

On the Composition of Simultaneous Differential Systems of the First Order

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§ 1. Consider the system of n first order linear differential equations:

$$\frac{du_i}{dx} + \sum_{k=1}^n g_{ik}(x) u_k = 0 \quad (i = 1, 2, \dots, n),$$

together with the n boundary conditions

$$\sum_{k=1}^n a_{ik} u_k(a) + \sum_{k=1}^n b_{ik} u_k(b) = 0 \quad (i = 1, 2, \dots, n),$$

where a_{ij}, b_{ij} are constants and where we assume for simplicity of notation that $g_{ii} \equiv 0$.

We write this system of equations and boundary conditions in matrix notation thus:

$$\begin{bmatrix} d/dx & g_{12} & \dots & g_{1n} \\ g_{21} & d/dx & \dots & g_{2n} \\ \dots & \dots & \dots & \dots \\ g_{n1} & g_{n2} & \dots & d/dx \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \\ \dots \\ u_n \end{bmatrix} = 0,$$

$$\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \dots & \dots & \dots & \dots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{bmatrix} \begin{bmatrix} u_1(a) \\ u_2(a) \\ \dots \\ u_n(a) \end{bmatrix} + \begin{bmatrix} b_{11} & b_{12} & \dots & b_{1n} \\ b_{21} & b_{22} & \dots & b_{2n} \\ \dots & \dots & \dots & \dots \\ b_{n1} & b_{n2} & \dots & b_{nn} \end{bmatrix} \begin{bmatrix} u_1(b) \\ u_2(b) \\ \dots \\ u_n(b) \end{bmatrix} = 0,$$

or with an obvious notation

$$\begin{aligned} PU &= 0 \\ W_a U(a) + W_b U(b) &= 0. \end{aligned} \tag{1}$$

It is the product of operator systems of the form

$$W_a + W_b \tag{2}$$

and

$$Z_a + Z_b \tag{3}$$

that will be considered in this paper. It will be shown in § 2 that if we define the product of two such systems in the same manner as

we see that $G_{ij}(x, \xi)$ is continuous. It is also seen from the nature of the discontinuities of $L_{ik}(x, \xi)$ and $M_{ik}(x, \xi)$ that G_{ij} has a continuous first derivative unless $x = \xi$ where G_{ii} has a jump of magnitude unity. Further,

$$\begin{aligned}
 QG(x, \xi) &= \int_a^b \begin{bmatrix} d/dx & q_{12} & \dots & q_{1n} \\ q_{21} & d/dx & \dots & q_{2n} \\ \dots & \dots & \dots & \dots \\ q_{n1} & q_{n2} & \dots & d/dx \end{bmatrix} \begin{bmatrix} M_{11}(x, \eta) & \dots & M_{1n}(x, \eta) \\ M_{21}(x, \eta) & \dots & M_{2n}(x, \eta) \\ \dots & \dots & \dots \\ M_{n1}(x, \eta) & \dots & M_{nn}(x, \eta) \end{bmatrix} \\
 &\quad \times \begin{bmatrix} L_{11}(\eta, \xi) & \dots & L_{1n}(\eta, \xi) \\ L_{21}(\eta, \xi) & \dots & L_{2n}(\eta, \xi) \\ \dots & \dots & \dots \\ L_{n1}(\eta, \xi) & \dots & L_{nn}(\eta, \xi) \end{bmatrix} d\eta \\
 &= \begin{bmatrix} L_{11}(x, \xi) & \dots & L_{1n}(x, \xi) \\ \dots & \dots & \dots \\ L_{n1}(x, \xi) & \dots & L_{nn}(x, \xi) \end{bmatrix},
 \end{aligned}$$

since each column of $M(x, \xi)$ satisfies the system Q , the only discontinuities being along the principal diagonal; hence

$$PQG(x, \xi) = 0,$$

and $G(x, \xi)$ satisfies the boundary conditions of (4), and so is the Green's matrix for the product system.

§ 3. The adjoint to the system (1) is given by¹

$$\begin{bmatrix} -d/dx & g_{21} & \dots & g_{n1} \\ g_{12} & -d/dx & \dots & g_{n2} \\ \dots & \dots & \dots & \dots \\ g_{1n} & g_{2n} & \dots & -d/dx \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ \dots \\ y_n \end{bmatrix} = 0,$$

or $P'Y = 0$

together with the boundary conditions

$$[y_1(a) \dots y_n(a)] W_a^{-1} + [y_1(b) \dots y_n(b)] W_b^{-1} = 0.$$

Then we state the following result which can easily be verified: let

$$Q(u) = \sum_{k=1}^n u_k'^2 + \sum_{i,r,k=1}^n g_{ik} g_{rk} u_i u_r - \sum_{i,r=1}^n g_{ri} u'_i u_r + \sum_{i,k=1}^n g_{ik}^2 u_i^2,$$

where $g_{ss} = 0$ and in the second summation $i \neq r$; then the differential equations of the system

$$PP'Y = 0$$

¹ Birkhoff and Langer, *loc. cit.*, 64.

are given by

$$\frac{d}{dx} \left\{ \frac{\partial Q}{\partial u_i'} \right\} - \frac{\partial Q}{\partial u_i} = 0 \quad (i = 1, 2, \dots, n).$$

This incidentally proves that *this system is self-adjoint*.¹

§ 4. Let

$$\begin{aligned} Py_1 &= 0 \\ [A_i y_1]_a + [B_i y_1]_b &= 0 \quad (i = 1, 2 \dots p), \end{aligned} \quad (6)$$

where P is a linear operator of order p , be an incompatible system.

The solution of

$$\begin{aligned} Qz &= f(x) \\ [C_i z]_a + [D_i z]_b &= 0 \quad (i = 1, 2, \dots, 2), \end{aligned}$$

when the corresponding homogeneous system is incompatible, is given by

$$z(x) = \int_a^b M(x, \xi) f(\xi) d\xi.$$

Then we state the following result: *the solution of the product system*

$$\begin{aligned} PQ u(x) &= f(x) \\ [A_i Qu]_a + [B_i Qu]_b &= 0 \\ [C_i u]_a + [D_i u]_b &= 0 \end{aligned}$$

is given by

$$u(x) = \int_a^b M(x, \eta) y_1(\eta) d\eta$$

in terms of solutions of the component systems; where

$$y_1(x) = \int_a^b L(x, \zeta) f(\zeta) d\zeta$$

is the solution of the system

$$\begin{aligned} Py_1 &= f(x) \\ [A_i y_1]_a + [B_i y_1]_b &= 0 \quad (i = 1, 2, \dots, p). \end{aligned}$$

¹ See Hilbert, *Gött. Nach.* (1906), 474.