned} d(x_1, x_2) &\leq H(Sx_0, Tx_1) \\ &< \phi\left(\max(D(x_0, Sx_0), D(x_1, Tx_1), \right. \\ &\quad \left. \frac{1}{2}(D(x_0, Tx_1) + D(x_1, Sx_0)), d(x_0, x_1))\right) \\ &\leq \phi\left(\max(d(x_1, x_2), \frac{1}{2}d(x_0, x_2), d(x_0, x_1))\right), \end{aligned}$$

which yield $d(x_1, x_2) < d(x_0, x_1)$.

Similarly, we have also $d(x_2, x_3) < d(x_1, x_2)$. Therefore, we have $d(x_2, x_3) < d(x_0, x_1) = \varphi(x_0)$, which is a contradiction to the minimality of $\varphi(x_0)$. Hence either $D(x_0, Sx_0) = 0$ or $D(x_1, Tx_1) = 0$. Since the proximal sets Sx_0 and Tx_1 are closed, it follows that either $x_0 \in Sx_0$ or $x_1 \in Tx_1$. This completes the proof.

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